

UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN

Andes Lidar Observatory (ALO)

Gary Swenson, Alan Liu (ERAU), Pete Dragic, Tony
Mangognia, **Chad Carlson, Ben Graf, Austin Kirchhoff,**
Scott Anderson (U of I)

And Collaborators

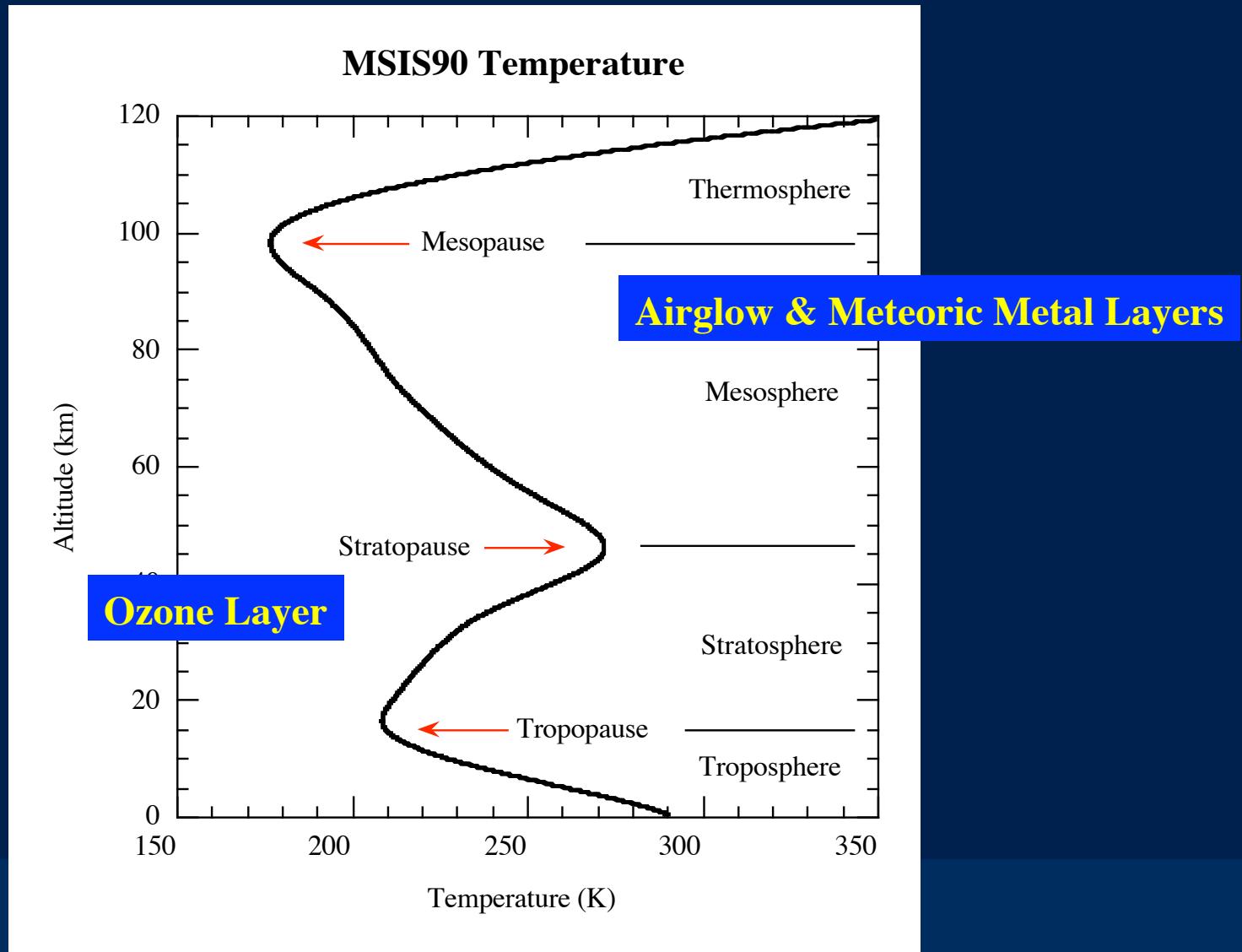
Steve Franke (U of I, Meteor radar)

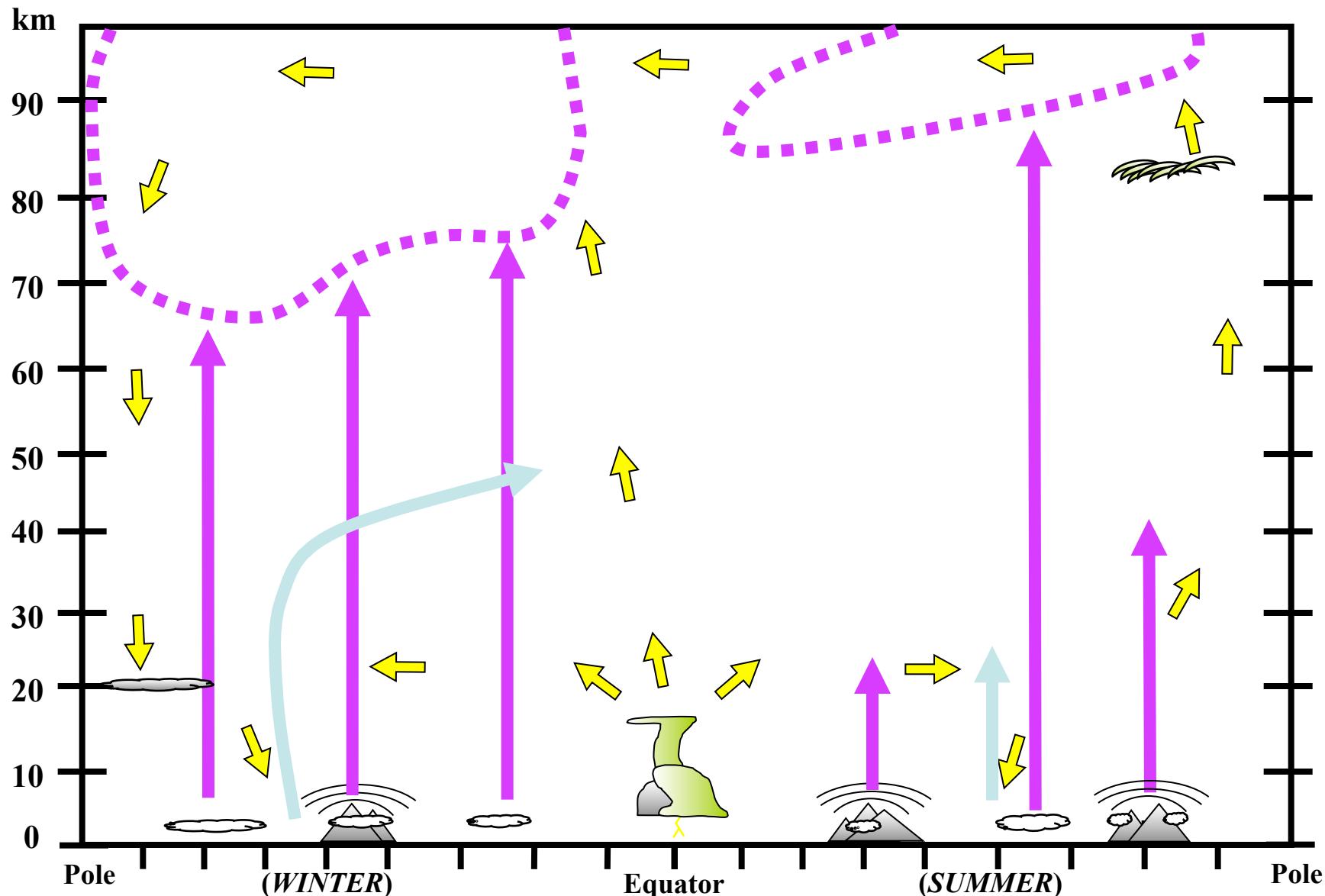
Jim Hecht (Aerospace Corp, 1.6 mm OH imager) and
Mike Taylor (USU, OH and O₂ A Band Temperature)

Outline

- Upper Atmosphere Research
- Remote Sensing Instruments
- Andes Lidar Observatory
- Lidar Development Activities
 - He (1083 nm) Resonance
 - Rayleigh (power in, and beam array)

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→ Gravity Waves
 (boxes are areas of induced drag)

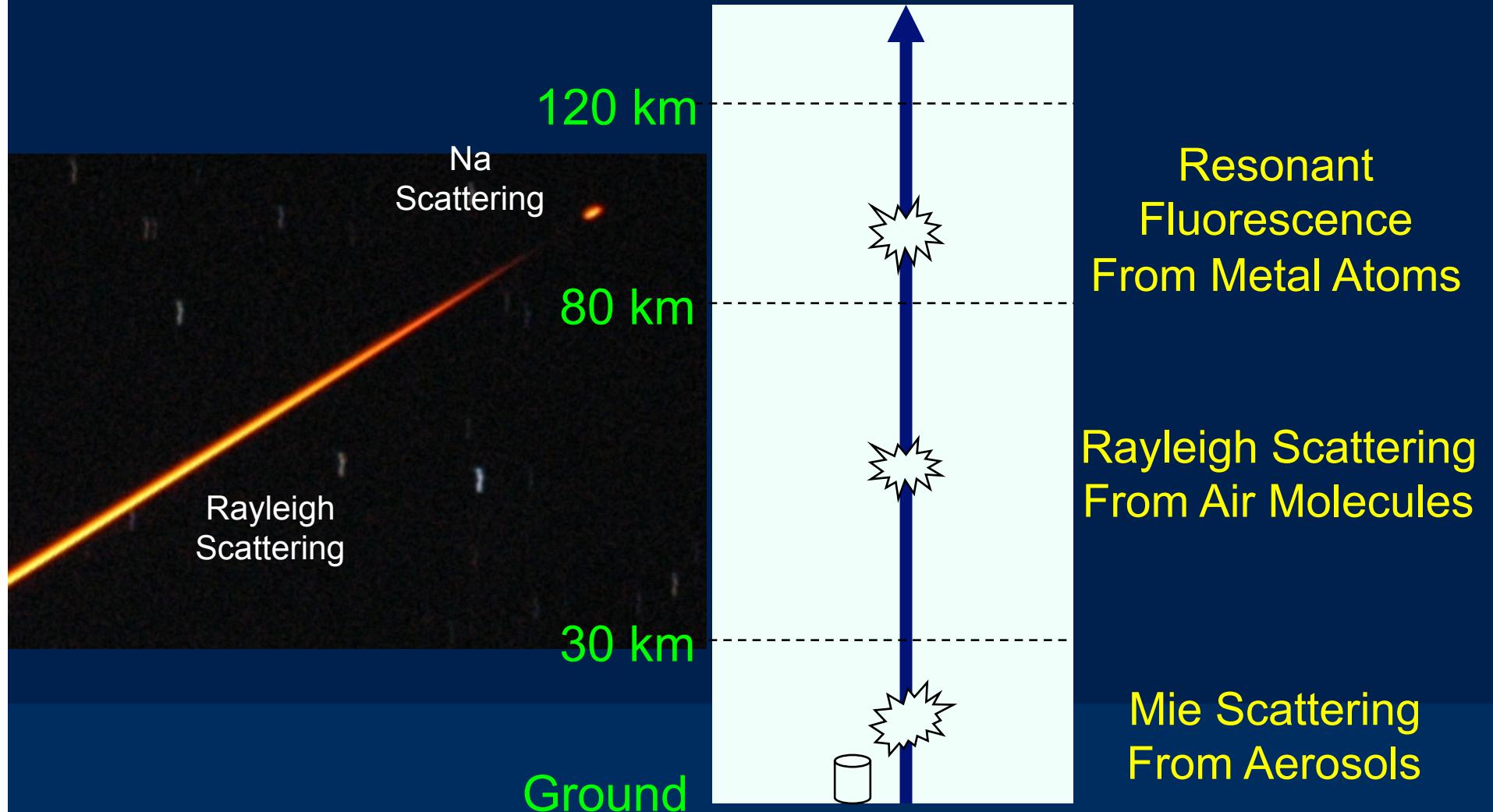
→ Planetary Waves



Circulation

Created by A. J. Gerrard, 10/99, based
 heavily on M. R. Schoeberl's depiction

Light Detection and Ranging (LIDAR)



