SCAR AAA 2021

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A technology pathfinder for time domain astronomy in the NIR

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The convergence of many new technologies will soon enable high cadence surveys of the infrared sky for the first time. We describe a pathfinder telescope currently under construction, which will demonstrate a technology for imaging over a field of view two orders of magnitude greater than previously achieved in the thermal infrared. The novel optical design not only delivers diffraction limited image quality over large fields, but its double meniscus corrector serves as the entrance window to a fully cryogenic optical path that assures low thermal background in spite of the large field of view. We describe the window manufacturing and support strategies which allow scaling to apertures larger than a meter, and the various methods to prevent ice precipitation. A new, cheaper, growth process for large format infrared detectors is showing promise of making a 600 megapixel NIR focal plane feasible. High speed direct drive telescope mounts, now commercially available, will be upgraded to provide the vibration isolation necessary to take advantage of the exquisite seeing.

To catch transients in NIR

49 deg² every1000s with SNR>5 for magnitude 23.3 at 2.3< λ <2.55 μ m



200 times wider field



Smaller pixels & darker sky



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Optics to match good seeing

Scan whole night sky in less than a "day"...



Cheaper large format IR detectors:

✓ good QE



- NSF-ATI grant has funded development at Raytheon of MBE-on-silicon process for making large NIR detectors 4x cheaper. (PI: Don Figer)
- ~80% QE in K_dark passband
- Peak of QE curve can be tuned for peak in middle of passband.
- 27e- read noise prior to multiple sampling.



Tight noise distribution

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\\falcon\disk1\VIRGO-V23\cold1\JMCE\darkcurrent\darkcurrent.20Aug21_1\results\q4\noref\slopeplots\region2\histograms\dark_70K_893.127_utr_50_

Low dark current.

Hybridize to SC 4Kx6K ROIC



8" wafer

- 4K*6K Readout IC by Sensor Creations Inc
 - Funded by NASA SBIR grant (via WFIRST)
 - Currently under test
- Cryoscope will deploy 6x4 mosaic
 - 24K*24K pixels
 - Instantaneous Field of View = 49 deg²
 - Beam obstruction by 6x4 mosaic is only 8%
- 10 μ m pixels \rightarrow 1.031 arcsec/pixel
 - telescope focal length = 2.0 m
 - 1.2m aperture
 - f/1.66
 - \rightarrow FWHM at diffraction limit = 4.2 µm

Air glow lines



South Pole - atmospheric transmission



Figure 3. Curves of <u>South Pole</u> atmospheric transmission taken from Hidas et al. (2000), with varying assumptions about the atmospheric water content. The three lines are for precipitable water columns of 84, 164, and 328 μ m.

Black body power density



Reduced emission from telescope helps but very widefield designs have higher emissivity thus need to be as cold as sky.

Fucik Telescope



- Diffraction limited
 - Excellent image quality even at f1.2 and 100 sq.deg.
- All fused silica corrector → scalable to large aperture.
- Arizona Mirror labs are developing glass slumping to fabricate large menisci economically.
 - Similar lenses are used in prime focus correctors.
- Shorter than a Schmidt → smaller primary for given aperture and FoV

Negligible aberrations !

Pathfinder

- 4.06 deg x 4.06 deg field of view
- 260mm aperture at f/2

Spots are much smaller than 18 μm pixel RMS radius < 1.2 μm



Temperature profiles Dome C

PNRA radiosonde data

200 -80.00 180 -72.00 -68.00 160 -64.00 Height above ground level (m) -60.00 140 -56.00 -52.00 120 -48.00 100 -44.00 40.00 80 -36.00 -32.00 60 -28.00 40 -24.00 -20.00 20 Temperature 0 (degrees, C) 50 100 150 200 250 300 350 Day Number, 2006 7-77-

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Why a cryogenic telescope ?

Usual measures to block rays from warm telescope limit FoV.

...but without re-imaging optics and cold Lyot stop, telescope emissivity is closer to 1 than the \sim 2% emissivity of optics.

- At top of inversion layer (25-30m above ice), T= ~230 K ← not cold enough
- We really want telescope temperature < sky temperature < 200 K.
- 2nd corrector element of Fucik optical design can serve as window, so *full* optical path can be cryogenically cooled.



Detector test system assembled



- This is a lab test dewar, not Cryoscope.
- Allows early testing of components to be used in Cryoscope: controller, wiring and detector.
- Readout waveforms in development now.
- Tests Cryoscope detector control software.



