

# Graph Neural Networks for Photon Searches with the Underground Muon Detector of the Pierre Auger Observatory



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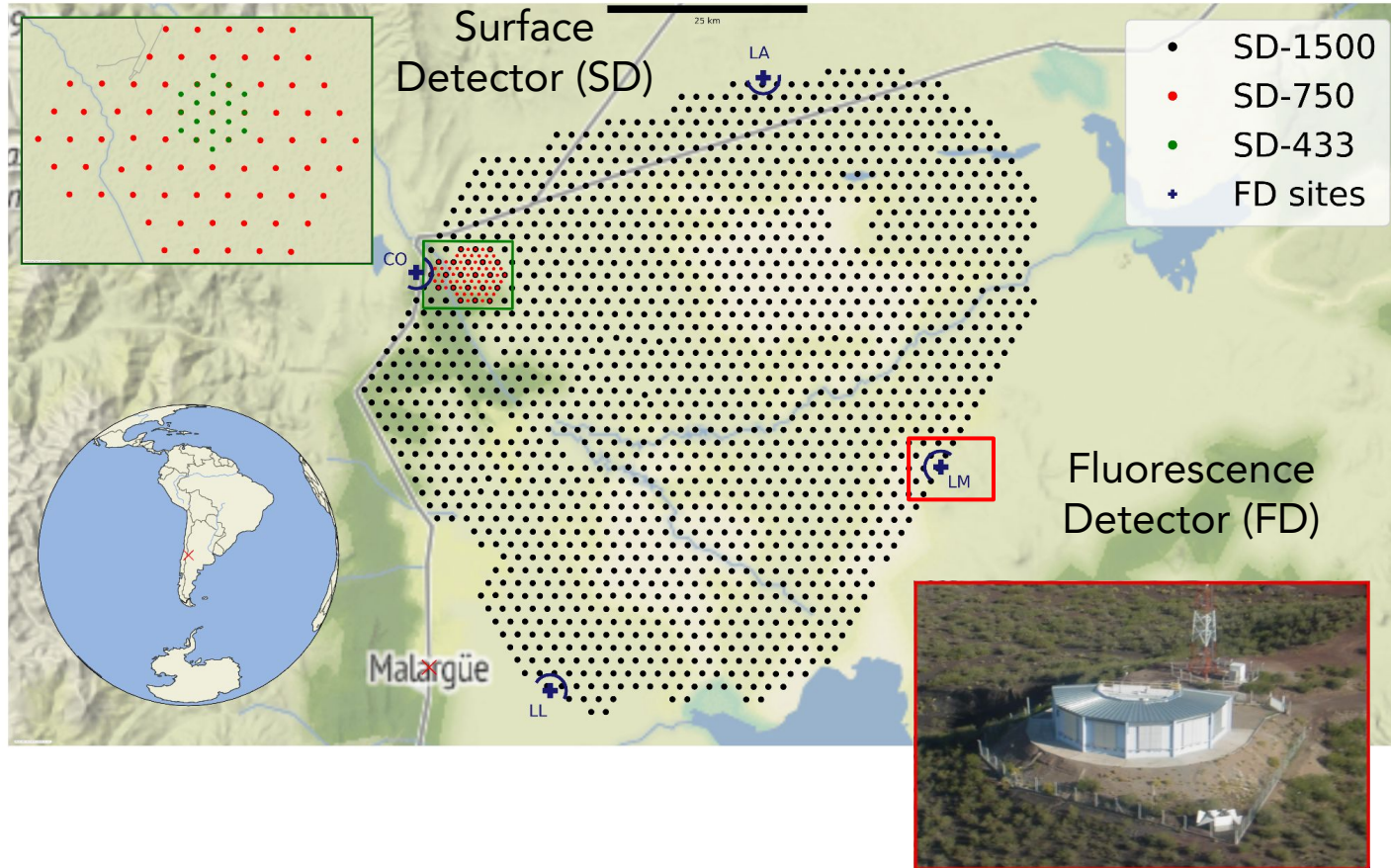
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2. Karlsruher Institut für Technologie, Karlsruhe, Germany
3. Observatorio Pierre Auger, Malargüe, Argentina

January 30, 2025

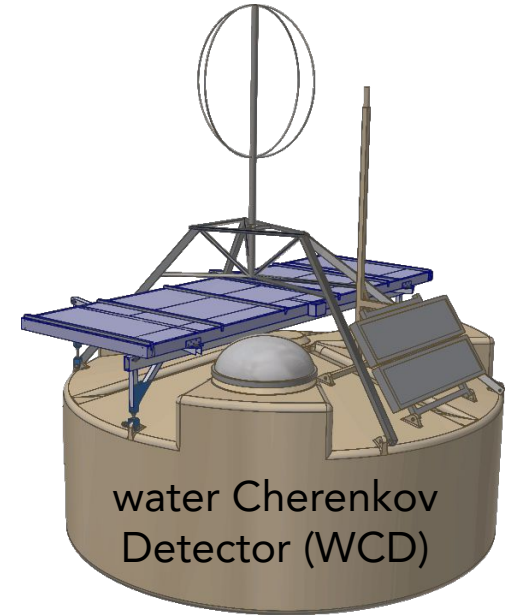
Workshop on Machine Learning for  
Analysis of High-Energy Cosmic Particles



# The Pierre Auger Observatory



## Upgraded SD station (AugerPrime)

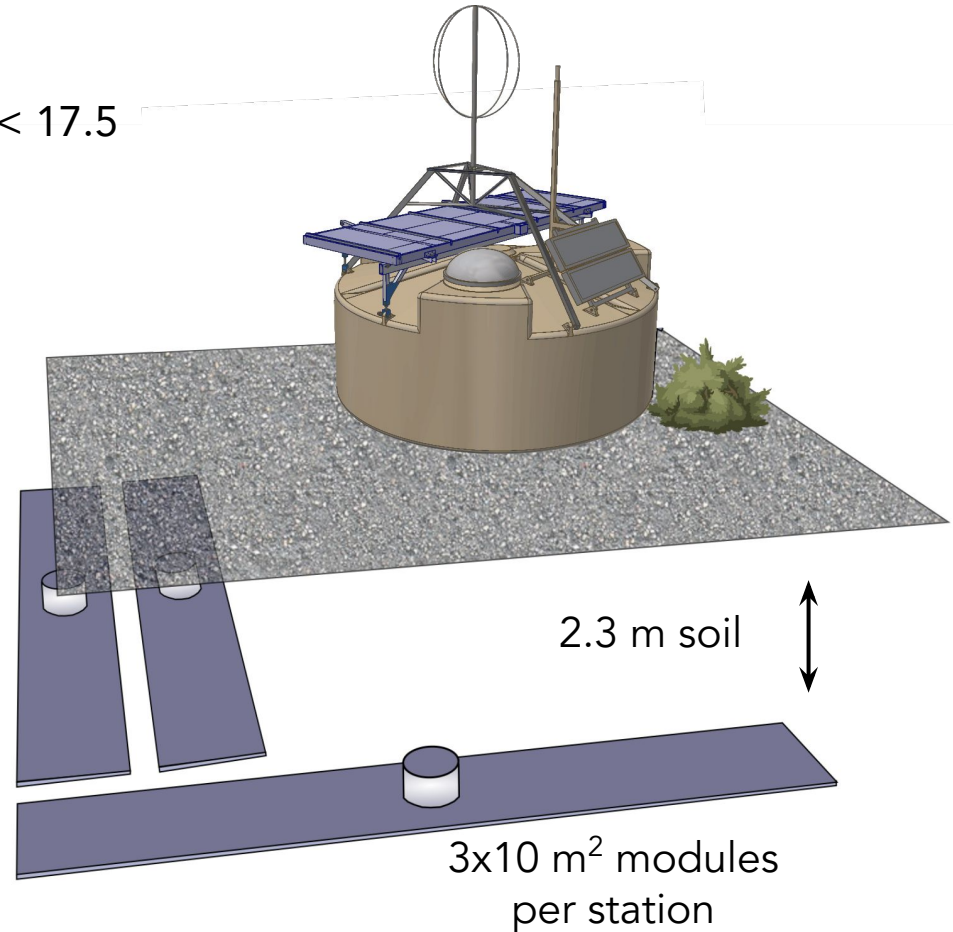
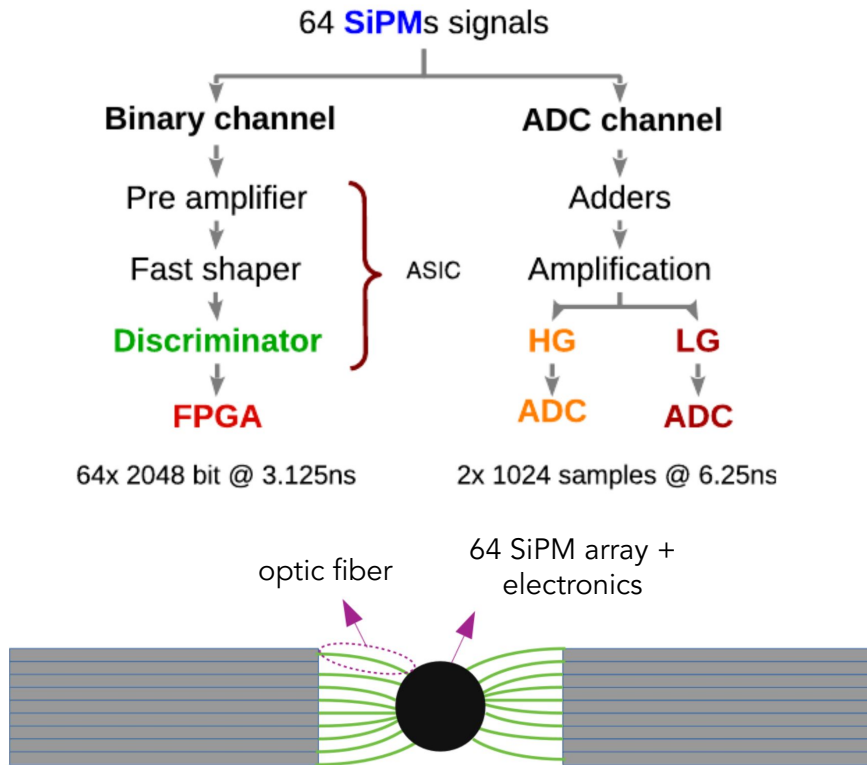


