

Paper about common calculations for discovery fluxes and sensitivities

J. Barrios-Martí

MANTS meeting at Mainz

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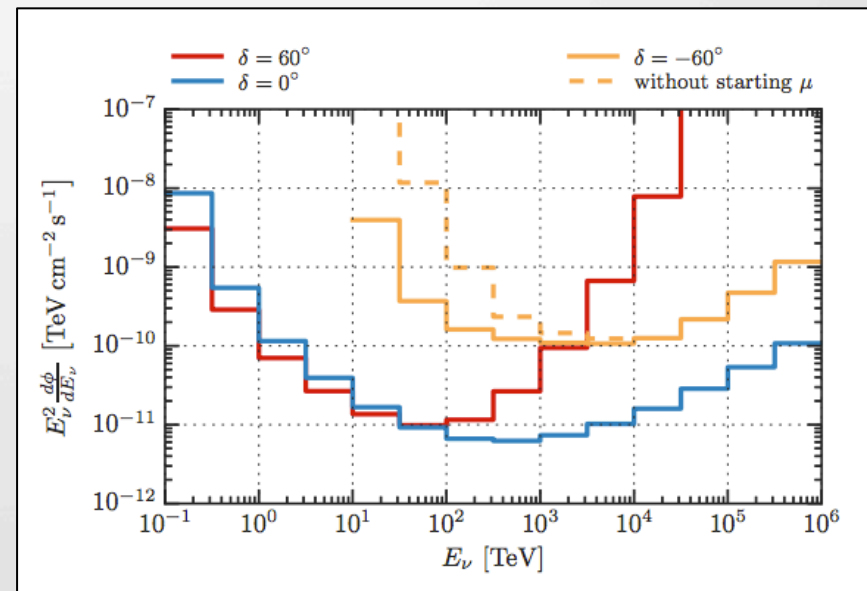
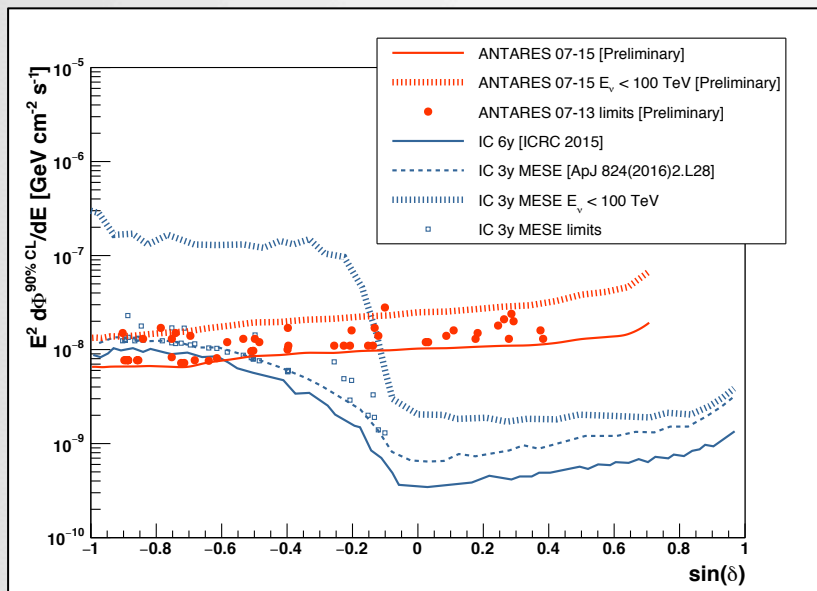
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Paper on comparisons

- Aim: How to perform comparisons between different experiments?
 - Started from PS
 - Different methods
 - Different features we want to show from each experiment



Paper on comparisons: The 2x3 matrix

	Steady point source	Steady extended source	Transient point source
(Diff) Discovery flux			
(Diff) Sensitivity			



Outline for paper

- First part: Methods
 - Likelihood definitions, **differences**
 - The ns feature for E^{-2} likelihood
 - Procedure in simulations
 - Differential sensitivities
 - ...
- Second part: Contributed plots from the collaborations
- Draft (mostly with first part) begun

Likelihood definitions / considerations

- Likelihood definitions:

$$L(n_{sg} | \gamma) = \prod \left(\frac{n_{sg}^s}{N} \cdot P_s(\vec{X}_i | \gamma) + \left(1 - \frac{n_{sg}^s}{N}\right) \cdot P_b(\vec{X}_i) \right)$$

- In ANTARES and KM3NeT, source spectrum is fixed.
- In IceCube, they fit the spectrum between -4.0 and -1.0.
- Also, in ANTARES/KM3NeT the extended likelihood has been used, but no significant differences are seen:

$$\log L(n_s) = \sum_i \left(n_s \cdot P_s(\vec{X}_i | \gamma) + N_b \cdot P_b(\vec{X}_i) \right) - n_{sg} - N_{bg}$$

- Possibly it would be (slightly) better if spectrum was also fitted?