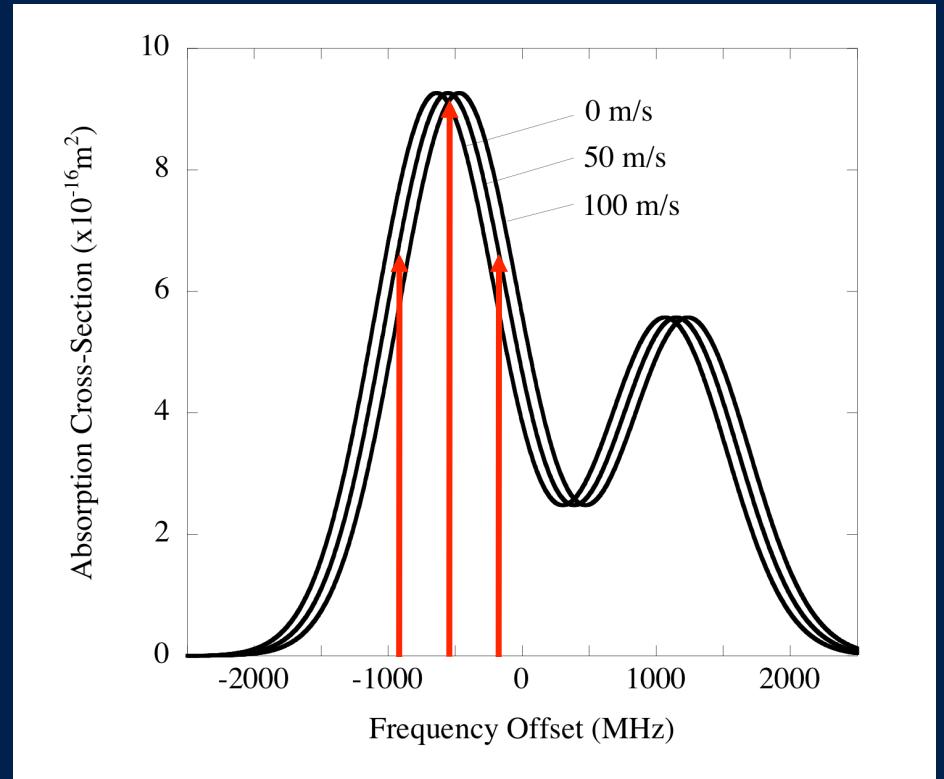
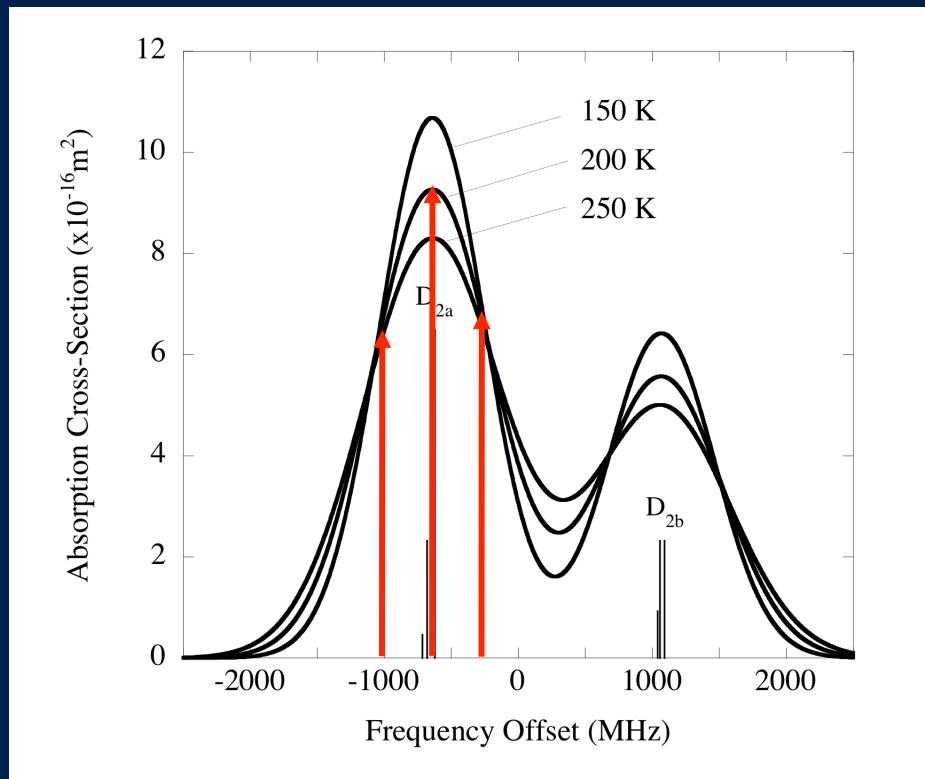
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Signal Processing

Doppler Method for Resonance Lidar:

Probing fluorescence spectrum with laser at 3-frequencies and measuring backscattered signal at each frequency

Principle of Na Doppler Lidar



Doppler Broadening – Temperature

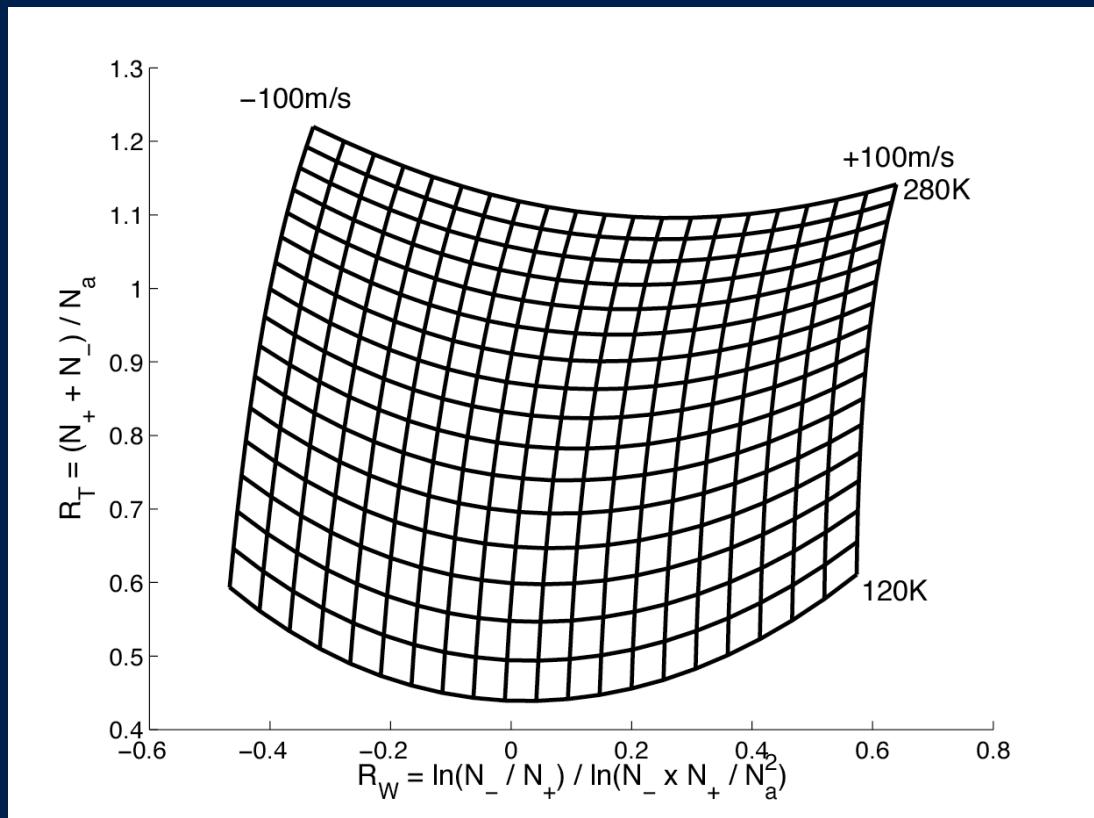
$$\sigma_D = \sqrt{\frac{k_B T}{M \lambda_0^2}}$$

Doppler Shift – Wind

$$v' = v \left(1 - \frac{v_R}{c} \right)$$

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Temperature and Wind Measurement



$$R_T = \frac{\sigma_+(T, V) + \sigma_-(T, V)}{2\sigma_0(T, V)}$$

$$R_W = \frac{\ln[\sigma_+(T, V)/\sigma_-(T, V)]}{\ln[\sigma_+(T, V)\sigma_-(T, V)/\sigma_0^2(T, V)]}$$

$$R_T = \frac{N_+ + N_-}{2N_0}$$

$$R_W = \frac{\ln(N_- / N_+)}{\ln(N_- N_+ / N_0^2)}$$

Lidar Equation

$$N(z,t) = \left\{ \frac{P_l \Delta t \tau_a E(z)}{hc/\lambda} \right\} \left\{ \sigma_{eff}(f, T, v_r) \rho(z, t) \Delta z \right\} \left\{ \frac{A}{4\pi z^2} E(z) \tau_a \eta \right\} + B$$

$N(z,t)$ = number of photons received from z at t

P_l = average laser power (W)

Δt = integration time (s)

τ_a = one-way atmospheric transmittance

$E(z)$ = extinction coefficient

h = Plank's constant (J s)

c = velocity of light (m/s)

λ = laser wavelength (m)

$\sigma_{eff}(f, T, v_r)$ = effective scattering cross section

Δz = altitude range (m)

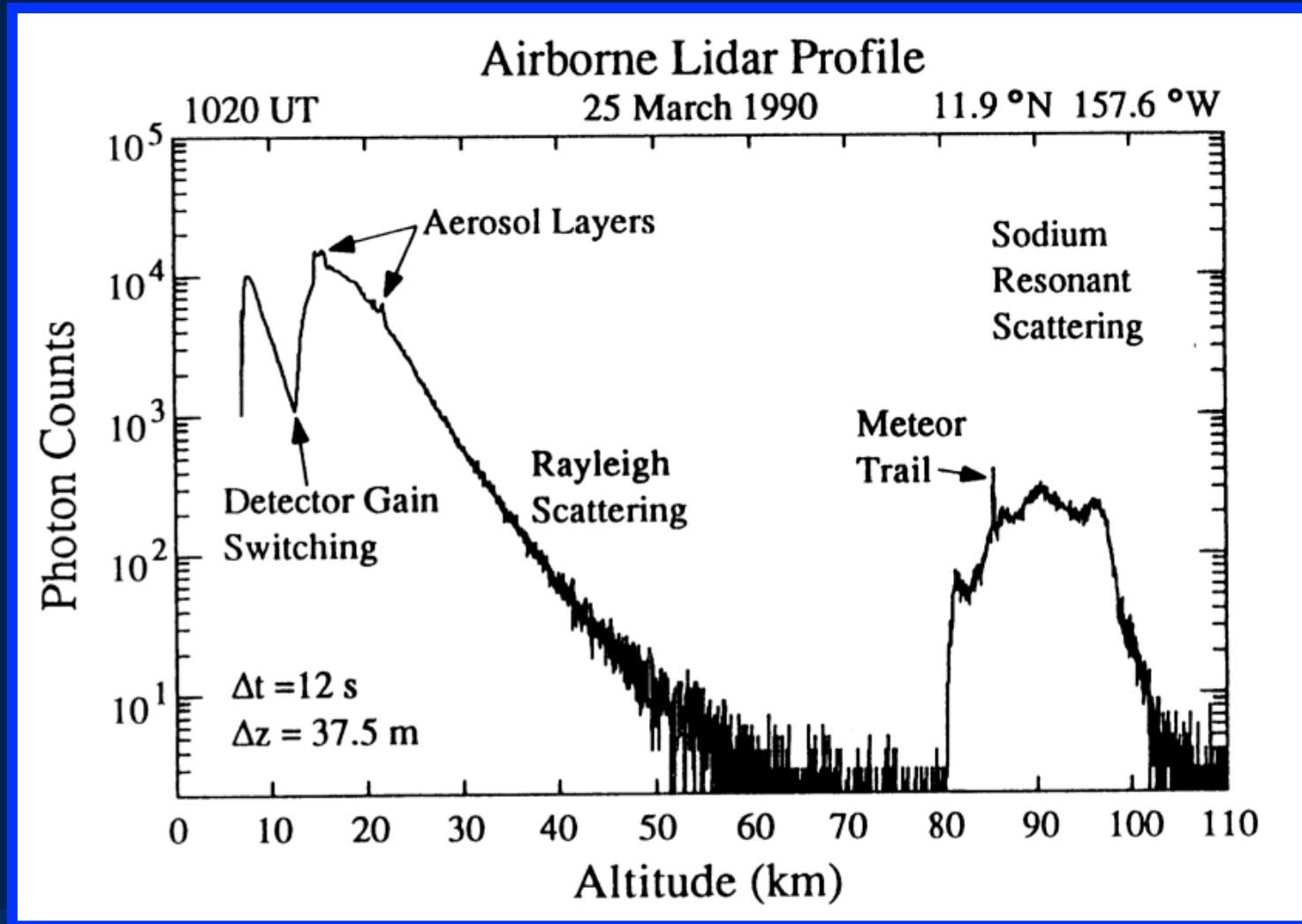
A = aperture of receiving telescope (m^2)

z = altitude above telescope (m)

η = lidar system efficiency

B = background counts

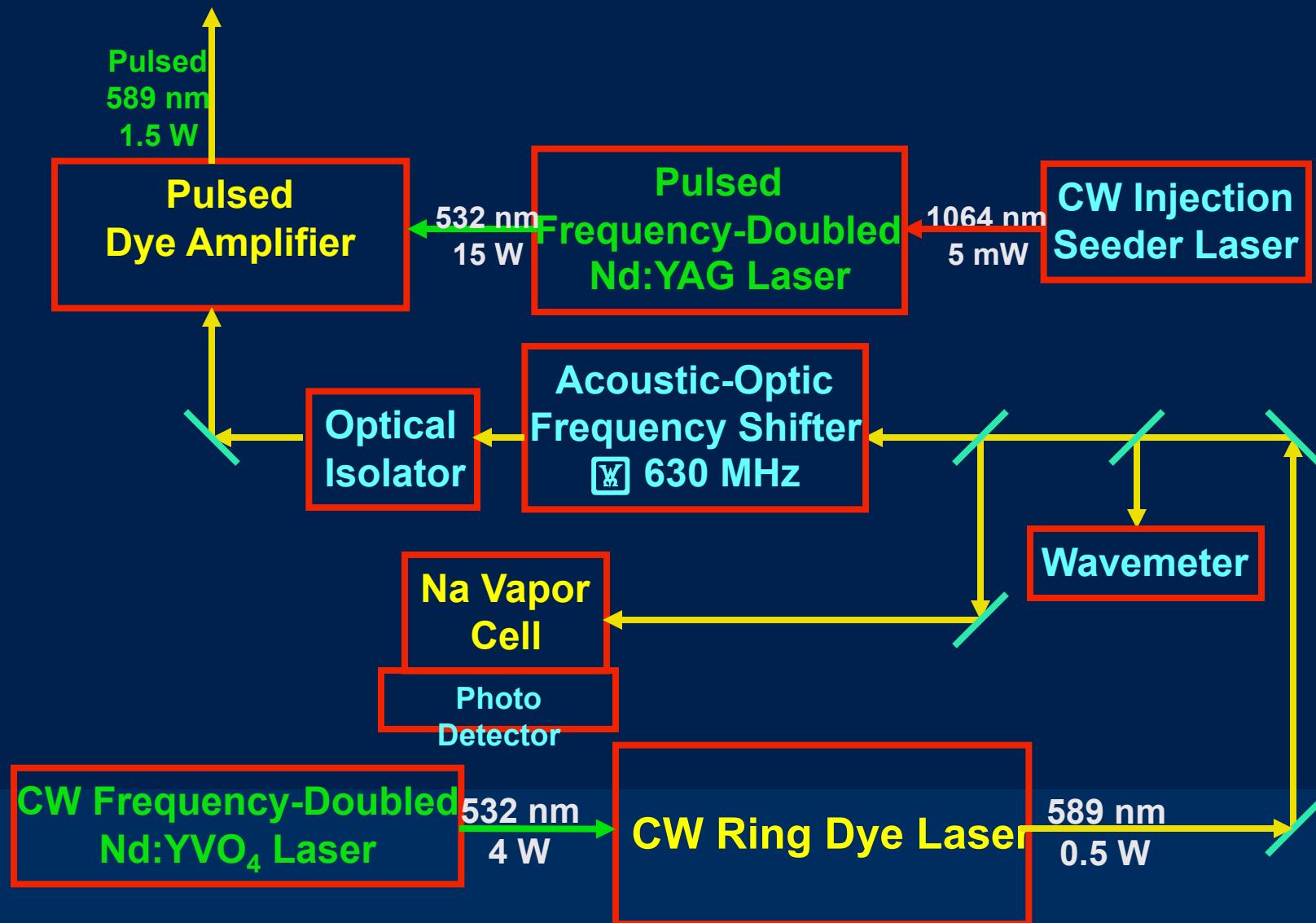
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This photon count profile illustrates the rich variety of atmospheric constituents and processes that can be studied with lidar systems₁₀