Each WCD has 3 Large Photomultiplier Tubes (PMTs)

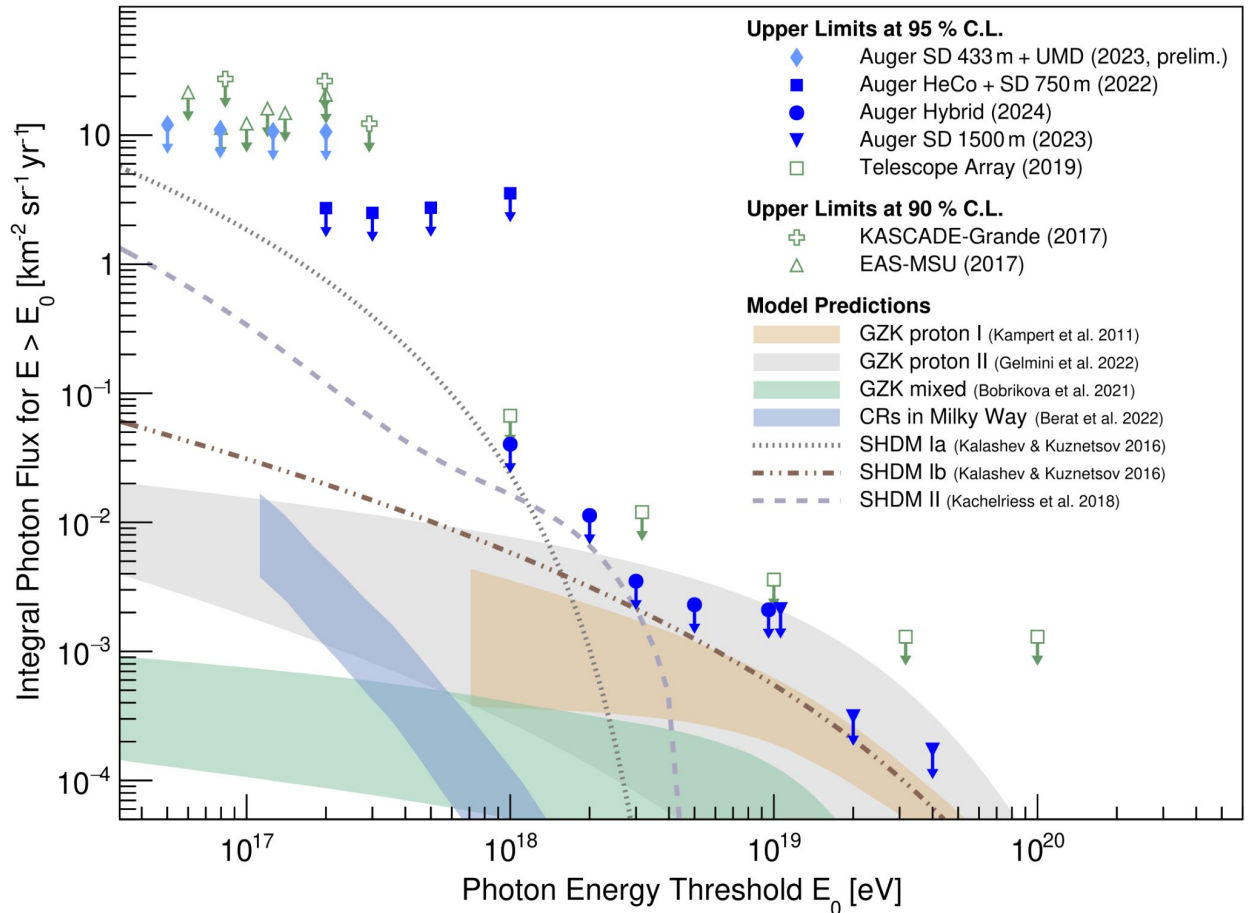


# Underground Muon Detector (UMD)

- Coupled to SD-750 and SD-433
- The energy range for this work is  $16.5 < \lg(E/eV) < 17.5$