Window Stress Analysis

Tangential support by silicone gasket keeps glass in compression







Figure 37: 8.7mm tall x 1mm thick Gasket Window Minimum Principal Stress at -75C



Figure 35: 8.7mm tall x 1mm thick Gasket centered on the window edg



8.7mm tall x 1mm thick Gasket Equivalent Stress at -75C

>80% of radiation from window is returned to window (non-sequential ray tracing)

	Total Input	Total Missed*		Total Detector**	Total Exiting Window and Reflected Off Baffles ^{***}	Baffle 1 ^{**}	Baffle 2**	Baffle 3**	Baffle 4**		Baffle 6**
Cone Baffles	1.0000 W	W	0.3990 W (100%)	0.0009 W (0.2%)	0.1758 W (44.1%)	0.1276 W (32.0%)	0.0246 W (6.2%)	0.0132 W (3.3%)	0.0072 W (1.8%)	0.0020 W (0.5%)	0.0013 W (0.3%)
Elliptical Baffles	1.0000 W	W	0.3990 W (100%)	0.0005 W (0.1%)	0.1990 W (49.9%)						
Mixed Baffles E(2,3,4);C(1,5,6)	1.0000 W	W	0.3990 W (100%)	0.0005 W (0.1%)	0.1569 W (39.3%)	0.1270 W (31.8%)		0.0267 W (6.7%)		0.0020 W (0.5%)	0.0012 W (0.3%)

Since making the above table, this number has been raised to 80% with addition of baffle here



Further improvement is anticipated by filling this gap

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Neglible out-of-field light scatters onto detector (non-sequential ray tracing)

Config		Total Missed*	Total Enters Window	Total Detector**	Total Exiting Window and Reflected Off Baffles**	Baffle 1**	Baffle 2**		Baffle 4**		Baffle 6**
Cone Baffles	1.0000 W	0.3076 W	0.4499 W (100%)	0.0363 W (8.1%)	0.2361 W (52.5%)	0.0099 W (2.2%)	0.0170 W (3.8%)	0.0284W (6.3%)	0.0487 W (10.8%)	0.0710 W (15.8%)	0.0584 W (13.0%)
Elliptical Baffles	1.0000 W	0.3076 W	0.4499 W (100%)	0.0017 W (0.4%)	0.4024 W (89.4%)						
Mixed Baffles E(2,3,4);C(1,5,6)	1.0000 W	0.3076 W	0.4499 W (100%)	0.0017 W (0.4%)	0.3764 W (83.7%)	0.0086 W (1.9%)				0.0749 W (16.6%)	0.0565 W (12.6%)



Flux Entering Window

150.0



*Light that does not enter corrector lens 1.

** Percent calculated from total flux entering the window.



Image stabilizing telescope mount

Must isolate telescope from vibration of tower:

- Use low friction bearings rated for low temperature.
- Direct drive torque motors, so coupling is magnetic only.
- Active feedback from bright stars provided by sensor using sub-array readout.
- Use optical encoders only during slews.





Torque motor in telescope mounts by planewave.com

Custom bearings and servo are under discussion with Planewave.

Masters Student in Robotics at JHU is planning to test cryogenic bearing and develop image stabilizing servo

Conclusion

Cryoscope will validate:

- ✓ New optical design (diffraction limited over wide field)
- ✓ Cryogenic optical path
- \checkmark Low sky background (when telescope emission is suppressed).
- ✓ Window temperature control (narcissus baffle performance)







	0.03	0.27	0.11
%	0.42	100.00	0.30
	-0.03	0.31	-0.04

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Background: sky + telescope

- Low sky temperature pushes rising edge of blackbody curve beyond 2.55 µm.
- Reduced emission from telescope helps but very widefield designs have higher emissivity thus need to be colder.



We will eliminate this

Figure 6. Measured infrared sky brightness from the South Pole taken from Ashley et al. (1996). Thermal self-emission from the instrumentation, as well as simple emissivity models assuming a cold, dry dome-A atmosphere are also presented (further details in the text). Note that Figure 1 of Phillips et al. (1999) provides additional observations of the sky from the South Pole, however these data appear to have an error in their wavelength calibration, and so are not used here.

Dome C seeing

- These numbers are for 30m above ice.
- 75% of time, seeing is better than Cryoscope diffraction limit (0.4").
- Full potential when mounted on tower.
- Pathfinder (0.26m aperture) is small enough to be mounted on existing building.



Figure 3 Histograms and cumulative distributions of the atmospheric seeing and the isoplanatic angle. **a**, Histogram of Dome C seeing above 30 m from MASS combined with SODAR, and cumulative distributions of seeing at Dome C (DC), Mauna Kea (MK) (derived from ref. 4), and Cerro Paranal (CP)². **b**, Histogram of Dome C isoplanatic angle derived from the MASS instrument, and the cumulative distribution of isoplanatic angle from Dome C and Cerro Paranal².