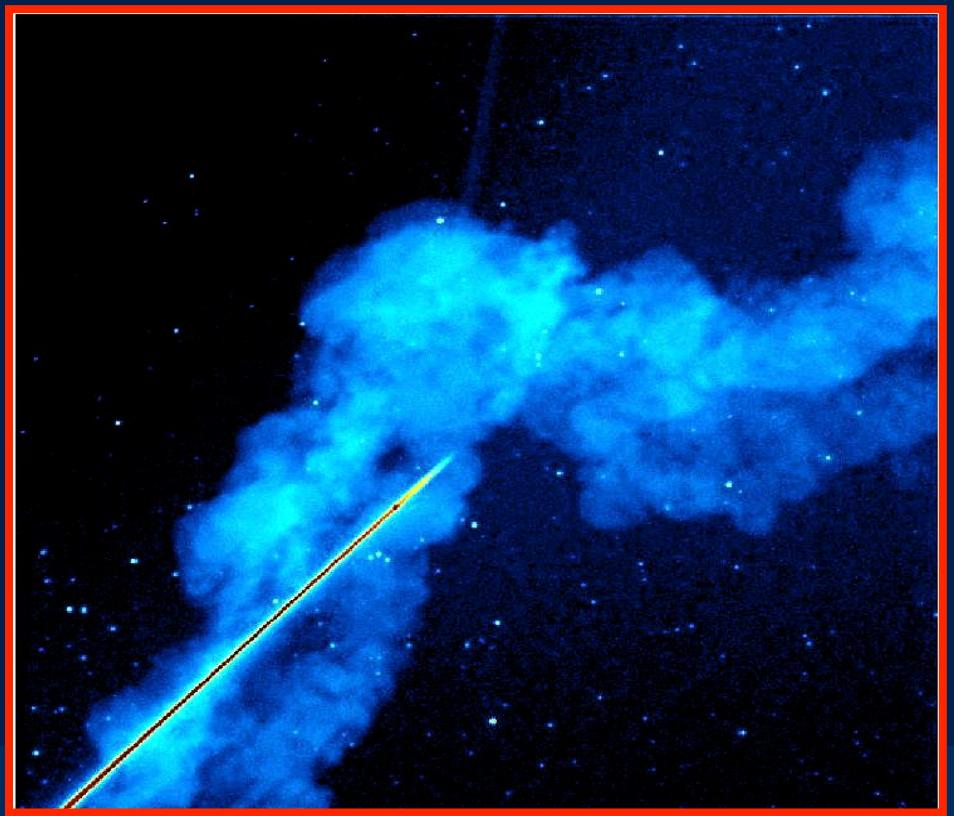
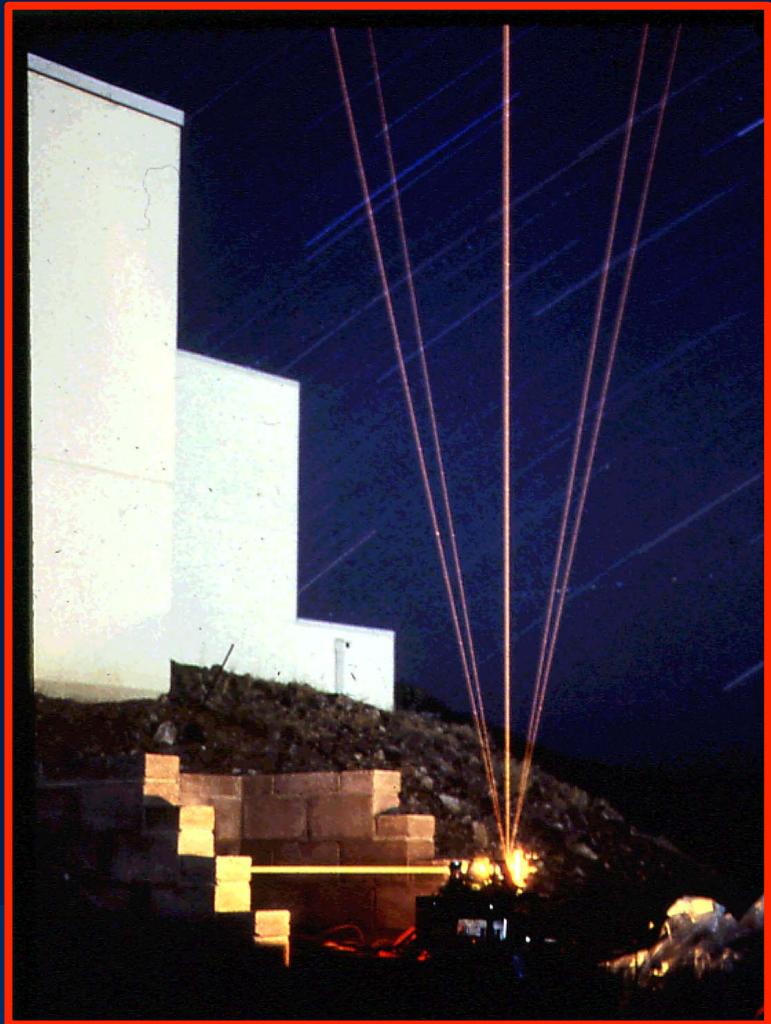
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Na Wind/Temperature LIDAR



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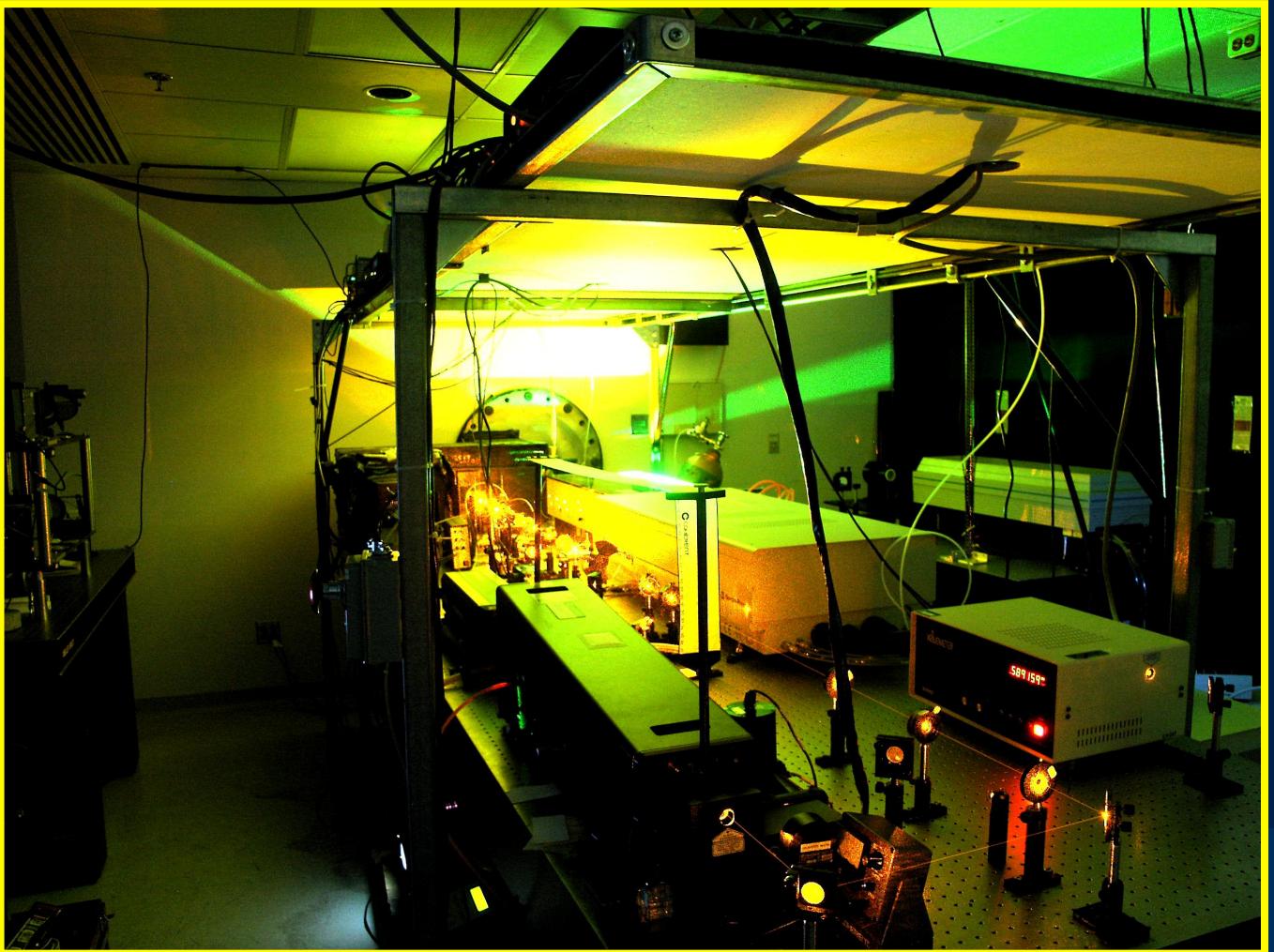
Starfire Optical Range, NM (35N, 106w)



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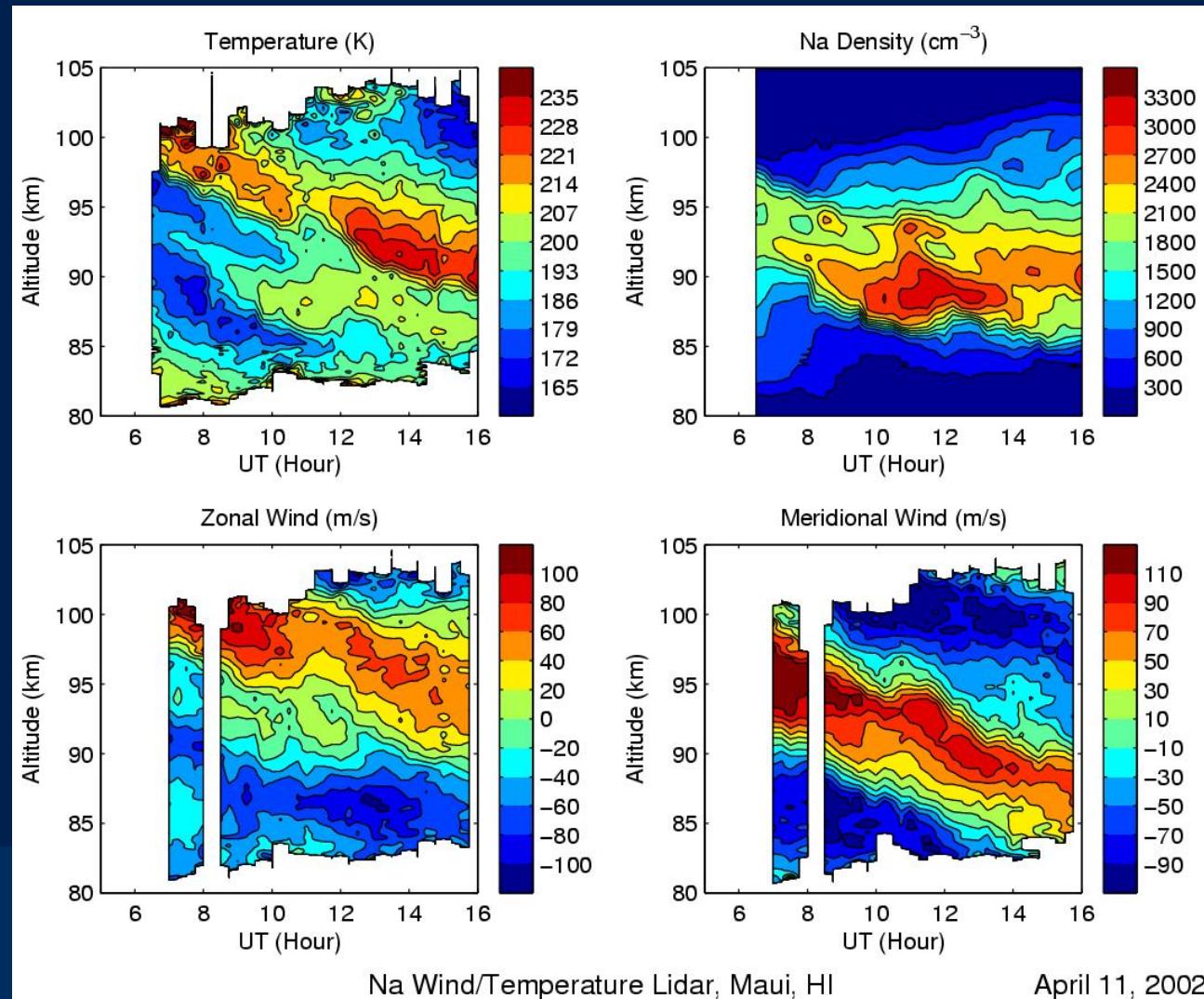
Multi-instruments at Maui (21N, 156W)

Na Wind/Temperature
All Sky Airglow Imaging
Meteor Radar
etc.