# Photon searches at Auger

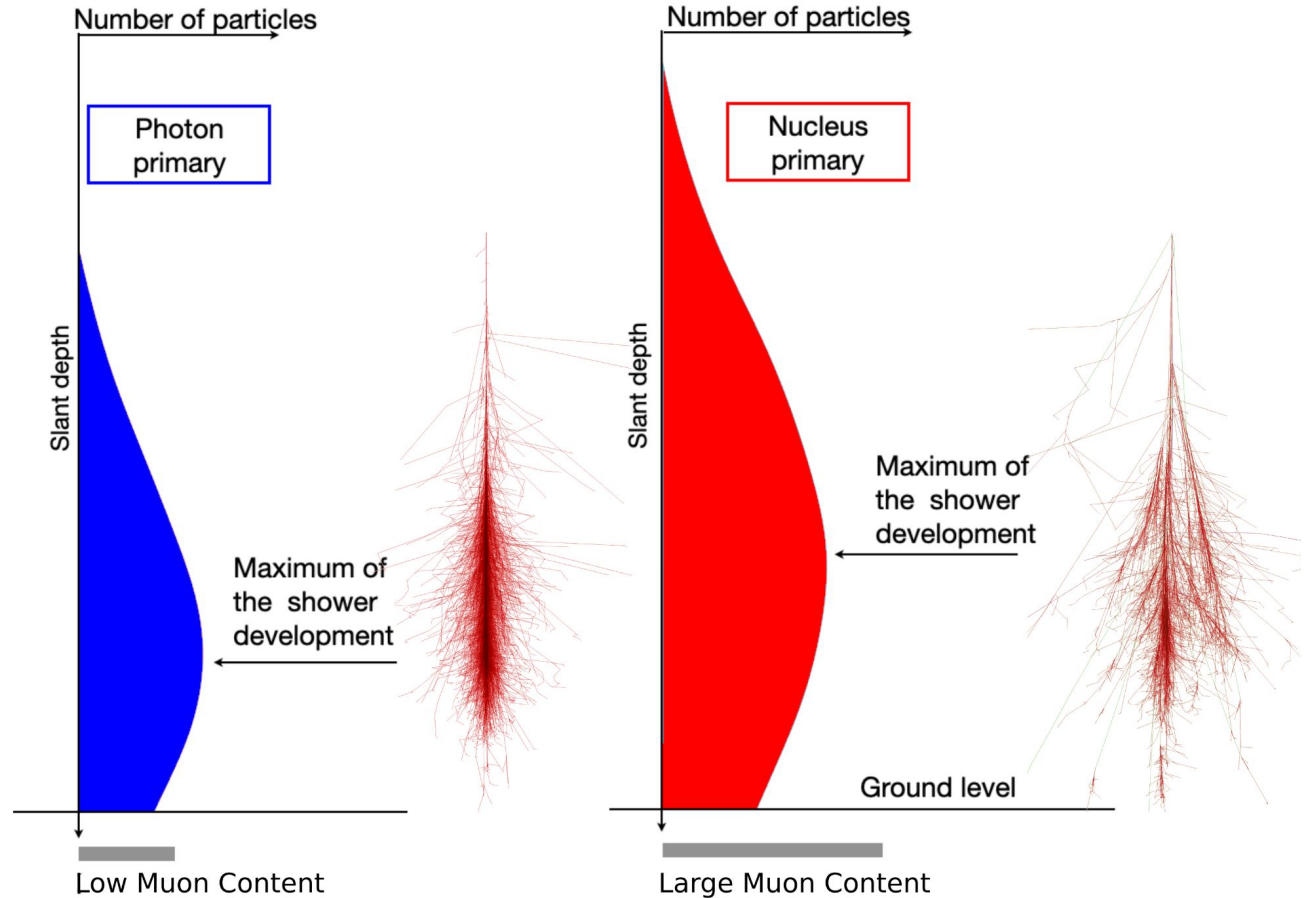


Produced in cosmic-ray acceleration sites (astrophysical fluxes), during cosmic-ray propagation (cosmogenic fluxes) or in the decay of dark matter particles, photons trace the local Universe.

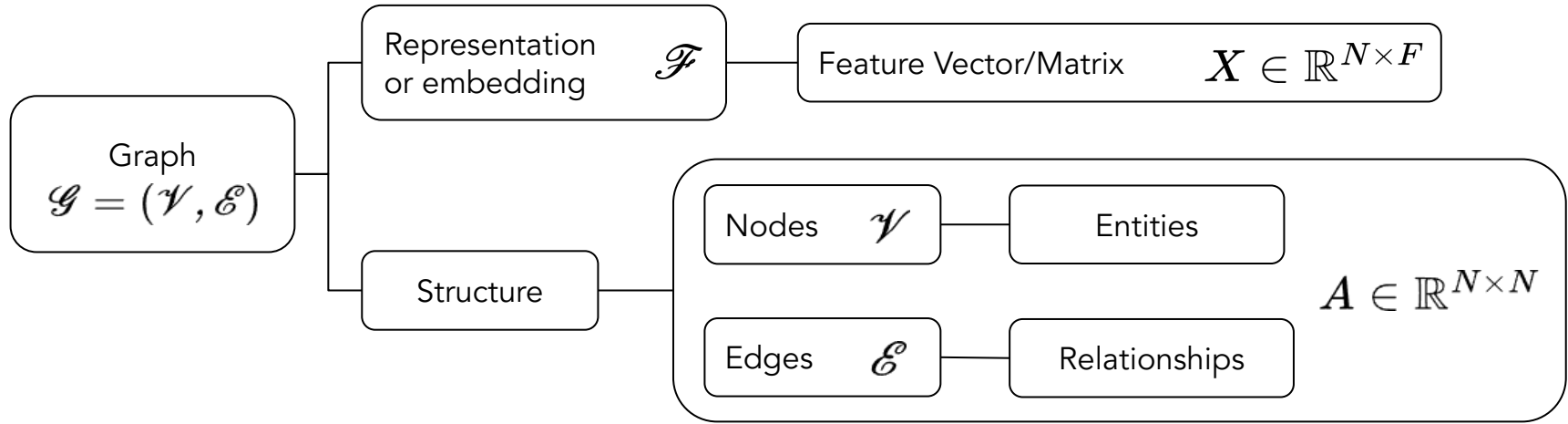
All previous searches were conducted with traditional statistical methods.

# Photon-induced air showers

- Photon-Induced Showers:  
Low muon content, develop deeper in the atmosphere.
- Hadron-Induced Showers:  
Large muon content, develop shallower in the atmosphere.

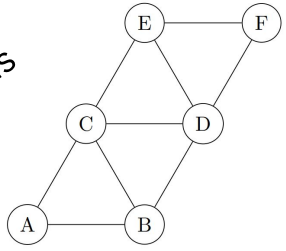


# What are graphs in the context of Deep Learning?



Toy example:

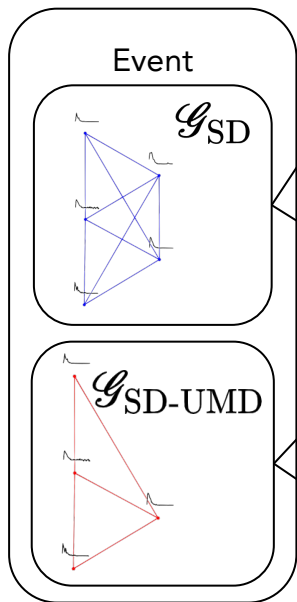
1st neighbour connections



$$\mathbf{A} = \begin{array}{c|cccccc} & A & B & C & D & E & F \\ \hline A & 0 & 1 & 1 & 0 & 0 & 0 \\ B & 1 & 0 & 1 & 1 & 0 & 0 \\ C & 1 & 1 & 0 & 1 & 1 & 0 \\ D & 0 & 1 & 1 & 0 & 1 & 1 \\ E & 0 & 0 & 1 & 1 & 0 & 1 \\ F & 0 & 0 & 0 & 1 & 1 & 0 \end{array}$$

$$\mathbf{X} = \begin{array}{c|ccc} \text{Node} & x & y & \lg(S) \\ \hline A & -216.5 & -374.98 & -0.05 \\ B & 216.5 & -374.98 & -0.08 \\ C & 0 & 0 & 2.2 \\ D & 216.5 & 0 & 0.77 \\ E & 433 & 374.98 & 0.85 \\ F & 807.98 & 374.98 & 0.29 \end{array}$$

# Event representation



$$X_{SD} =$$

Node	$\Delta x_{\text{hottest}}$	$\Delta y_{\text{hottest}}$	$\Delta z_{\text{hottest}}$	$\Delta t_{\text{hottest}}$	$n_{\text{PMTs}}$
SD <sub>hottest</sub>	...	...	...	...	...
...	...	...	...	...	...
...	...	...	...	...	...

$$X_{\text{traces}} =$$

Node	$t_1$	$t_2$	...	$t_{n_{t\text{-bins}}}$
SD <sub>hottest</sub>	...	...	...	...
...	...	...	...	...
...	...	...	...	...

$$X_{SD\text{-UMD}} =$$

Node	$\Delta x_{\text{hottest}}$	$\Delta y_{\text{hottest}}$	$\Delta z_{\text{hottest}}$	$\Delta t_{\text{hottest}}$	$n_{\text{PMTs}}$	$\rho_{\mu}$	$A_{\text{eff}}$
SD <sub>hottest</sub>	...	...	...	...	...	...	...
...	...	...	...	...	...	...	...
...	...	...	...	...	...	...	...

up to 2nd neighbour connections

More event representations in the backup slides!

- Some stations might be missing information from the UMD
- We need 2 graphs to account for missing values in UMD features
- We don't want imputation!