Optical tolerances are quite loose

Parameter	Value [mm]	Tolerance	Change to RMS WFE [nm]
L1 Center Thickness (CT)	12.5	±0.10 mm	0.00
(L1:S1) Radius of Curvature (RoC)	600.0 CC	±0.1%	2.34
(L1:S2) Radius of Curvature (RoC)	670.5 CX	±0.1%	1.52
(L1:S1) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.38
(L1:S2) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.44
L1 Wedge Angle	0.00	±0.017° (±1')	9.81
(L1:S2) Aspheric Surface Decenter	0.00	±0.05 mm	0.76
(L1:S1) Surface Roughness	0.00	< 2.5 nm rms	na
(L1:S2) Surface Roughness	0.00	< 2.5 nm rms	na
L2 Center Thickness (CT)	12.5	±0.10 mm	0.00
(L2:S1) Radius of Curvature (RoC)	600.0 CX	±0.1%	0.00
(L2:S2) Radius of Curvature (RoC)	670.5 CC	±0.1%	0.00
(L2:S1) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.44
(L2:S2) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.38
L2 Wedge Angle	0.00	±0.017° (±1')	13.35
(L2:S2) Aspheric Surface Decenter	0.00	±0.05 mm	1.39
(L2:S1) Surface Roughness	0.00	< 2.5 nm rms	na
(L2:S2) Surface Roughness	0.00	< 2.5 nm rms	na
M1 Radius of Curvature (RoC)		±0.1%	
M1 Surface Figure Errors (SFE)	2	<75 nm rms	
M1 Surface Roughness	0.00	< 2.5 nm rms	na
L3 Center Thickness (CT)	10.0	±0.10 mm	0.26
(L3:S1) Radius of Curvature (RoC)	237.3 CX	±0.1%	0.06
(L3:S2) Radius of Curvature (RoC)	595.0 CC	±0.1%	0.00
(L3:S1) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.13
(L3:S2) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.06
L3 Wedge Angle	0.00	±0.017° (±1')	1.71
(L3:S2) Aspheric Surface Decenter	0.00	±0.05 mm	0.63
(L3:S1) Surface Roughness	0.00	< 2.5 nm rms	na
(L3:S2) Surface Roughness	0.00	< 2.5 nm rms	na
L4 Center Thickness (CT)	10.0	±0.10 mm	1.71
(L4:S1) Radius of Curvature (RoC)	241.7 CC	±0.1%	0.06
(L4:S2) Radius of Curvature (RoC)	187.7 CX	±0.1%	0.06
(L4:S1) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.00
(L4:S2) Surface Figure Errors (SFE)	0.00	<75 nm rms	0.00
L4 Wedge Angle	0.00	±0.017° (±1')	0.76
(L4:S2) Aspheric Surface Decenter	0.00	±0.05 mm	0.38
(L4:S1) Surface Roughness	0.00	< 2.5 nm rms	na
(L4:S2) Surface Roughness	0.00	< 2.5 nm rms	na

Element Specifications 🔿	Mounting, alignment and	flexure tolerar	nces	
Parameter	Value [mm]	Tolerance	Change to RMS WFE [nm]	
L1 Piston (Z)	0.00	±0.200 mm	0.01	
L1 Decenter (X,Y)	0.00	±0.200 mm	2.09	
L1 Tilt (TX, TY)	0.00	±0.150°	8.80	
L2 Piston (Z)	0.00	±0.200 mm	na	
L2 Decenter (X,Y)	0.00	±0.200 mm	0.78	
L2 Tilt (TX, TY)	0.00	±0.150°	13.92	
M1 Piston (Z)	na	±0.100 mm	na	
M1 Decenter (X,Y)	0.00	±0.200 mm	0.00	
M1 Tilt (TX, TY)	na	±0.100°	na	
L3 Piston (Z)	0.00	±0.200 mm	na	
L3 Decenter (X,Y)	0.00	±0.200 mm	3.16	
L3 Tilt (TX, TY)	0.00	±0.150°	12.91	
L4 Piston (Z)	0.00	±0.200 mm	1.14	
L4 Decenter (X,Y)	0.00	±0.200 mm	0.09	
L4 Tilt (TX, TY)	0.00	±0.150°	3.65	
Detector (Z)	0.00	±0.200 mm	1.46	
Detector (X,Y)	na	±0.180 mm	na	
Detector (TX,TY)	0.00	±0.02°	3.23	
TOTAL RMS WFE				
EXPECTED STREHL RATIO (> 80%)				
DESIGN RMS WFE	3.94			

