

# Machine Learning in IceCube

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#### Outline

- Machine learning introduction and general methods
- Decision Trees
- Neural Networks





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# Machine Learning (ML)

- A field of artificial intelligence in which you "teach" a computer to perform a task without having to explicitly program how to do the task
- A lot of the time, this effectively means optimizing a function on a set of data
  - A lot of linear algebra, calculus, and probability
- There are many kinds of machine learning algorithms, but today we will focus on two that show up very often in IceCube work:
  - Decision Trees
  - Neural Networks





#### Tasks

- A machine learning algorithm learns how to perform a specific task. Here are a couple examples that are common in IceCube:
  - **Regression:** Find a function such that  $f(x_i) = y_i$  for all  $x_i$  in the data
    - Energy reconstruction, direction reconstruction
  - **Classification:** Organize  $x_i$  into n classes for all  $x_i$  in the data
    - Neutrino flavor identification, separating atmospheric muons from muon neutrino events



https://dev.to/petercour/machine-learning-classification-vs-regression-1gn



# Types of Learning

- There are many ways to optimize. Here are a couple common examples:
  - **Supervised learning:** Provide the ML algorithm the data  $x_i$  and the truth  $y_i$
  - **Unsupervised learning:** Provide the ML algorithm with the data  $x_i$ , have it learn qualities of the data
- Supervised learning is the most common method used in IceCube, due to our huge amount of simulation

#### Loss Functions

- A loss function is the metric you use to quantify how well your machine learning algorithm is performing a task
- When learning, we minimize the loss
- Different loss function are good for different tasks

Loss	Equation	Property	
L2	$\sum_{i} (f(x_i) - y_i)^2$	Pretty standard	
L1	$\sum_{i}  f(x_i) - y_i $	Better at characterizing outliers than L2	
Huber	$\begin{cases} 0.5(f(x_i) - y_i)^2 \text{ for }  f(x_i) - y_i  < \delta \\ \delta( f(x_i) - y_i  - 0.5\delta) \text{ otherwise} \end{cases}$	Combo of L1 and L2	
Beta	$-\sum_{i} \log(p_{beta}(f_{\alpha}(x_{i}), f_{\beta}(x_{i})))$	Neural network produces a PDF	
Classification Loss Functions			
Loss	Equation		Property
<b>Binary Cross</b> Entropy Loss $N^{-1} \sum_{i} w_i [y_i \log(f(x_i)) + (1 - y_i) \log(1 - f(x_i))]$		For 2 classes	
Cross Entrop Loss	$N^{-1}\sum_{i} -w_{y_{i}}\log\left(\frac{\exp\left(f(x_{i,y_{i}})\right)}{\sum_{C}\exp\left(f(x_{i,C})\right)}\right)$		For >2 classes

**Regression Loss Functions** 



# Training

- "Training" refers to optimizing the algorithm to minimize the loss
  - Optimization method depends on the ML algorithm being trained
- For huge amounts of data, stochastic gradient descent is a very common optimization algorithm
  - General Idea: you can roughly find the correct direction to descend if you use a small batch of your data to compute the gradient
- Batch: A portion of data to use to calculate the gradient for every step
- Epoch: One use of all data you are using to train



https://www.researchgate.net/figure/A-plot-of-the-gradient-descent-algorithm-leftand-the-stochastic-gradient-descent\_fig1\_303257470

# Overfitting

- Generally, we want our ML algorithm to learn things about the population from which our data sample comes from
- Overfitting occurs when the ML algorithm learns features that are specific to the sample of data it was trained on
- To prevent this, you could separate your data into the following sets:
  - **Training set:** The data that you optimize the ML algorithm with
  - Validation set: Used at the end of each epoch to evaluate performance
  - **Test set:** Used to evaluate performance of the ML algorithm once training is completed
- You generally should stop training when the validation loss achieves a minimum