$X_{SD}$  : 5 rows, 5 cols

$X_{SD\text{-UMD}}$  : 4 rows, 7 cols

$X_{\text{traces}}$  : 5 rows,  $n_{t\text{-bins}}$  cols for  $\mathcal{G}_{SD}$

$X_{\text{traces}}$  : 4 rows,  $n_{t\text{-bins}}$  cols for  $\mathcal{G}_{SD\text{-MD}}$

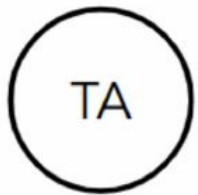
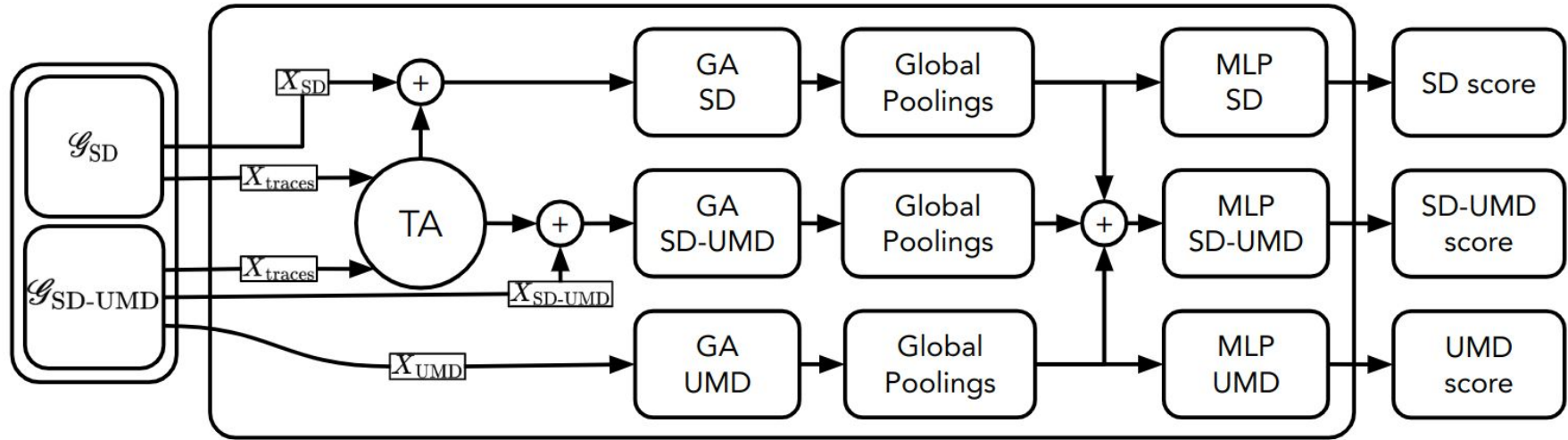
Redundant information.

$$\mathcal{V}_{SD\text{-UMD}} \subseteq \mathcal{V}_{SD}$$

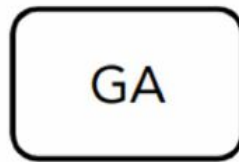
$$\mathcal{E}_{SD\text{-UMD}} \subseteq \mathcal{E}_{SD}$$

$$\mathcal{F}_{SD} \subseteq \mathcal{F}_{SD\text{-UMD}}$$

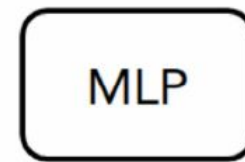
# The network



Trace Analyzer  
3 layers of 1D convolutions



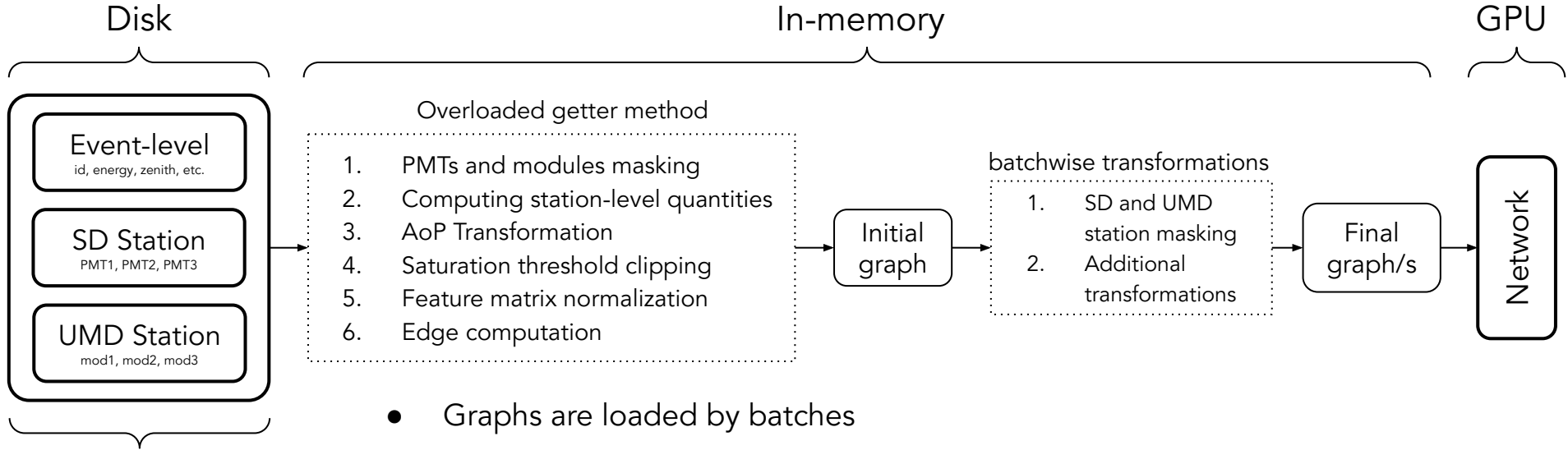
Geometry Analyzer  
3 layers of Graph Attention  
Layers (GATv2)



Multi-layer Perceptron  
3 dense layers



# Augmentation pipeline and training loop



- Pre-processed once
- Streamed from JSON files and stored in PyTorch format

- Graphs are loaded by batches
- All parts of the augmentation can be turned on and off
- Edge logic can be modified
- Graph transformations are applied in the training loop
  - Implementing transformations can be cumbersome
- Requires more memory than just reading from disk
- DataLoaders load the new batch in-memory as the current batch goes to GPU

