Simulation chain and signal classification for acoustic neutrino detection in sea water

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Overview

- aim: compare sensitivities of different detector configurations
- use Mediterranean Sea as an example (based on measurements from/around AMADEUS)
- adaptable software approach (modular SeaTray software, based on IceTray)

Content:

- Effects of refraction on the simulation
- Simulation using parameterizations
- Full simulation chain
- Signal classification



Influence of curved sound paths on simulations

- Sound path is bent towards lower speed (upwards for the deep sea)
- Path r determined by:

$$\frac{\partial^2 r}{\partial x^2} = -\left(1 + \left(\frac{\partial r}{\partial x}\right)^2\right) \cdot \frac{\partial c}{c \cdot \partial z}$$

- Requires ray tracing: 100.000 times slower than with straight paths
- Refraction leads to a blind space for hydrophones





Loss of effective volume



Hydrophone mounted > 100 m above seafloor

No significant impact on the effective volume derived from simulations Use straight propagation to save time



Approaches towards simulation

Simulation consists of several modules in a framework (SeaTray) Modules are easy to replace/reuse

Full simulation:

- Generate waveform & noise sample
- Full DAQ/Trigger simulation
- Deriving flux limits, developing analysis methods etc.
- Requires a lot of CPU time (> 10s/event)

Using parameterizations:

 Very fast (1 ms/event), providing an estimate of the detector performance



Simulation with parameterizations





Comparing different detector setups

AMADEUS

- 2 lines, 230m apart
- 3 floors/line, 14.5 100m
 - 6 hydrophones/floor



Comparing apples and oranges:

- 2D setup vs. 3D setup
- Different number of sensors per cluster

KM3NeT Phase 1

- 24 lines, 100m apart
- 18 optical modules/line, 36m
 - 1 acoustic sensor/module





Effective volume for acoustic detection





Simulation chain modules











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Ambient noise



- Ambient noise from 5 years of AMADEUS data
- Determines energy threshold



DAQ & Sensor simulation

Directional system response of the sensors & Inherent noise of the sensors

System response of the ADC board & Inherent noise of the ADC board



Filter simulation

According to online filter used in AMADEUS Matched filter + coincidence test



Has to be adapted for different setups



Signal classification needed



- High rate of transient background with bipolar pulses, from e.g. whales and dolphins
- Additional background suppression is necessary

- Acoustic signal from neutrinos is emitted in a O(20 m) thick plane
- Most background is emitted as spherical waves
- Use the sound propagation geometry as classification for the signals in a large volume acoustic detector

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Simulated events



- Neutrinos (Energy $10^{19} 10^{21} \text{ eV}$)
- Signals from the positioning system
- Spherical sources
- Random coincidences



Distinctive features of signals

- Generate characteristic features from the signature for classification
- Features should be independent of the detector geometry
- Good candidates are:
 - Number of hits
 - Center of gravity of the event
 - Principal components
 - PCA also yields a pancake-reconstruction:
 - RMS of the distance from the triggered hydrophones to the plane
 - Agreement of the reconstructed vertex with the pancake plane

• ...



Classification with boosted trees

- Use these features for a multivariate analysis
- Boosted Trees show the best performance: Recognition rate of 99%
- Tested with different detector geometries:
 - 8 lines, 14 floors
 - 24 lines, 18 floors (KM3NeT Ph1)
- Classification works with the same features and learned models for similar setups!
- Outlook: Checking the stability of the classification with reduced signal quality





Summary and Outlook

- Fully operational simulation chain available
- Refraction of sound paths has negligible effect on sensitivity in simulations
- DAQ Simulation will be adapted to KM3NeT
- Signal classification is working, but has to be tested with overlapping events



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Thank you for your attention!



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Backup



Signature of particle showers in an acoustic array



- Acoustic signal is basically emitted in a O(20 m) thick plane
 - Curved like a normal acoustic signal: ~10 m deflection after 1 km
- Typical detector setup:
 - ~100 m between lines
 - ~20 m between floors
- Signature of events is not affected by the curvature



Simulations can be done with straight propagation, but position reconstruction should include these effects for long distances



Sound speed profile

- Sound speed profile is nearly linear below 200 m
- Sound path mainly determined by:





Sound path (short distance)





Sound path (long distance) **Sound Path** Depth [m] 0 -1000 -2000 40000 10000 20000 30000 0 Distance [m]