https://www.geeksforgeeks.org/underfitting-and-overfitting-in-machine-learning/





# Regularization

- If the ML algorithm is learning in an undesirable way, you can use regularization to alter the optimization
- Total Loss = Standard Loss + Regularizing Term
- Some examples:
  - **L1/L2 regularization:** Apply the L1/L2 loss to the weights of the model. Good for overdetermined systems to prevent overfitting
  - **Early stopping:** We've seen this before!
  - **Physics informed neural networks:** Add loss terms that enforce specific physics



https://www.nature.com/articles/s42254-021-00314-5



### Hyperparameters

- These are parameters that affect the training and performance of the ML algorithm that are not optimized (learning rate, hidden layer size, tree depth, regularization constant, etc.)
- There is no go-to method for determining hyperparameters
  - Could use a genetic algorithm or cross validation for hyperparameter selection
  - If the training is fast enough / the number of hyperparameters is small enough one can do a grid scan
  - Can hand-tune hyperparameters until the desired performance is achieved



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# **Decision Trees**

- A series of binary decisions to give something a label
- Nodes: Data is sorted based on a binary criteria
  - The variables used in a node and the cuts are what is learned
  - Chosen via information gain
- Leaves: A terminal node representing the class, probability, or value assigned to the input
- Can be used for classification or regression tasks





#### **Decision Trees**

- Boosted Decision Trees: Iteratively train trees on data weighted by error of the linear combination of previous trees
- Random Forests: Produce many uncorrelated decision trees with bootstrapping and then combine their outputs with an ensemble method
- Good for when you want to use high level information (previous reconstructions, for example)
- Very fast to train
- Python supports multiple packages for training decision trees: scikit-learn, XGBoost



https://www.nbi.dk/~petersen/Teaching/ML2022/Week1/ML2022\_DecisionTrees\_ XGboost.pdf



#### **Decision Tree Examples**

#### **Energy Reconstruction**







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### **Neural Networks**

- An artificial brain
- Series of neurons and connections
  - Each neuron uses the output of all connected neurons from a previous layer as input
  - Each connection has an associated weight
  - Linear combination of inputs is passed to a non-linear activation function
- The weights and biases are what are learned



https://www.researchgate.net/figure/A-biological-neuron-in-comparison-to-an-artificial-neuralnetwork-a-human-neuron-b\_fig2\_339446790



### **Activation Functions**

- An activation function is used to produce non-linearity in the neural network
- Tend to be chosen to have an "on/off" type behavior, like a neuron
- For deep neural networks, ReLU is a good first choice to use
  - Does not have saturation / second order gradient issues



https://medium.com/@shrutijadon/survey-on-activation-functions-for-deep-learning-9689331ba092



# **Neural Network Architectures**

- There are many kinds of neural networks, they are usually designed to exploit different features of data
- Multilayer Perceptron
  - The simplest neural network (shown in slide 17)
- Convolutional Neural Networks (CNNs)
  - Good for uniform data with translational symmetry
- Recurrent Neural Networks (RNNs)
  - Good for data with a specific sequence



https://www.researchgate.net/figure/A-valid-convolution-of-a-5x5-image-with-a-3x3-kernel-The-kernel-will-be-applied-to\_fig5\_322505397



# **Neural Network Architectures**

- More advanced architectures:
- Graph Neural Networks (GNNs)
  - Good for data that can be naturally described as a graph (point cloud data, for example)
- Transformers
  - Better version of RNN, CNN





https://theaisummer.com/Graph\_Neural\_Networks/

# Neural Networks

- Good for low level data / more complex data structures (photon hits, voltage waveforms, etc.)
- Can pick up on features of the data that may be missed by traditional reconstruction methods
- There are many packages that support training and using neural networks
  - Tensorflow / Keras
  - PyTorch
  - GraphNet
- For large amounts of data or large models a GPU may be needed for training in a reasonable amount of time





#### Examples in IceCube

Latitude [b]

tude [*b*]

lat

Latitude [b]

Latitude [b]

4 -15° 15°

0 °

0

0

-15 15

0 °

-15° 180





# Questions?