# Dataset and training

Models: EPOS-LHC; FLUKA INFN

Offline: v4r0p2-pre3

CORSIKA: 7.7xx

Energy range:  $\lg(E/eV) \in (16.5-17.5)$

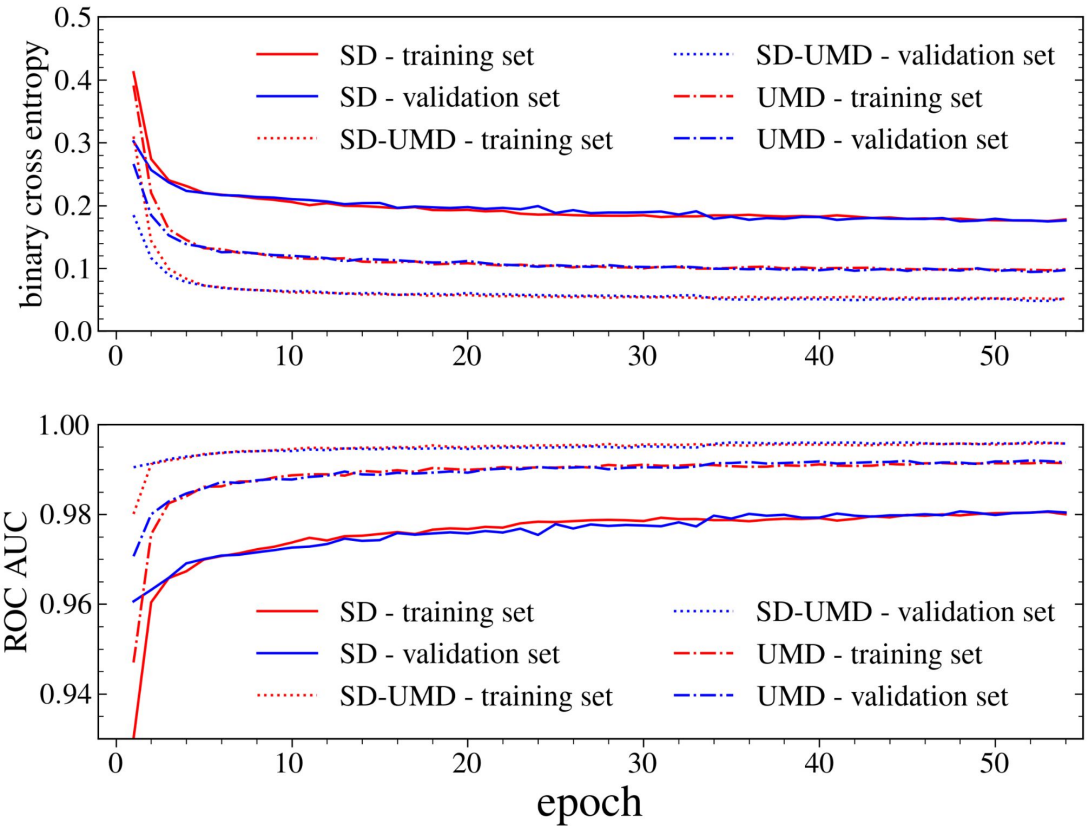
Zenith up to 45 deg

Training: 118k, Validation: 40k, Testing: 50k

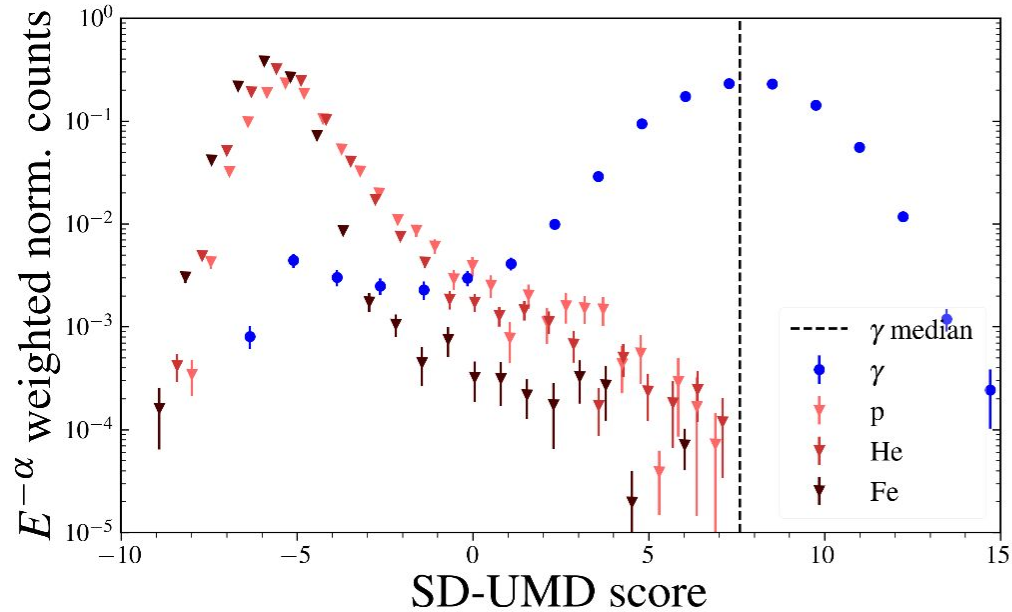
Equal Mix of photons/protons

- Binary cross entropy as loss
  - global loss is the sum of the 3 losses
- We augment the dataset during training

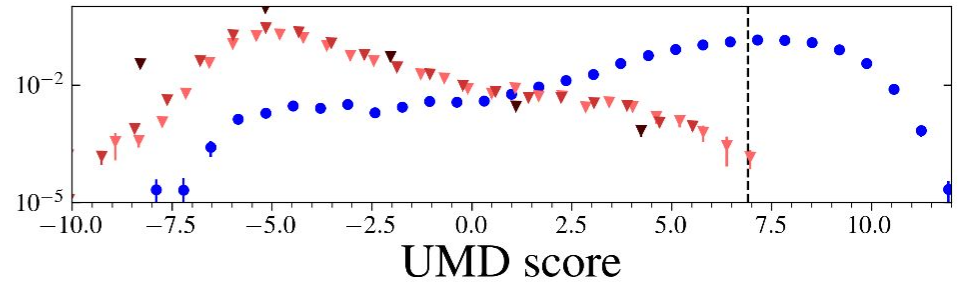
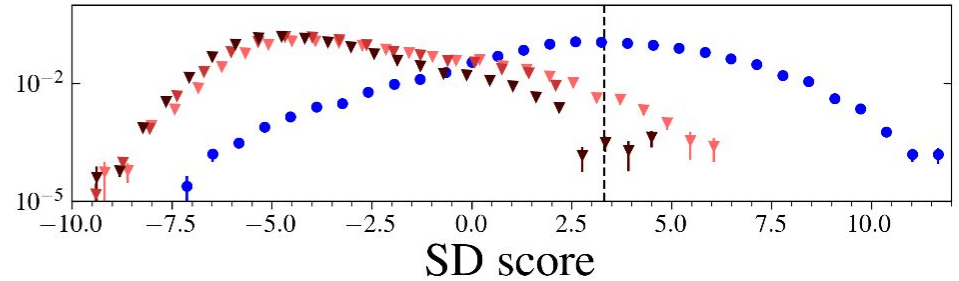
Check the backup slides for more information.



# Performance



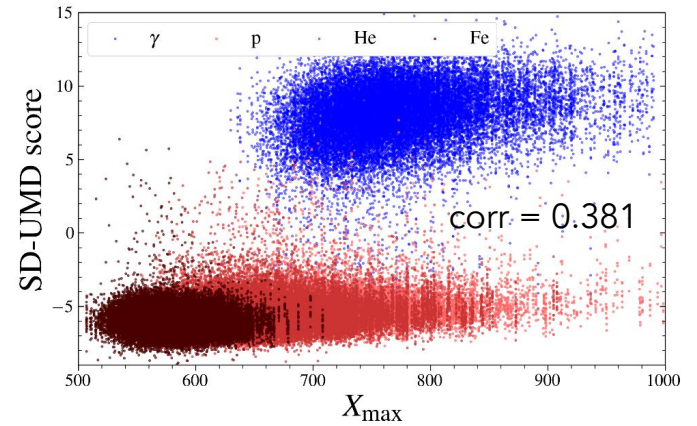
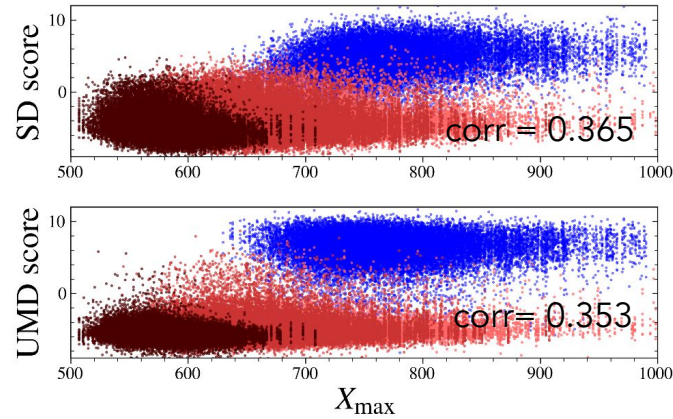
Photons are weighted by  $\propto E^{-2}$  and  
hadrons  $\propto E^{-3}$ .



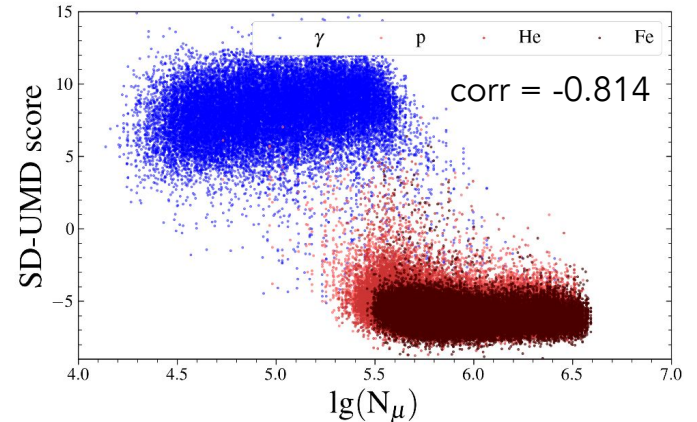
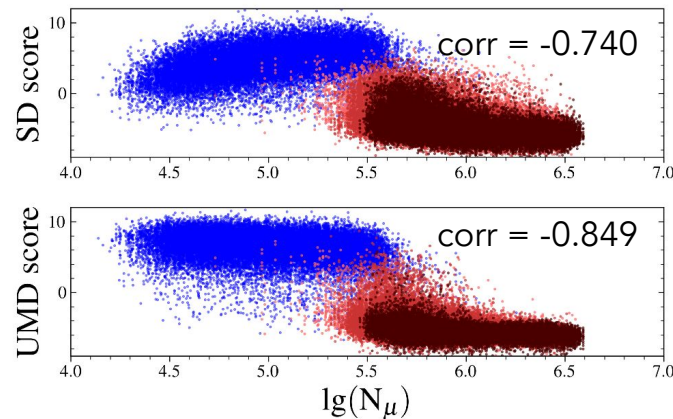
- Complete energy and zenith range ( $\lg(E/\text{eV}) \in (16.5-17.5)$  &  $\theta < 45$  deg)
- No background events after signal median  $\rightarrow$  study of tail of distributions for bkg. estimation
- Separation improves with the primary mass