Likelihood definitions / considerations

- Likelihood definitions:

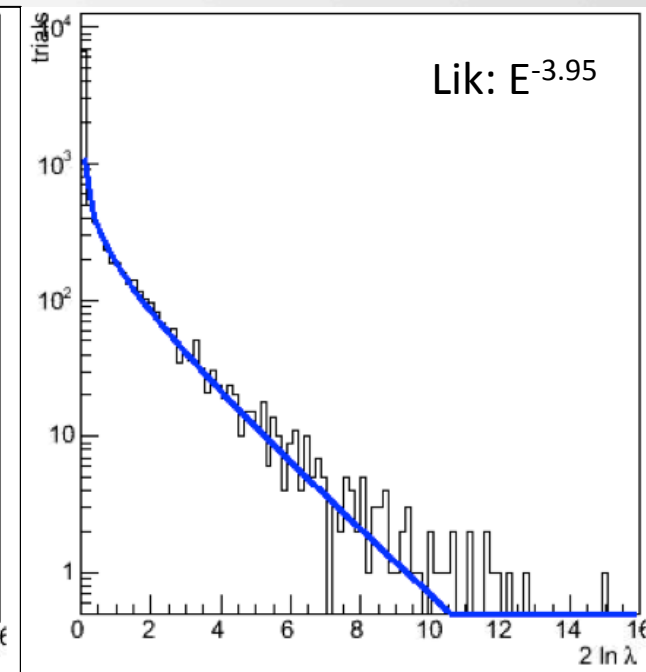
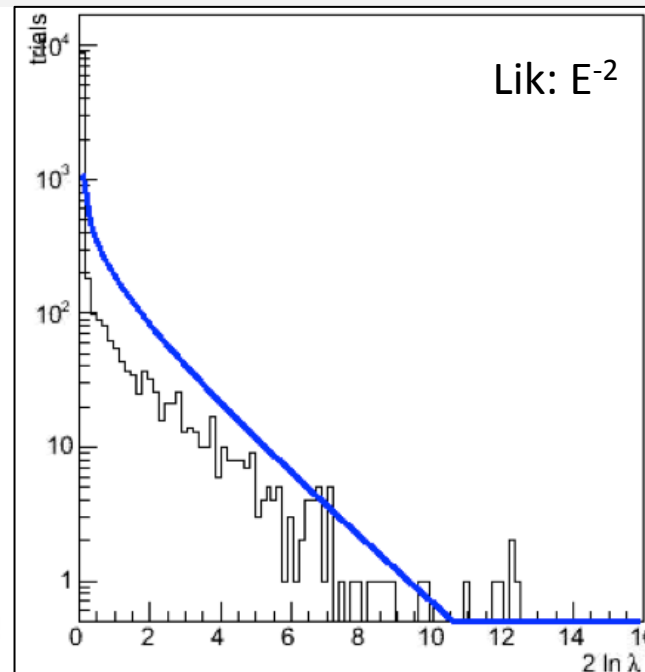
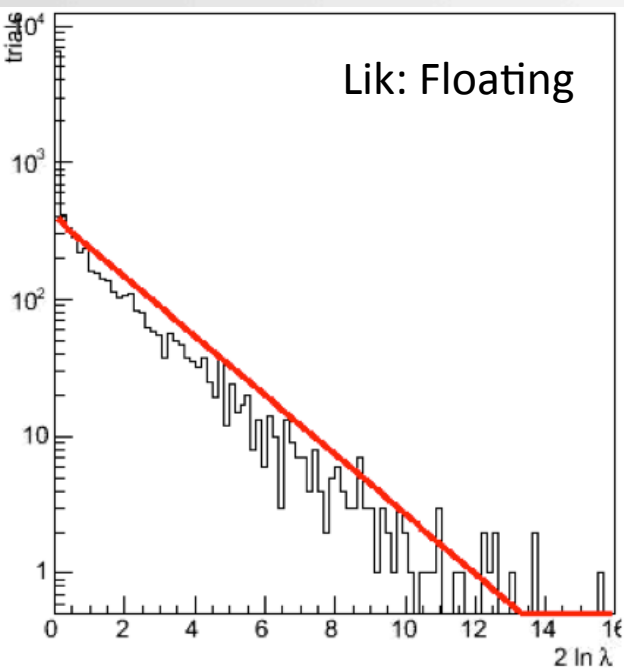
$$L(n_{sg} | \gamma) = \prod \left(\frac{n_{sg}^s}{N} \cdot P_s(\vec{X}_i | \gamma) + \left(1 - \frac{n_{sg}^s}{N}\right) \cdot P_b(\vec{X}_i) \right)$$

