## PSF and pointing accuracy

#### Colas Rivière CPPM



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### Overview

- Timing
- Absolute positioning
- Sea current
- Detector alignment

- Moon shadow
- Surface array
- Split event
- 2ns smearing

PSF

# Timing

| LCM to shore   | intra storey   | intra line   | intra line    | inter line               | inter line                          | Overall |
|--|--|--|---------------|--------------------------|-------------------------------------|---------|
| clock<br>phase   | 40K  | dark room<br>testbench   | LED<br>becons | multi line<br>events     | LASER<br>beacon                     |         |
| 0.1ns  | 0.6ns  | 0.6ns  | 0.3ns         | 0.5ns                    | 0.5ns                               | 1ns     |
|  |  |  |               | analysis<br>(~1ns        | ongoing<br>now)                     | 1.5ns   |
| Time residuals for each line   |  |  | TTS           | chromatic dispersion     |                                     | Overall |
|  |  |  | <b>1.3ns</b>  | 1.5ns @ 40m              |                                     | 2ns     |
| 1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>100<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1000<br>1   | 2000<br>2000<br>2000<br>1000<br>1000<br>1000<br>1000<br>1000 | Allow  |               | s 2000<br>1800<br>5 1600 |                                     |         |
| <sup>5</sup> <sup>min,5</sup> <sup>min,7</sup> <sup>m</sup> |  |  |               |                          | <sup>ĥn</sup> IJIJĿ <sup>ĸ</sup> ŀſ |         |
| Mine_9 Mine_10   | Nine_11  | ht residual (n) https://www.newson.org/action/actio |               | 600<br>400<br>200        |                                     |         |

-20 -15 -10 -5 0 5 10 15 20 intra-storey time difference [ns]

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8000 7000

7000 6000 5000

## Absolute detector orientation

- 5 reference transponders (RT): AGPS + low frequency acoustic positioning (LFLBL)
  - 8-16 kHz, 8 km range, <meter absolute precision
- Line Anchors: Boat+RB, LFBF
- Detector geometry (when low current): high frequency acoustic positioning (HFLBL)
  - 40-65 kHz, 700 m range, 3cm precision
- + relative z measurement (with pressure 10cm precision, with detector geometry when low current)



#### **Result:**



#### Sea current



#### Detector alignment: Relative geometry

Measurements every 2 minutes:

| HFLBL  | pitch/roll | compass  | total |
|--------|------------|----------|-------|
| 3cm    | 0.2°       | 1°       | <10cm |
| 5/line | 1/storey   | 1/storey | OM    |

- Current inferred, position of all OMs computed
- Result: <10 cm precision (<0.5 ns) **Difference triangulation/line** fit for L3F20, March 2010 (m) la 15 entries 800 **Positions of acoustic** 700 storeys of line 3, spring 2011 10 600 500 400 -5 300 -10 200 100 -15 -0.2 -0.15 -0.1 -0.05 0.05 0 0.1 0.15 0.2 -15 -10 10 15 -5 5 radial difference [m] Xrel (m)

## Moon shadow



Likelihood analysis based on PSF ( $\Lambda$ >-5.5, median resolution 0.75°):  $PDF(x|H_0) \propto 1$  $PDF(x|H_1) \propto (1 - PSF \otimes \delta_{Moon})(x)$ Significance 2D 3.5 <sup>b</sup> Delta zenith (deg) 3 2.5 2 1.5 0.5 -4 -2 0 2 Delta azimuth (deg) Current analysis, 2007-2010: **2.7σ** (expected  $2.1 \pm 0.9\sigma$ ) Stat \*2, \*5, \*10: 2.80, 4.20, 5.90

# Surface array







## Surface array



## Surface array



#### Crosscheck PSF with data: Split events

- Split each event into 2 sub-events containing half the hits
- Compare the directions of the 2 reconstructed sub-events ("experimental resolution")
- Prelim (only a few runs), but data & MC exp. resolution agree



## 2ns smearing

- Better quality in MC tracks than in data:
  - reduce OM acceptance?
  - degrade time resolution?
- Best fit (quality parameter shape, up-going neutrinos) with **2ns smearing** 
  - 3ns rejected at  $2\sigma$
  - 0 & 1ns disfavored



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### 2ns smearing

#### => Conservative approach, use 2ns smearing

Median angular resolution increased by ~0.1° with ∧>-5.4 cut (0.36° => 0.48°)



# How to get rid of them

- **Reduce uncertainties** on calibration (eg. interline offset)
- **Refine MC**, cutting down systematics:
  - run by run
  - OM response (TTS, pre/afterpulses)
  - water properties (chromatic dispersion, diffusion, absorption)
- Then **update PDF** in track reconstruction algorithms

# Many efforts ongoing, so hopefully we will get rid of some of this extra 0.1° soon

# Error estimate $\beta$

#### Uncertainty from the second derivative of the log likelihood function



## Results



Here, cuts  $\Lambda$ >-5.2 &  $\beta$ <1° Median resolution (including 2ns smearing):

- high energy 12 lines: 0.37°
- 2007-2010, E<sup>-2</sup> ν: 0.46°



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# Summary

- Absolute detector orientation:  $\sigma_{\text{horizontal}} = 0.13^{\circ} \sigma_{\text{vertical}} = 0.04^{\circ}$
- Moon Shadow, Surface array:
  - check correct ANTARES operation
  - no strong constrains on absolute pointing / PSF expected
- Most parameters measured well enough for optimal performance:
  - detector geometry
  - intraline timing
- Interline timing to ~1ns now, should be ~0.5ns soon
- 2ns extra smearing to reproduce data  $\rightarrow$  +0.1° to median res.
- Ongoing improvements to cut it down (chrom. disp., TTS, interline)

#### Median resolution 0.46° for 2007-2010 data, PS cuts