# Scores vs MC quantities

Best correlation with  $X_{\max}$   
UMD-SD score



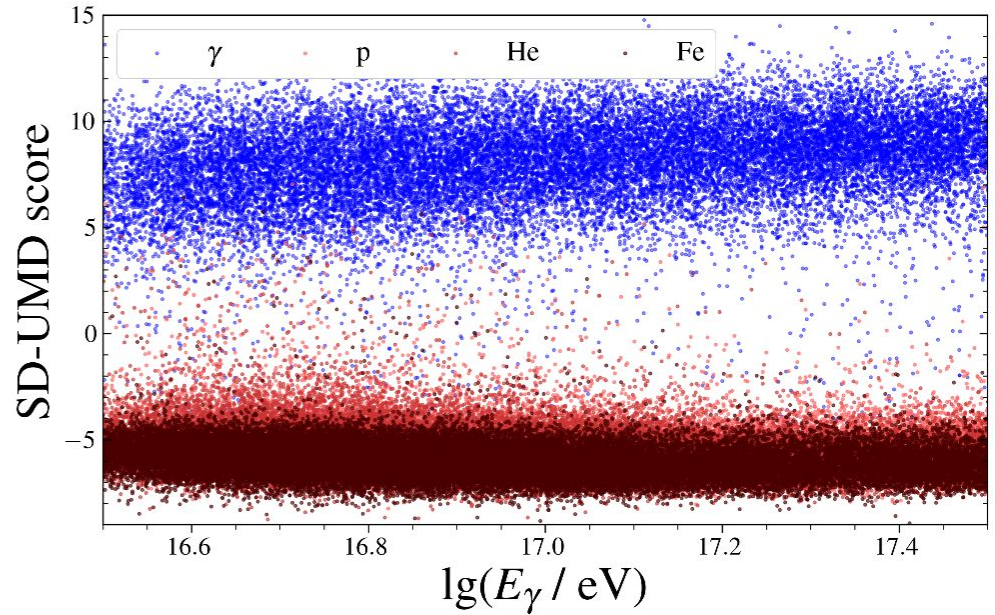
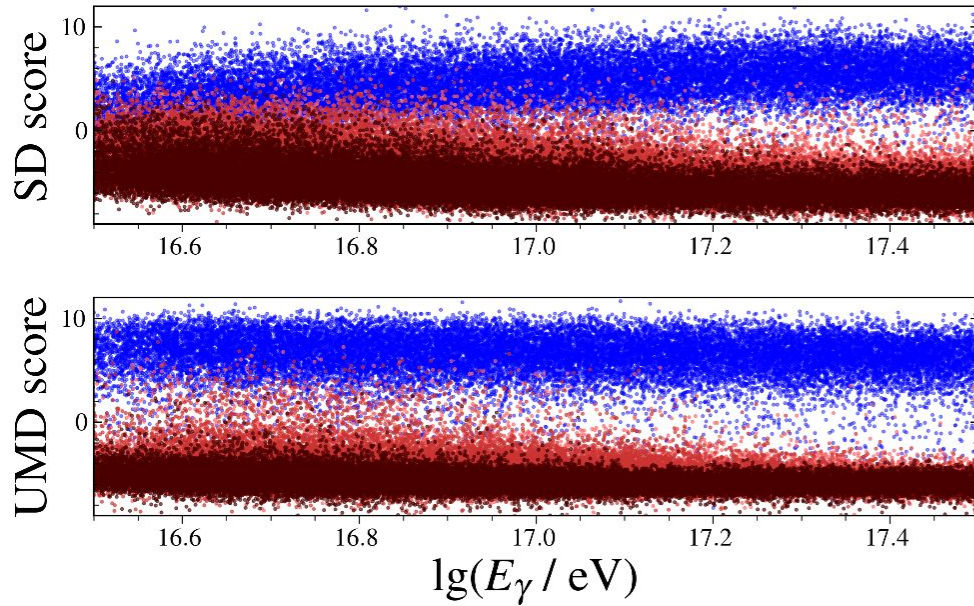
Best correlation with  
 $\lg(N_{\mu})$   
UMD score



The score reflects physical air-shower observables

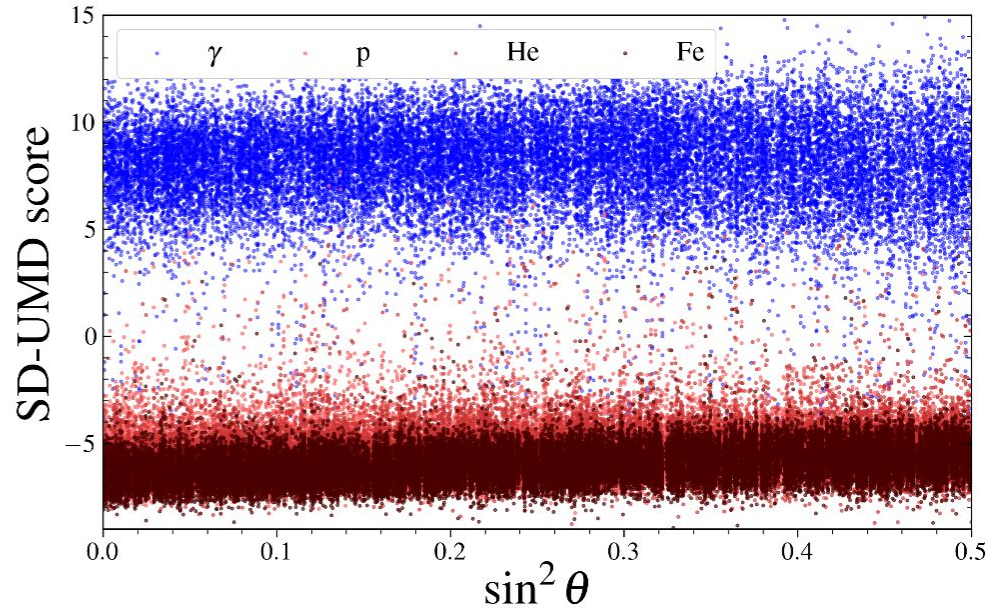
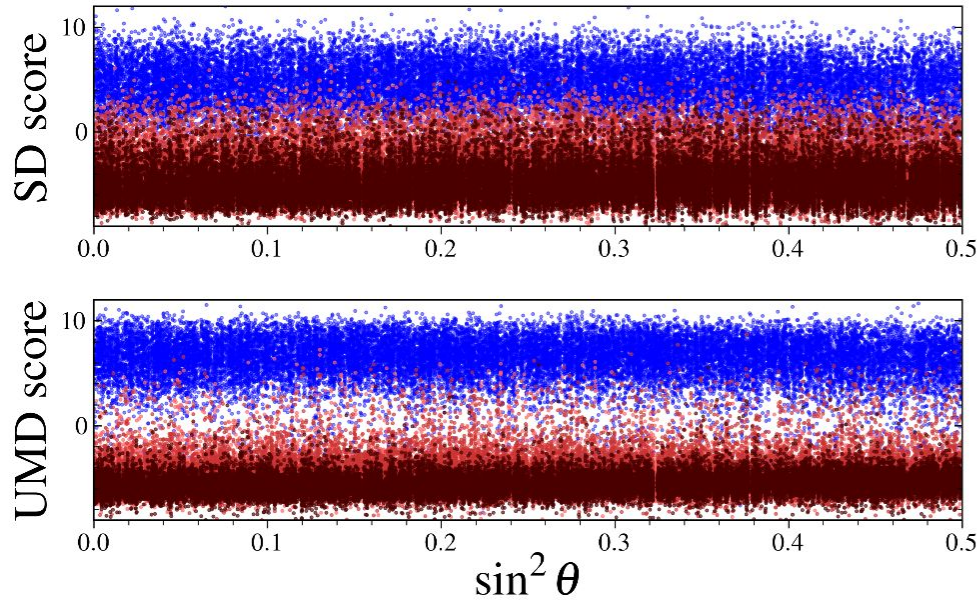


# Scores vs reconstructed photon energy



Discrimination depends little on reconstructed energy  $E_\gamma$

# Scores vs reconstructed zenith angle



Discrimination depends little on reconstructed zenith angle

# Summary

- Cosmic rays below  $10^{17}$  eV can be measured with Auger SD+UMD 433 m array
- In the quest for photon detection at the  $10^{16}$  eV decade, graphs allow for different types of representations
- Separating information inside the network allows for some level of introspection
- Networks are able to separate photons from hadrons
  - Cross-check with heavier primaries shows promising results
  - Separation depends little on reconstructed energy and zenith angle