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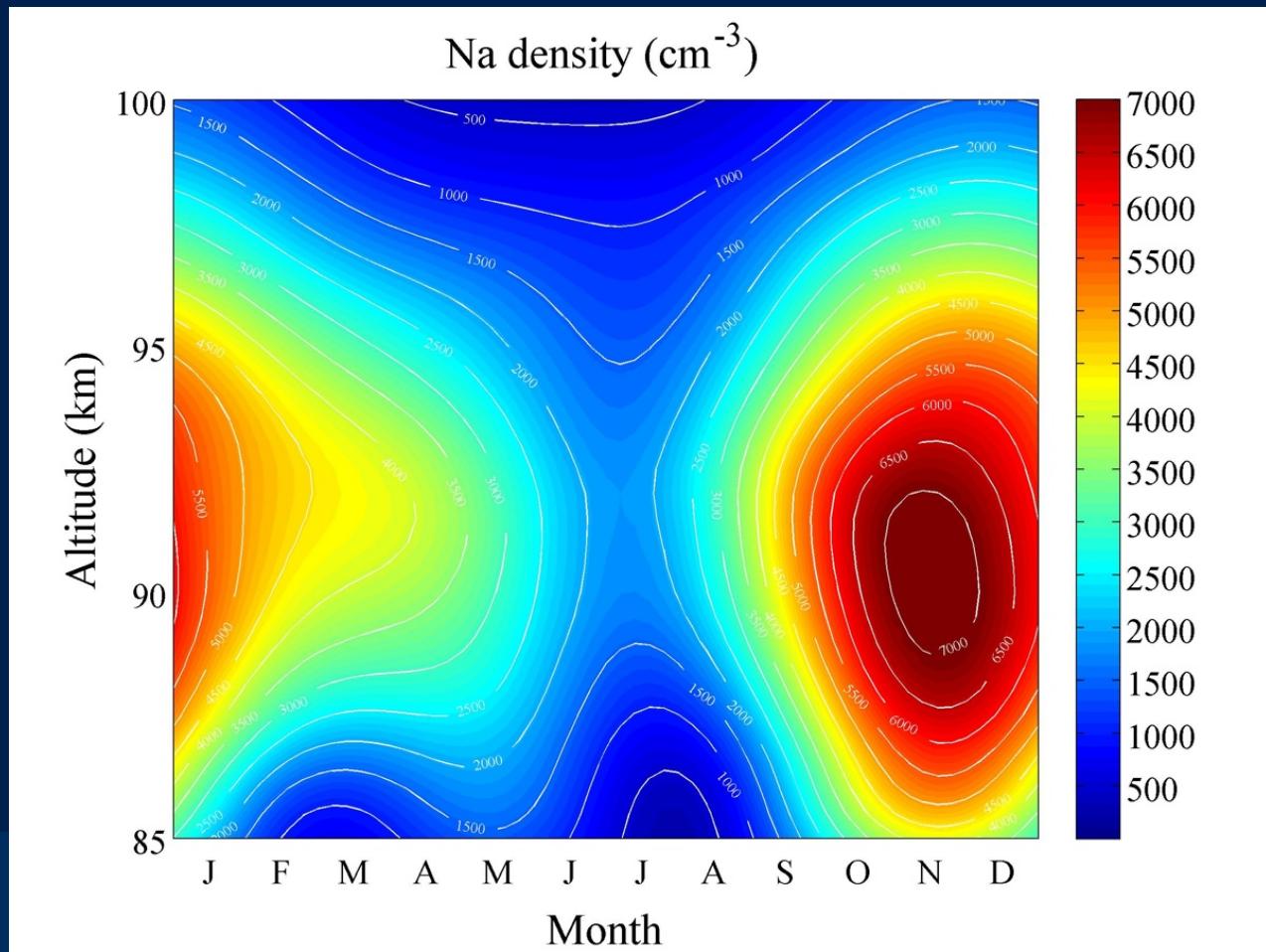
Na Lidar Measurement at Maui



ATMON'10, U of W, 13/14 Sep, 2010

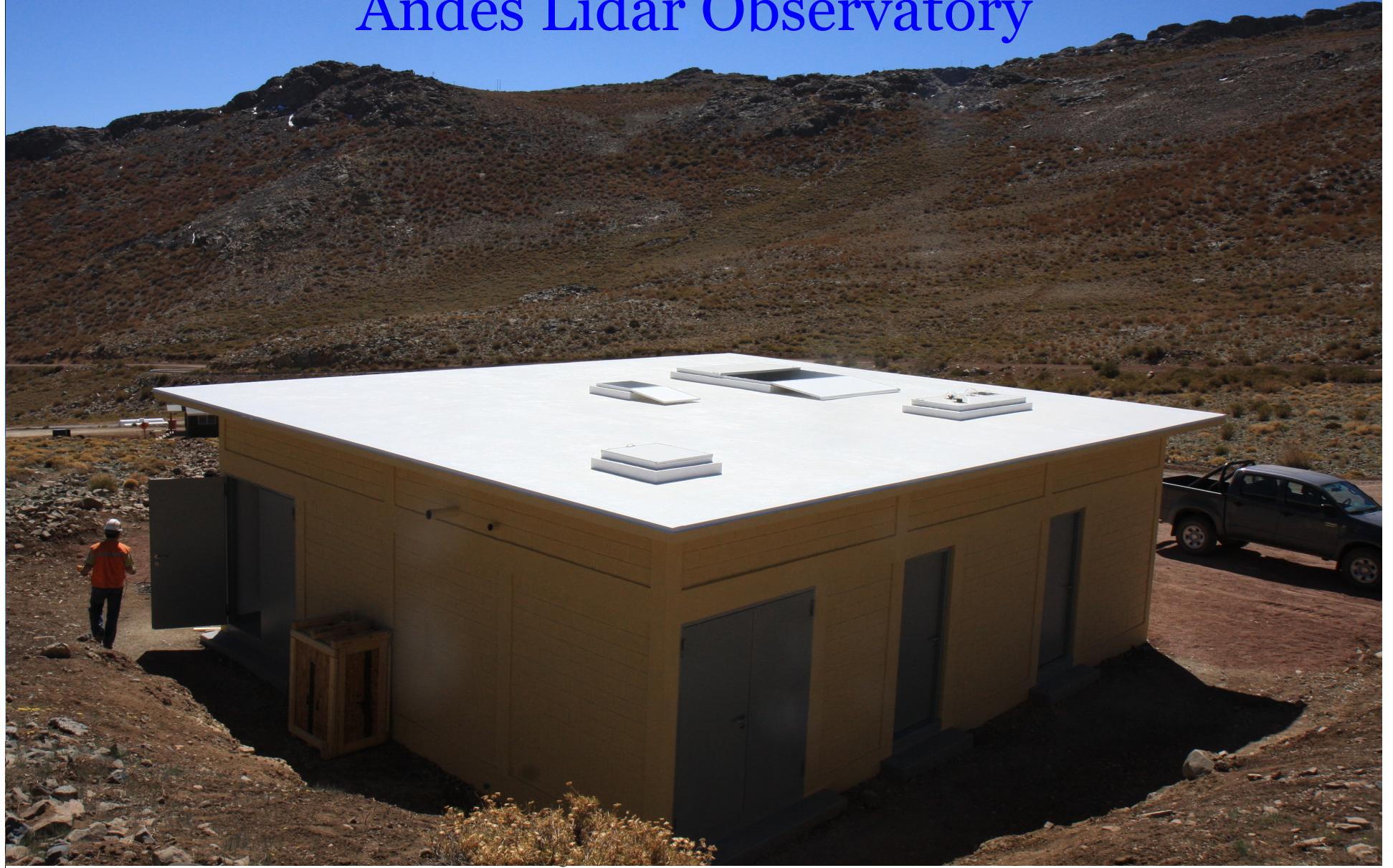
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Na Density at SOR



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Andes Lidar Observatory

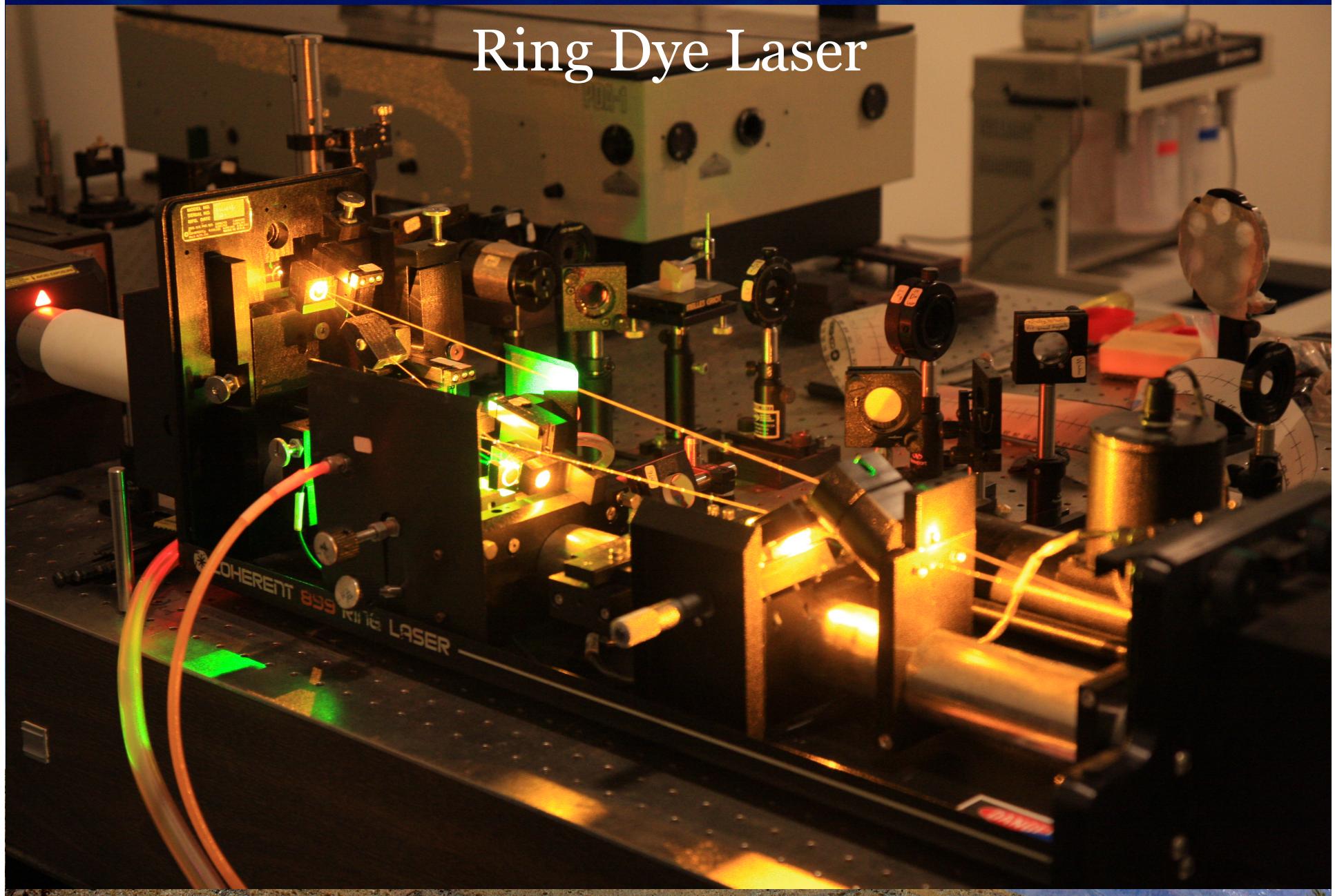


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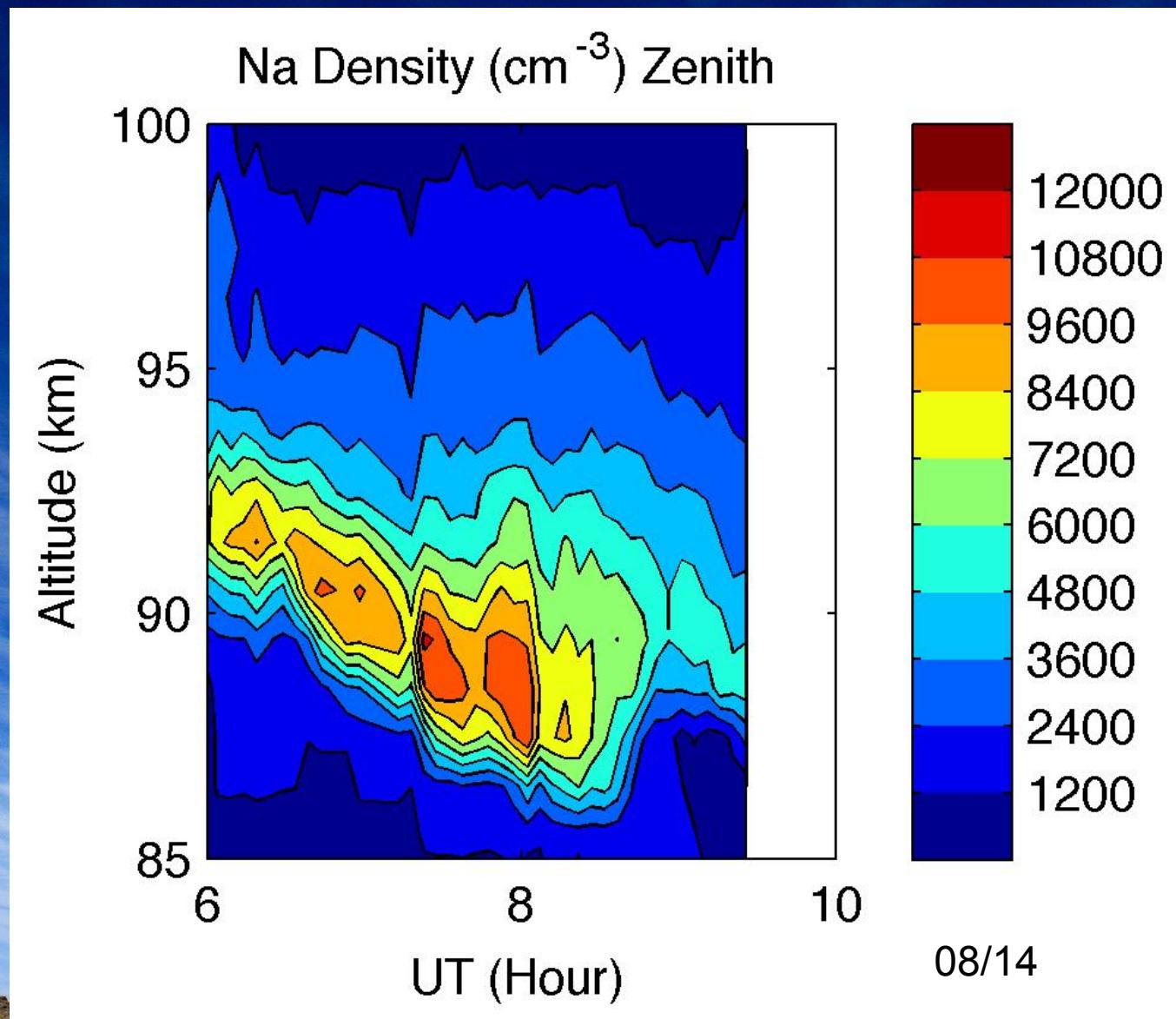
Ring Dye Laser