- In ANTARES and KM3NeT, source spectrum is fixed.
- In IceCube, they fit the spectrum between -4.0 and -1.0.

$$TS = -2 \left(\log L_{\max}(n_s, \gamma) - \log L_{bg}(n_s = 0, \gamma) \right)$$

- TS distributions for background case change significantly in the two approaches (E^{-2} fixed vs fitted spectrum). Reason: E^{-2} extremely different from background

Likelihood definitions / considerations

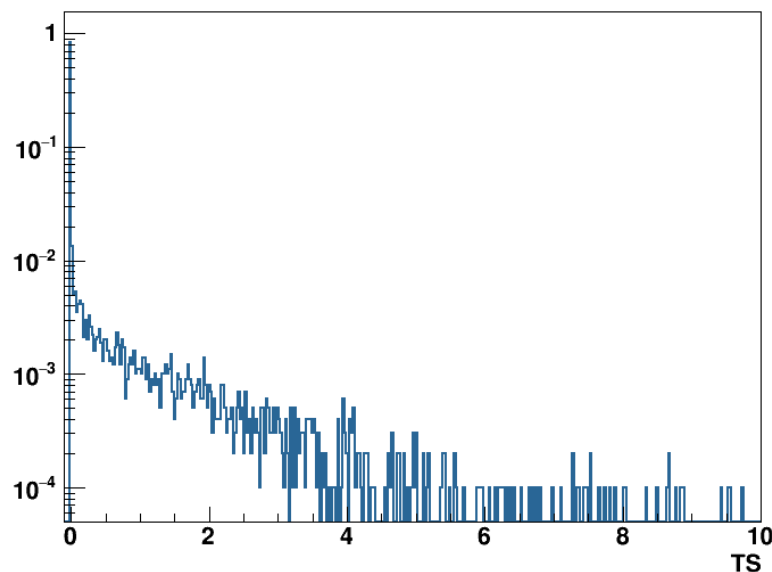


TS distributions for fixed-source search when simulating only background. Left: E floating likelihood. Middle: fixed E^{-2} spectrum. Right: $E^{-3.95}$ spectrum. Red line denotes the χ^2 distribution for 2 dof. Blue line for 1 dof. Plots performed by Chad Finley.

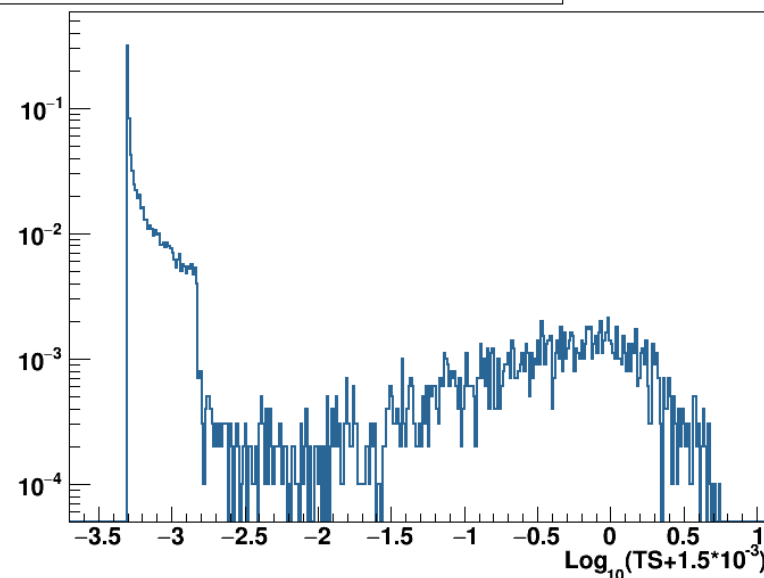
Likelihood definitions / considerations

- In the likelihood, set minimum of n_s to 0.001
 - If real maximum value for likelihood corresponds to $n_s < 0.001$, L_b will be larger than the calculated maximum, leading to a non-zero, negative TS value.
 - Possibility to see the “structure” of the first bin so to avoid overcoverage (i.e., possibility to calculate median TS value for background)