Backup



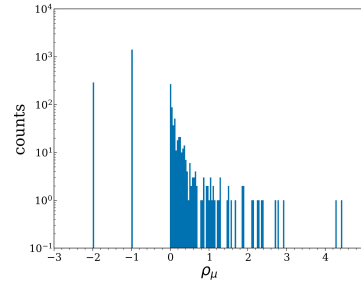
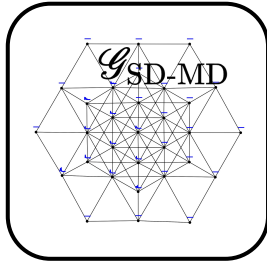
# Event representation with homogeneous graphs

1 graph = 3 matrices (features, traces, edges)

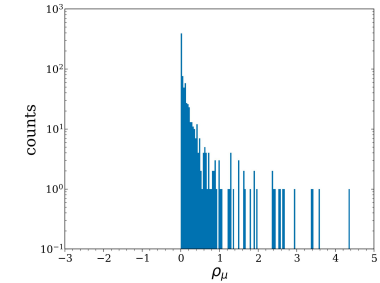
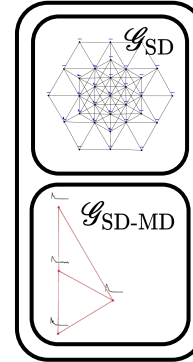
single input

dual input

with  
non-triggered  
stations

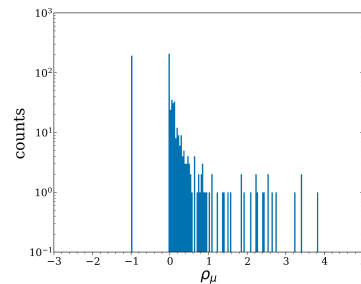
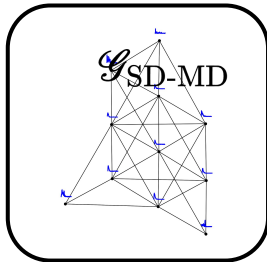


Min Max Scaling

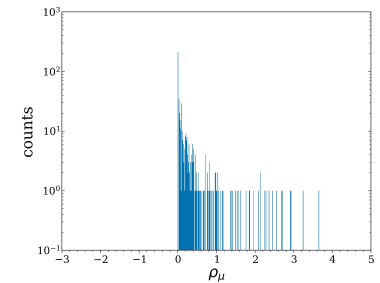
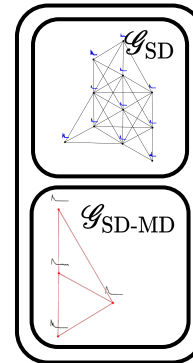


Standardization

without  
non-triggered  
stations



Min Max Scaling



Standardization

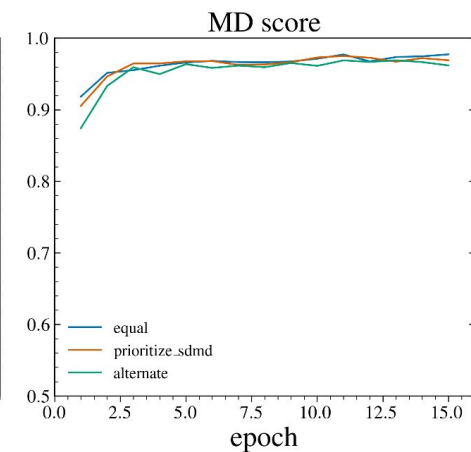
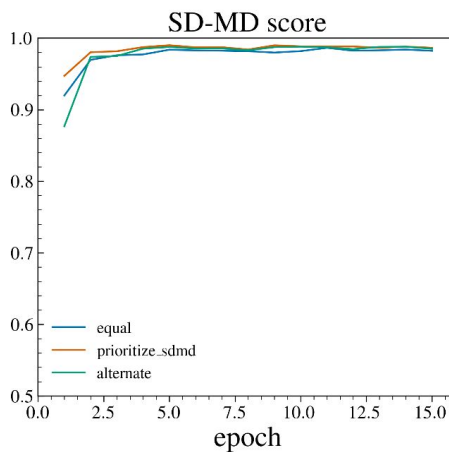
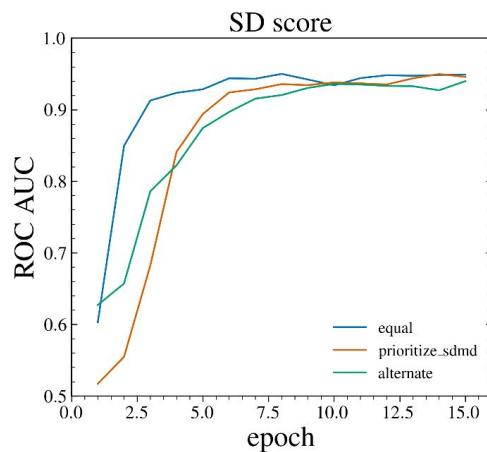
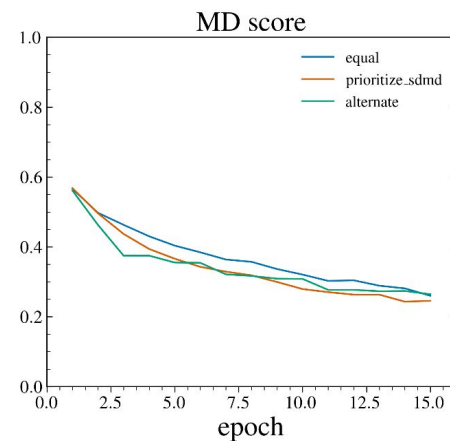
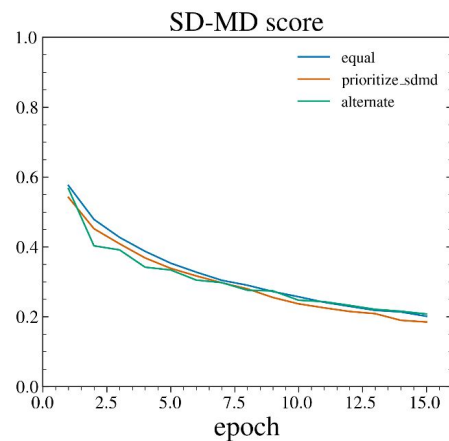
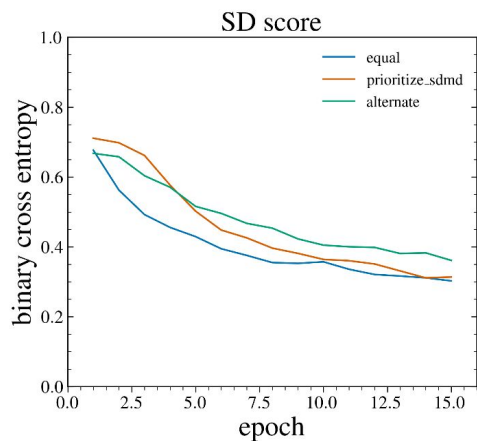
# Learning curves for different training strategies