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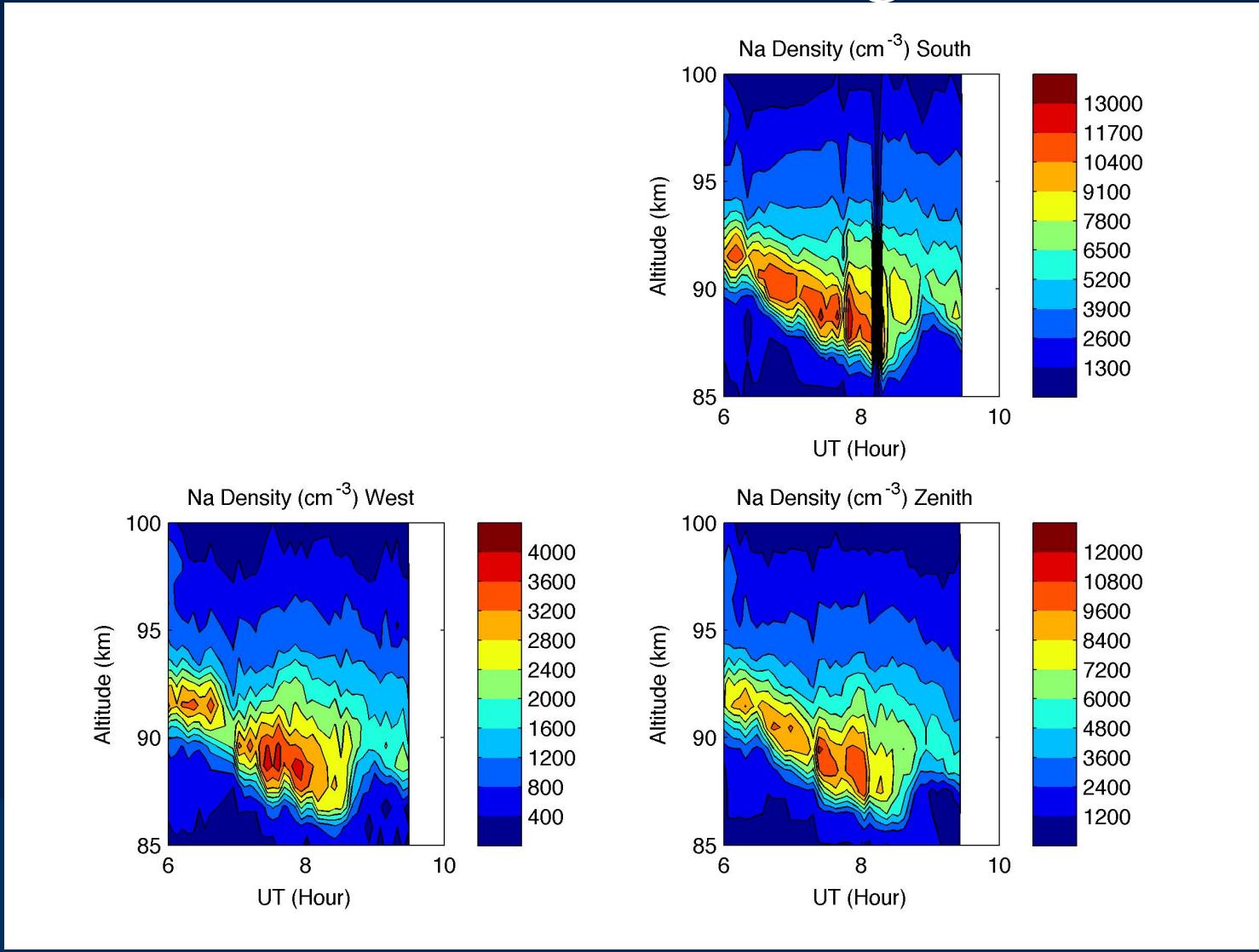


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Early results, Density, Aug, 2010



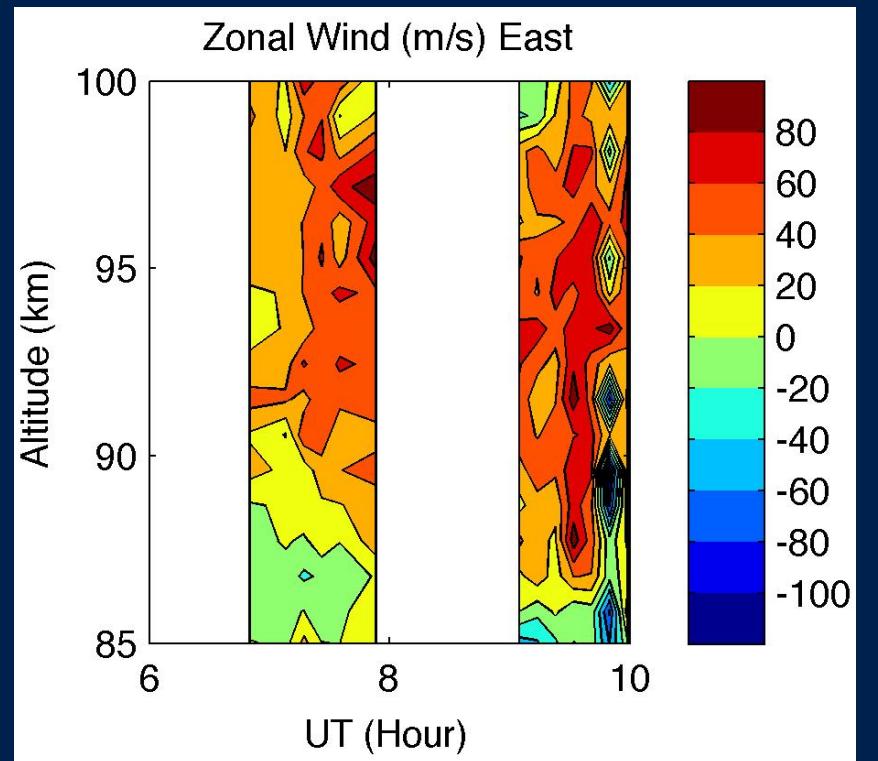
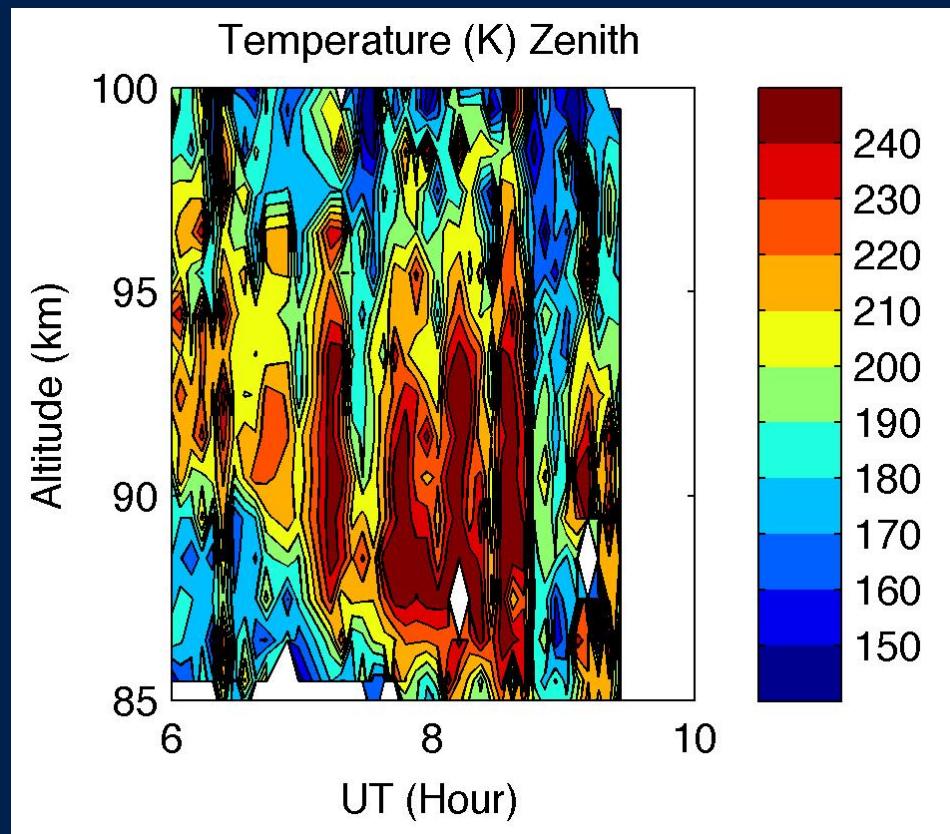
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ALO- First Results, Aug, 2010



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Early results, Wind and Temp, Aug, 2010

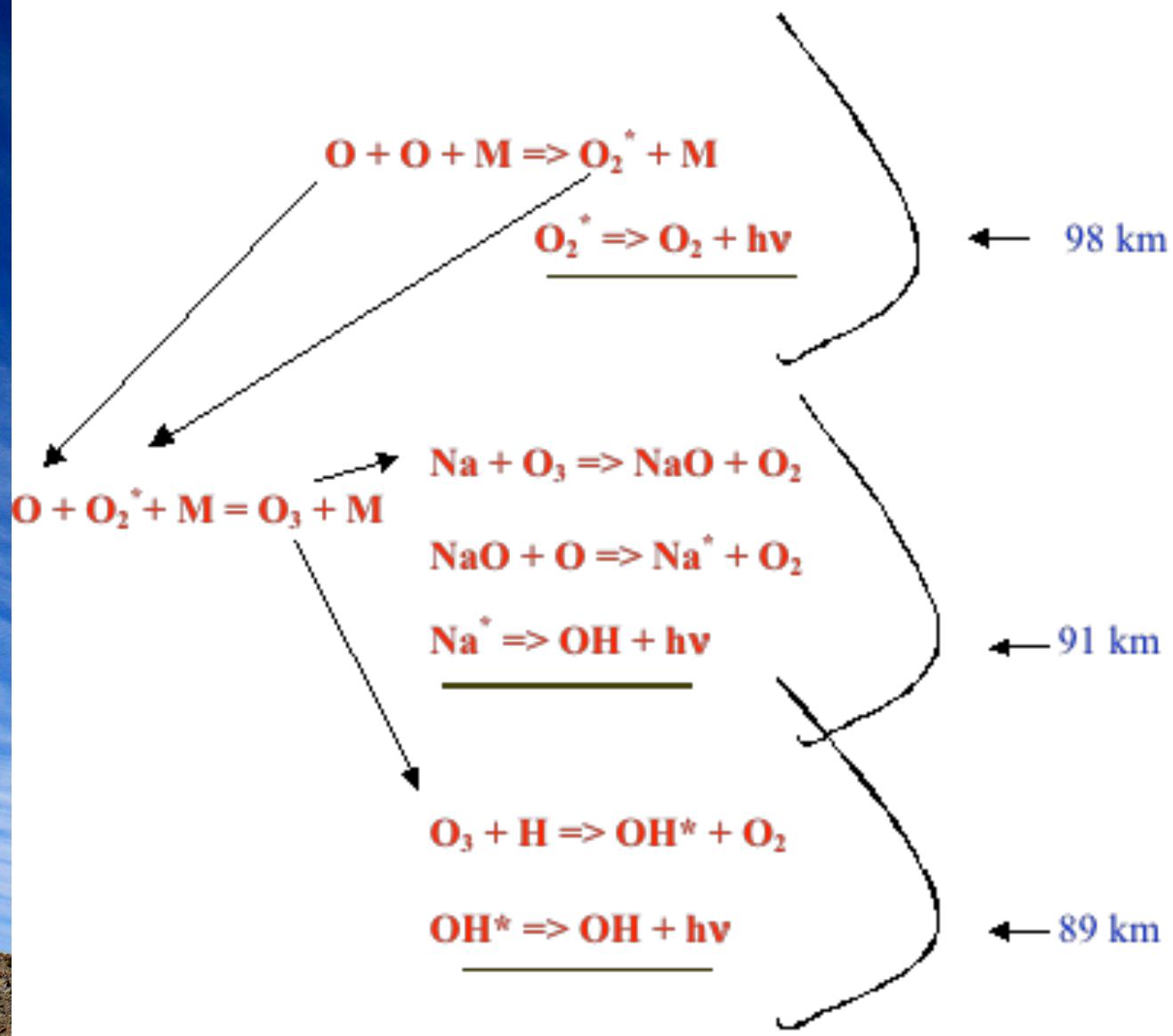


08/14

08/15

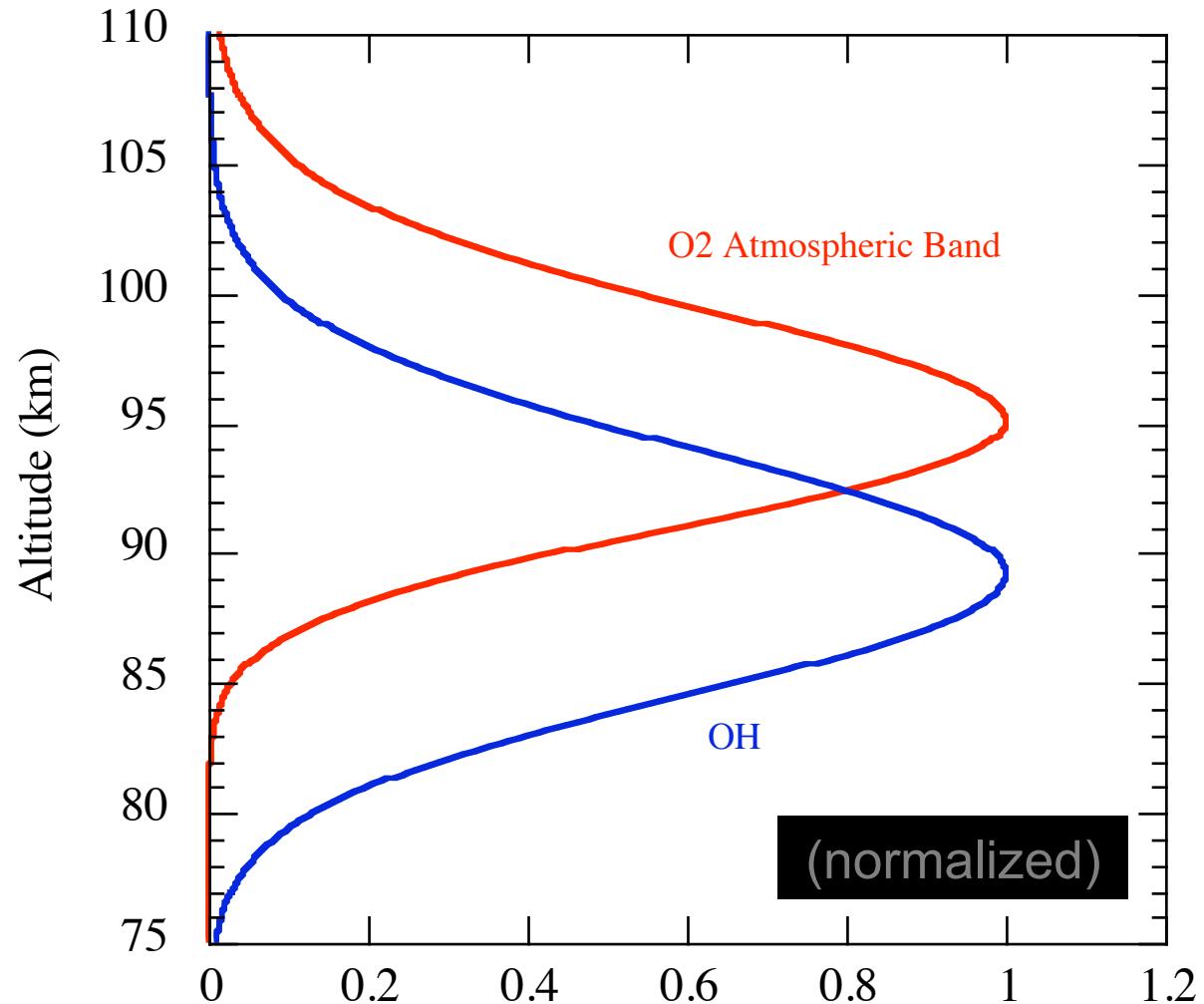
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Mesospheric Chemistry