TS distribution for $n_s = 0$

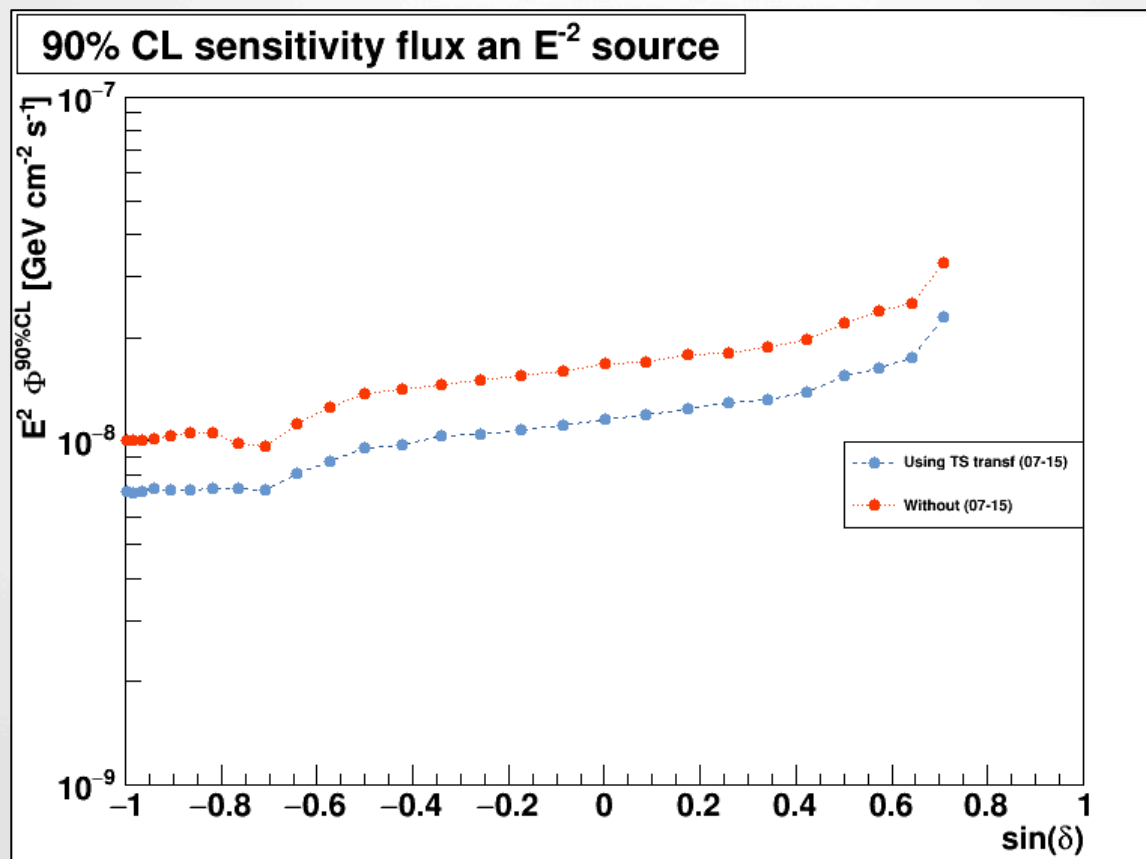


$\text{Log}_{10}(\text{TS}+1.5 \cdot 10^{-3})$ distribution for $n_s = 0$



Likelihood definitions / considerations

- Differences in use of $n_s > 0.001$ feature?



Differential sensitivities

- Simulations:
 - Source generated in pseudoexperiments with information of energy range (typically, step of 0.25 or 0.5 on $\log_{10}(E)$)
 - Source assumption needed

$$N_s(\Delta E, \delta) = \int_{\Delta E} \frac{d\phi}{dE dt dS} A_{\text{eff}}(E_\nu, \delta) dE dt$$