## Test with reduced dataset

10000 training events

1000 validation events

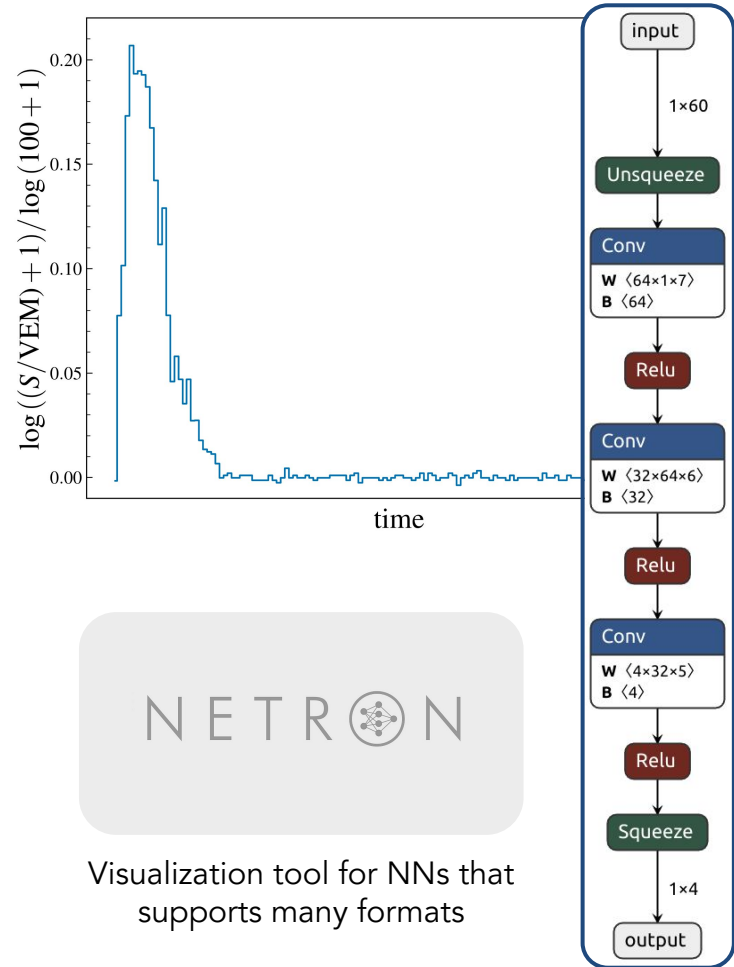
Only 15 epochs



# Trace Analyzer

- First 60 bins of the averaged VEM trace
- Randomly masking 0, 1, or 2 PMTs
- Batch normalization helps A LOT
- Only 4 features as output → Thanks Fiona!
- One Trace Analyzer for the whole network

```
TraceAnalyzer(  
  (conv_layers): Sequential(  
    (0): Conv1d(1, 64, kernel_size=(7,), stride=(3,))  
    (1): BatchNorm1d(64, eps=1e-05, momentum=0.1, affine=False, track_running_stats=True)  
    (2): ReLU()  
    (3): Conv1d(64, 32, kernel_size=(6,), stride=(3,))  
    (4): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=False, track_running_stats=True)  
    (5): ReLU()  
    (6): Conv1d(32, 4, kernel_size=(5,), stride=(1,))  
    (7): BatchNorm1d(4, eps=1e-05, momentum=0.1, affine=False, track_running_stats=True)  
    (8): ReLU()  
  )  
)
```



# Graph Convolutional Networks (GCN)

new representation

linear combination of features

$$H^{k+1} = \sigma \left( \underbrace{\tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}}}_{\text{weights based on neighborhood and node degree}} \underbrace{H^k W^k}_{\text{learnable parameters}} \right)$$

activation function

$$\tilde{A} = A + \mathbf{I}$$

$$\tilde{D}_{ii} = \sum_j \tilde{A}_{ij}$$

weights based on  
neighborhood and node  
degree

learnable  
parameters

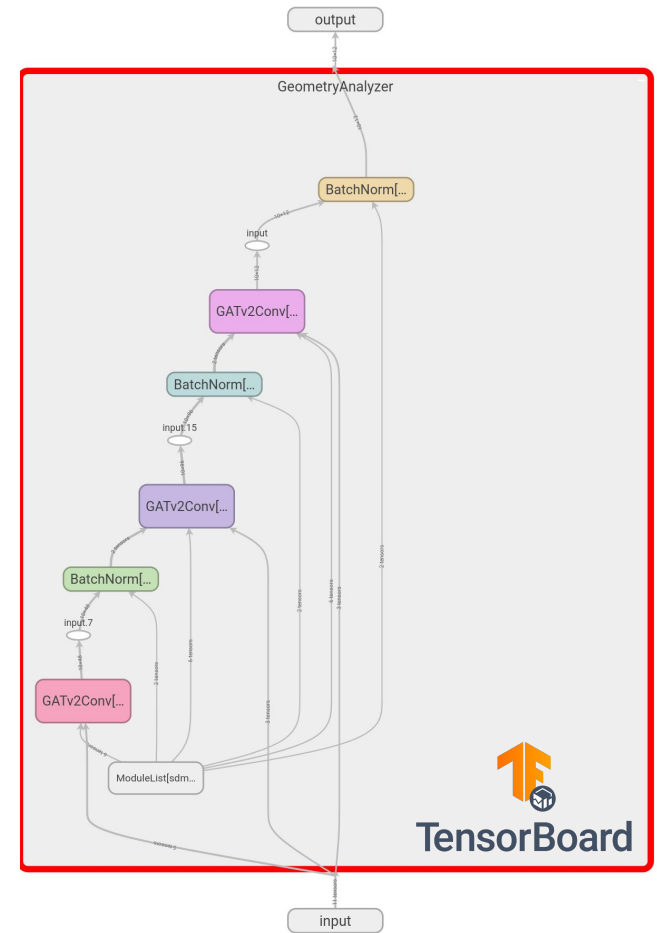
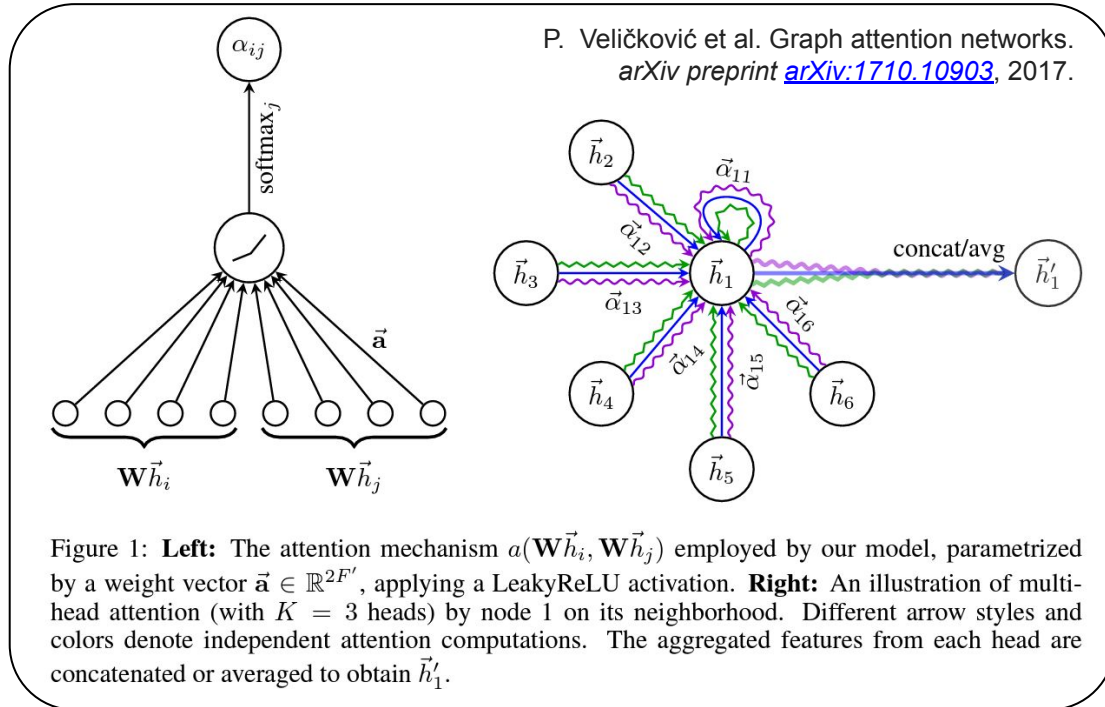
Conceptually: fancy linear combination

In practice: Forward Pass is just matrix multiplication



# Geometry Analyzer using Graph ATtention

- Using 3 Graph Attention layers
- 3 Geometry Analyzers
- 3 attention heads per layer
- Batch normalization here too



# Augmentation

Generating more simulations from existing simulations.

- Increase the variability in the dataset
  - ~105.k photon and ~105.k divided in train/validation/test sets)
- Reproduce more faithfully the events in data
  - Simulations are ideal (saturation effects, ageing, black tanks, etc.)
- Stress in the training to get a more robust network

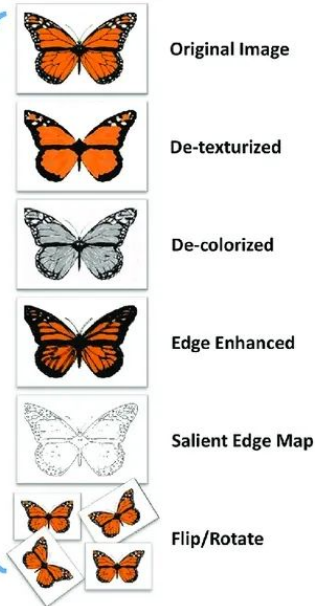
We'll focus on:

- Failures at PMT and UMD module level
- Area over Peak (AoP)
- Saturation
- Failures at SD and UMD station level

We use the latest Phase I SD433-UMD test productions to address these bullets.



Data Augmentation



We should retain the physics!