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Unperturbed O₂ and OH Emission



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Airglow Spectra

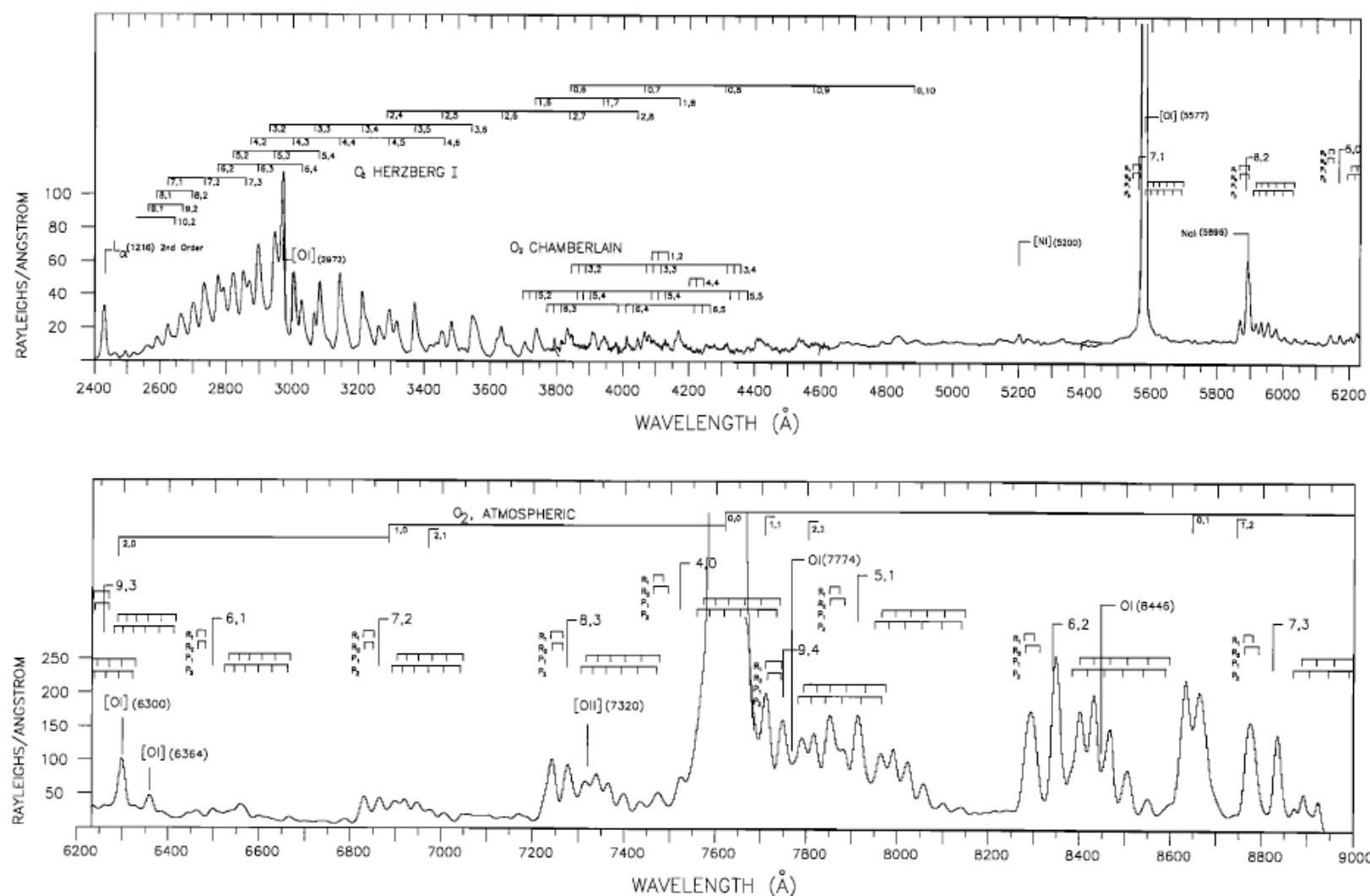
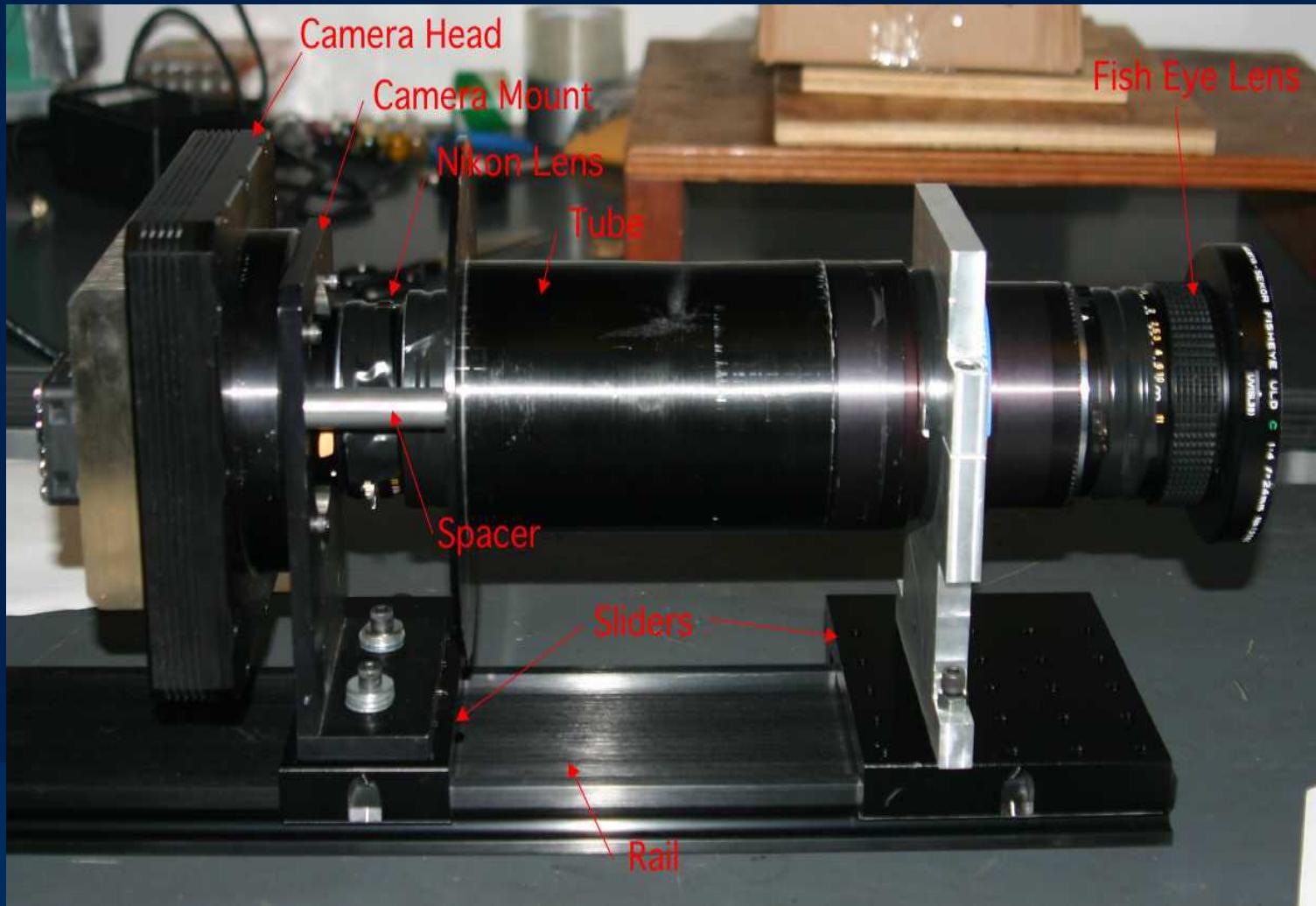


Figure 3. Sample nightglow spectrum observed by GLO-1 during the STS 53 shuttle mission. The primary atomic and molecular emissions are indicated.

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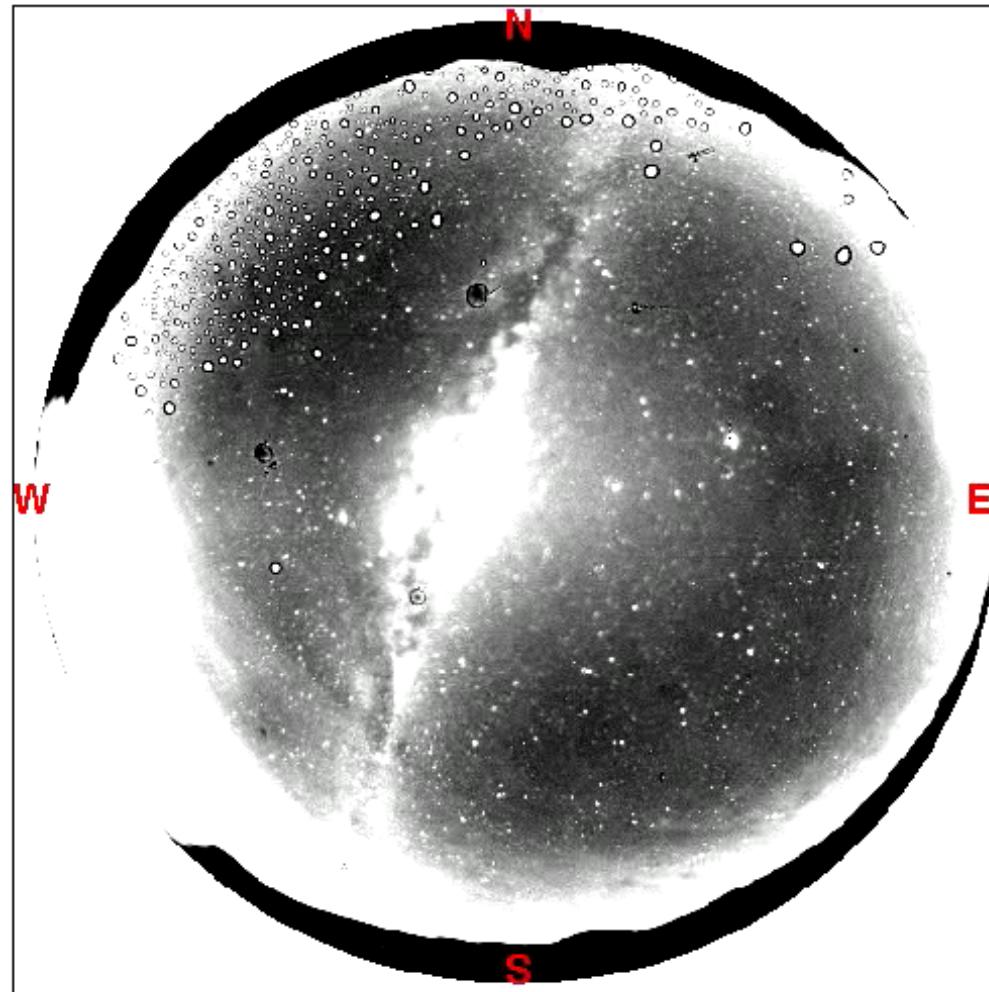
All Sky Airglow Imager



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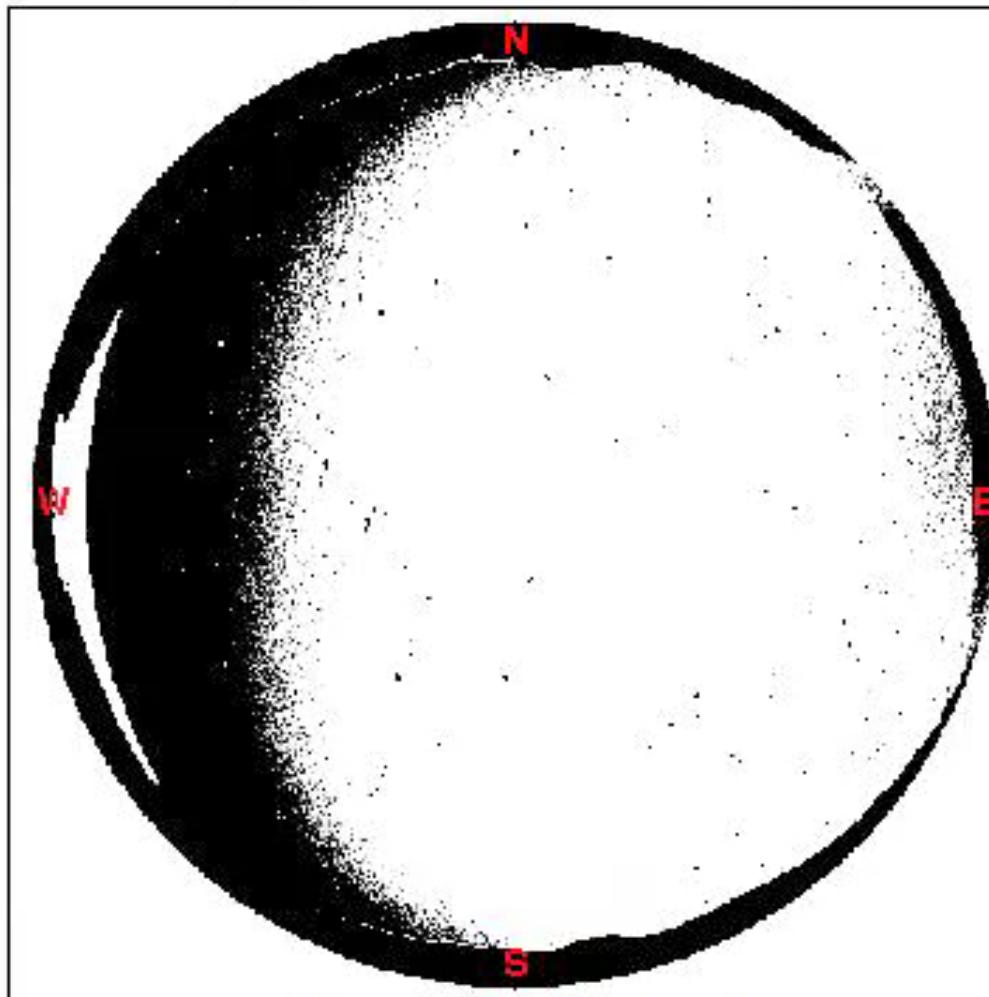
OH051 2009-09-19 23:51:06 UT



OH All Sky Imager at ALO

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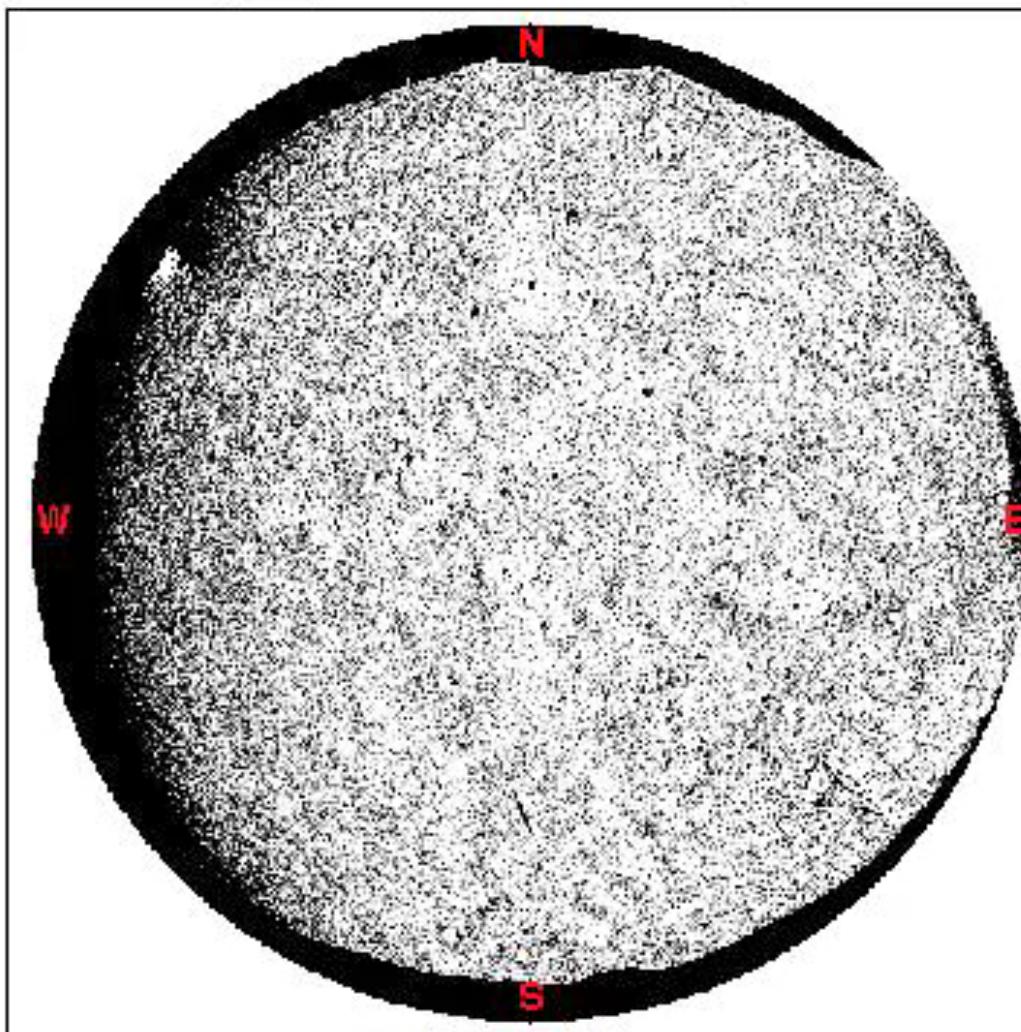
OH100508_2259_058 2010-05-08 22:59:59 UT -prev



OH All Sky Imager at ALO

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OH100417_2331_069 2010-04-17 23:31:03 UT - prev



OH All Sky Imager at ALO

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Imager Data Base:

http://eosl.csl.uiuc.edu/Data/cgi-bin/alo_imager_br.cgi?year=2010

ALO Imager Data Catalog

Select a year
2009
2010

2010

Start Date	Start Time	End Date	End Time	Duration	Keogram	Raw Movie	TD Movie
01-08	23:00:20	01-09	10:50:07	11:49:47		20100108	20100108
01-09	23:00:20	01-10	10:50:07	11:49:47		20100109	20100109
01-10	23:00:20	01-11	10:50:07	11:49:47			20100110
01-11	23:00:20	01-12	10:50:07	11:49:47			20100111
01-12	23:00:20	01-13	10:50:07	11:49:47			20100112
01-24	23:00:20	01-25	10:50:07	11:49:47			20100124

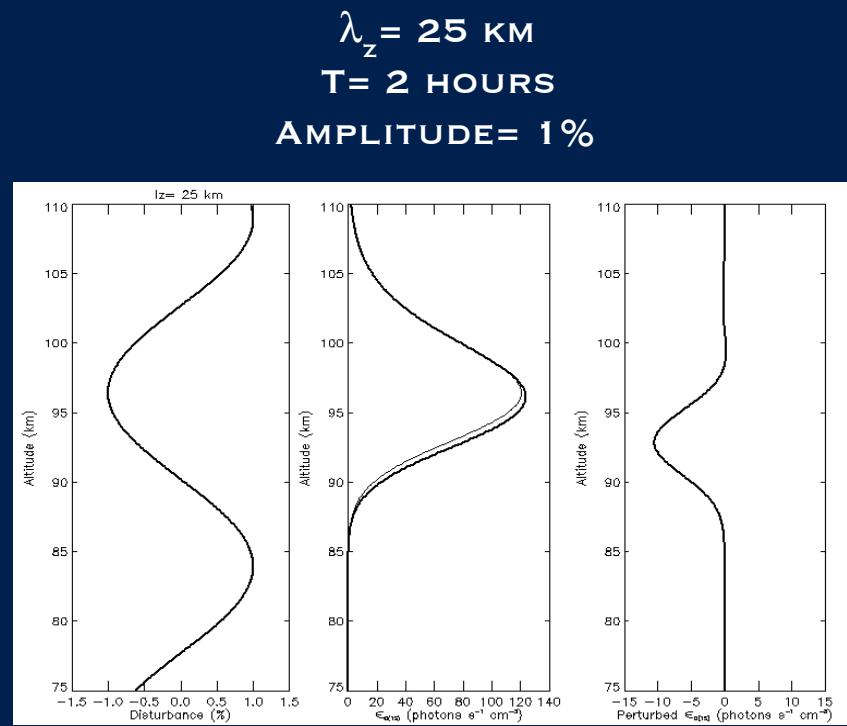
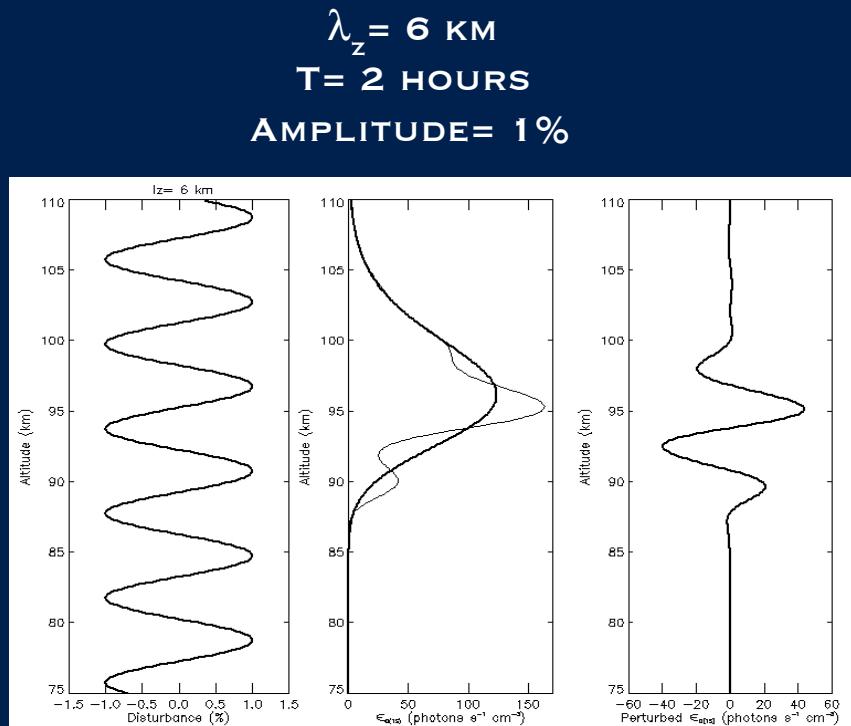
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10-01-13 00:32:33.25

ATMON'10, U of W, 13/14 Sep, 2010

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Airglow Perturbations and Gravity Waves

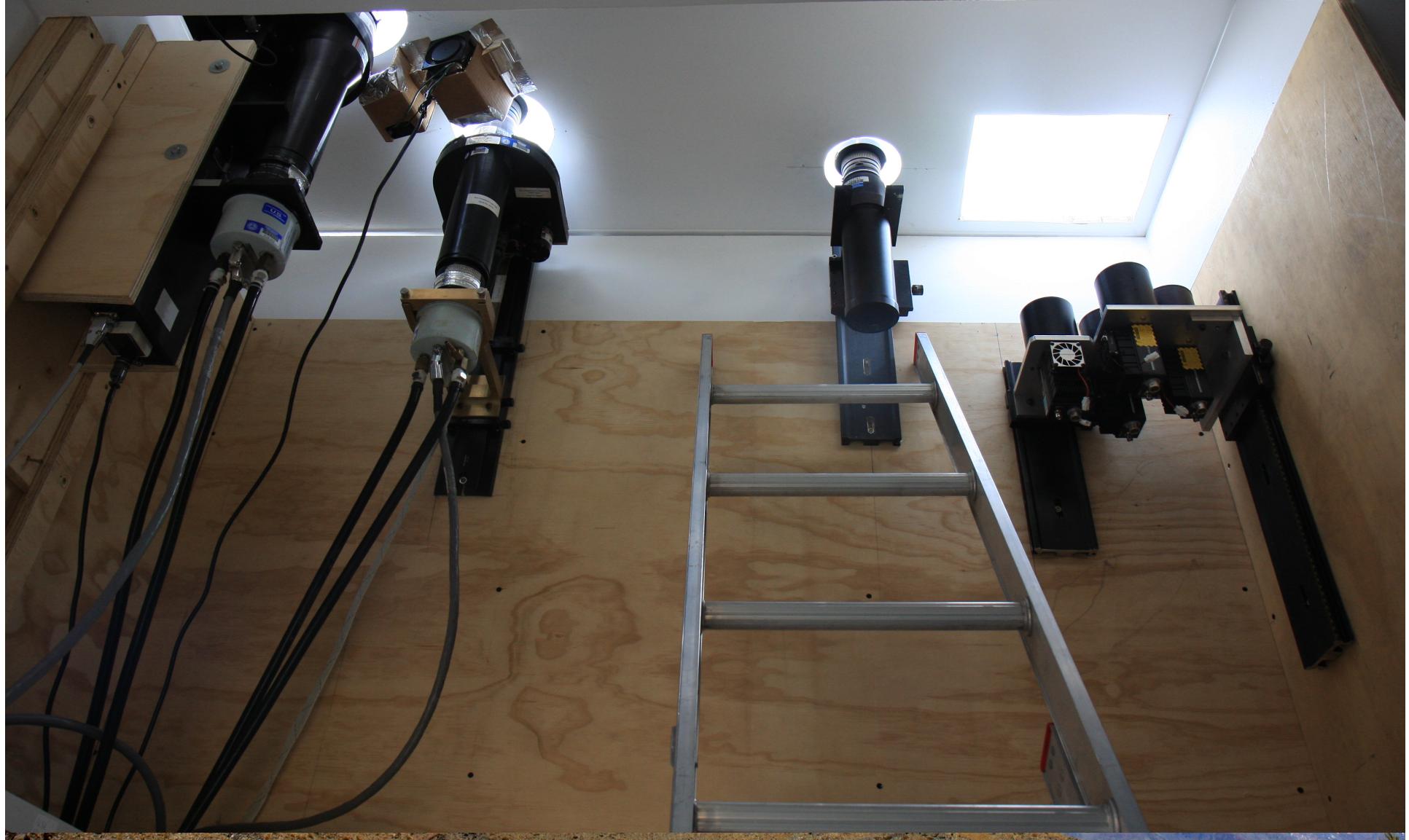


Ground based airglow observation is only sensitive to waves with vertical wavelength $> \sim 10 \text{ km}$

VARGAS ET AL. 2006

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Airglow Instruments Room



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Rayleigh (Power)

Nathaniel Liu and Gary Swenson

Objective: Sample Rayleigh returns to 130 km for density and hydrostatic temperature profile measurements.

Transmitter, 100-330 W (532 nm @ 8 kHz PRR)

(Note, may be performed at 355 nm, at lower average power)
Servo mirror, synchronously distributes into 8, 1 kHz beams
(Note, 1 kHz ranges to 150 km)

Receiver

Fiber plug with pigtails to receivers.

NOTE: Another servo can be added to pan the sampling array normal to the plane of the beam servo, and generate a 8x8 beam array over +/- 1° FOV



Lab test image of servo distributed beams,
With servo +/- .4°.

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Transmitter

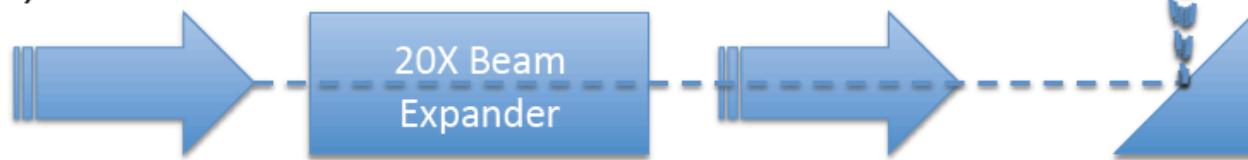
532 nm, Nd:Yag (Lee Laser LDP-200MQG)

100W average power,

8 kHz, Dia=2mm, Div=5 mr

Wall Power: 220W, 20 A (fused)

Heat: 1kW, air



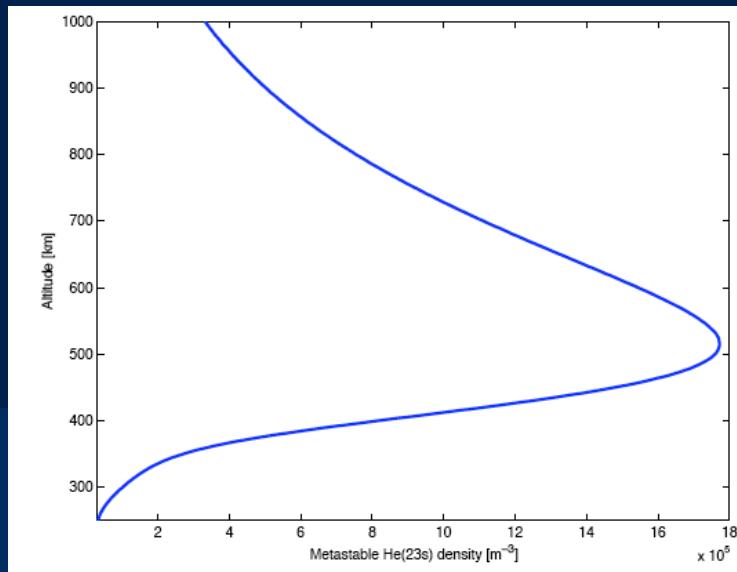
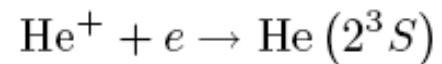
Dia=20mm,
Div=.25mr

Servo Mirror, 1 khz
i.e. 8 beam directions,
Each with 1 kHz Rate
(i.e. 150 range max);
Each with 12.5 W
average power

He Resonance Lidar

Objective: He metastable density and Doppler temperature and winds in the Thermosphere, 300-750 km altitude.

Method, resonance with He (23S), populated by photoelectrons



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Transmitter: CW, 10 W, at 1083. nm, MOPA, Fiber laser

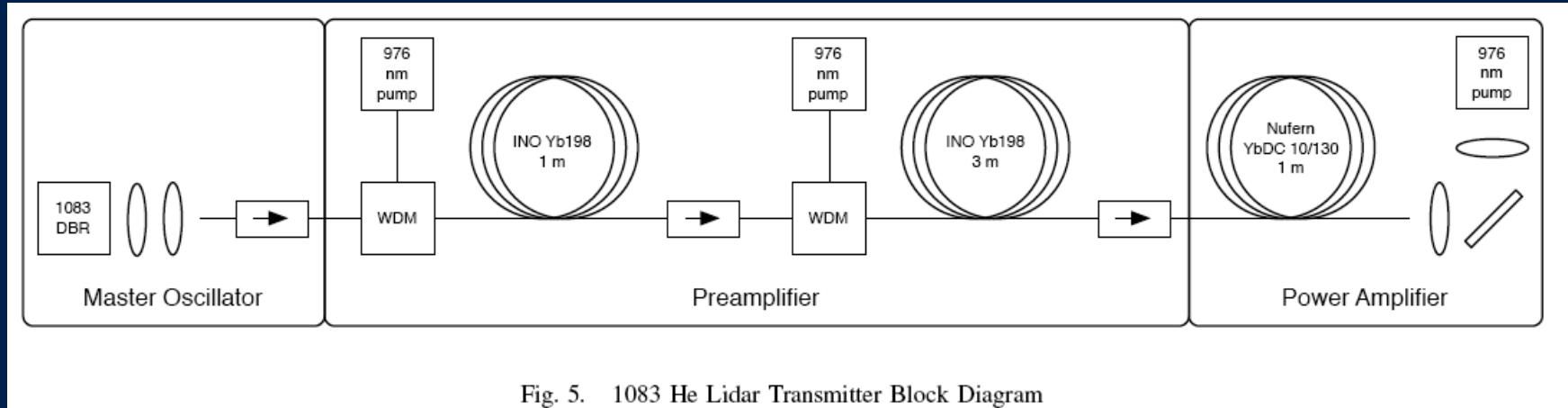
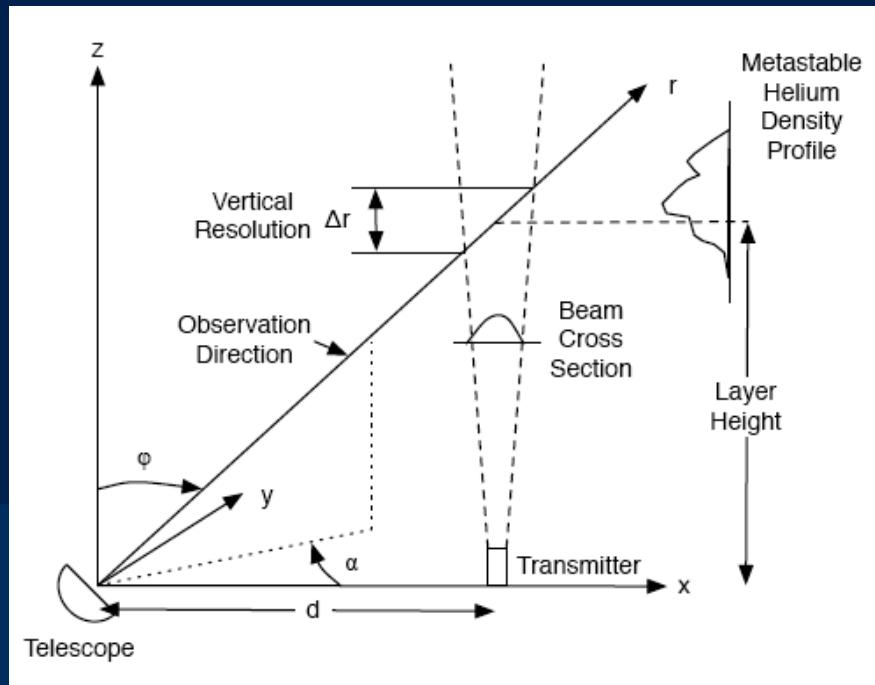
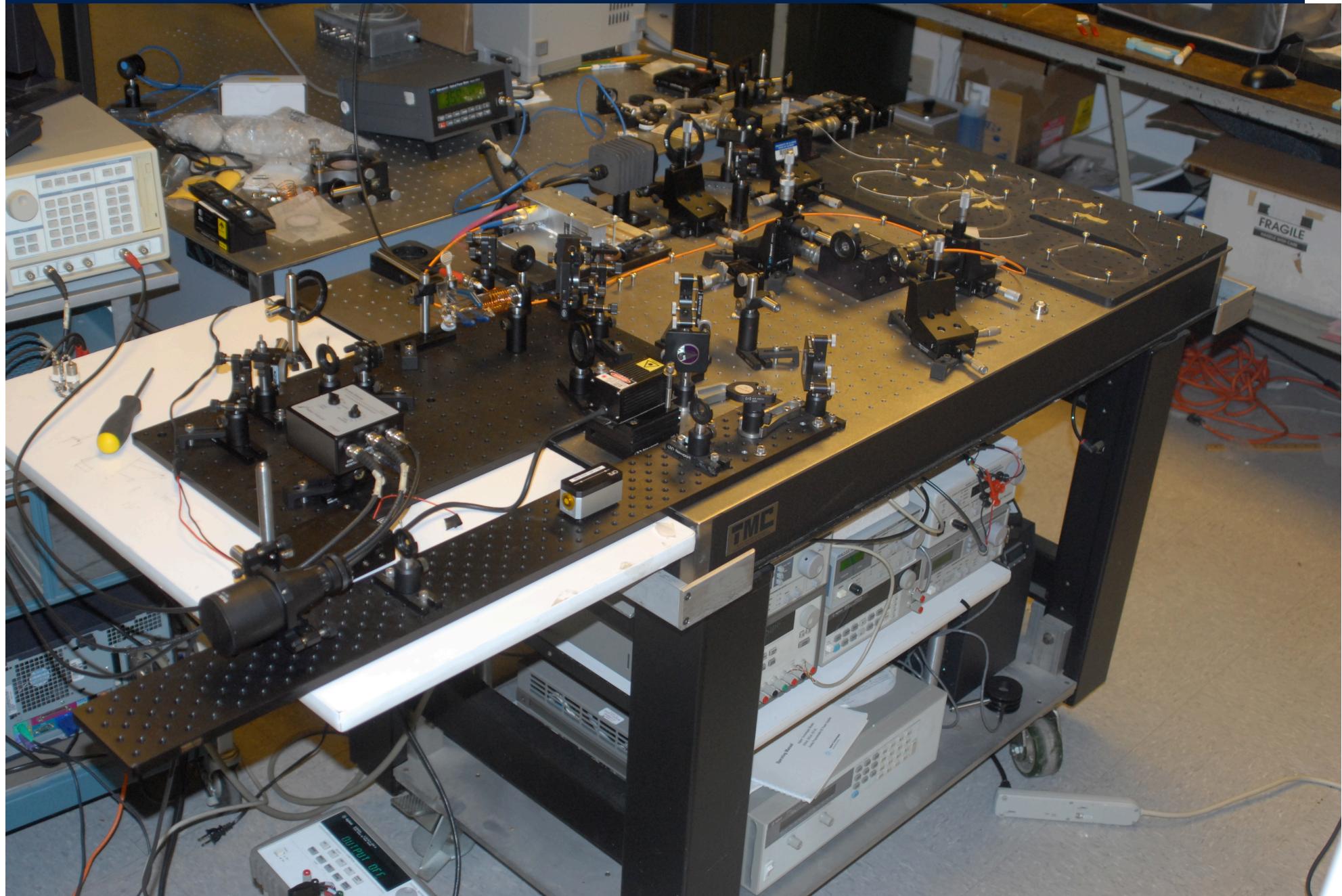


Fig. 5. 1083 He Lidar Transmitter Block Diagram

Receiver: Bistatic Imaging,
Magdalena Ridge Observatory
(Test site)



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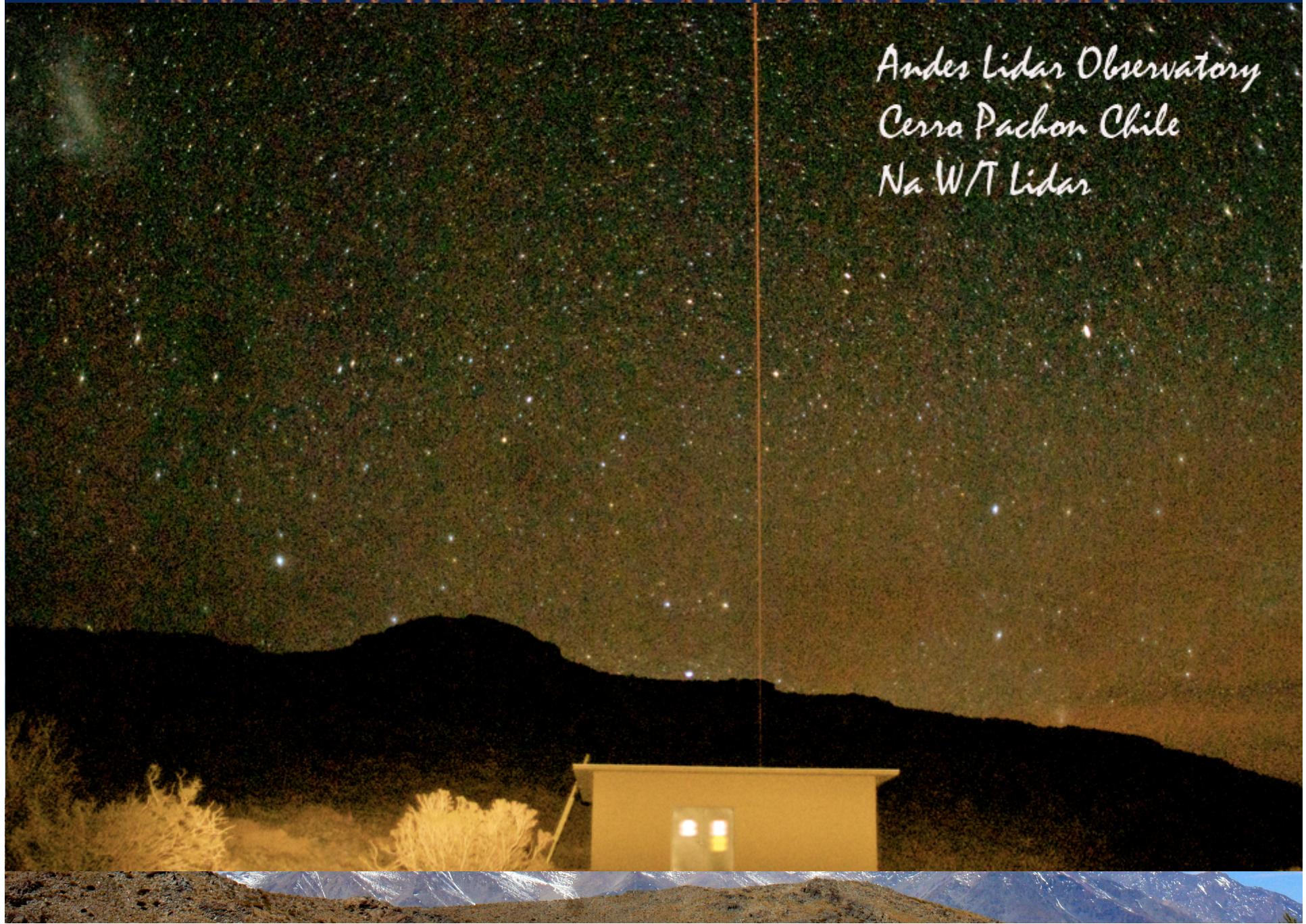
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Thank You!



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Andes Lidar Observatory
Cerro Pachon Chile
Na W/T Lidar



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