



*In-situ calibration and anechoic chamber measurement
for radio antenna development*

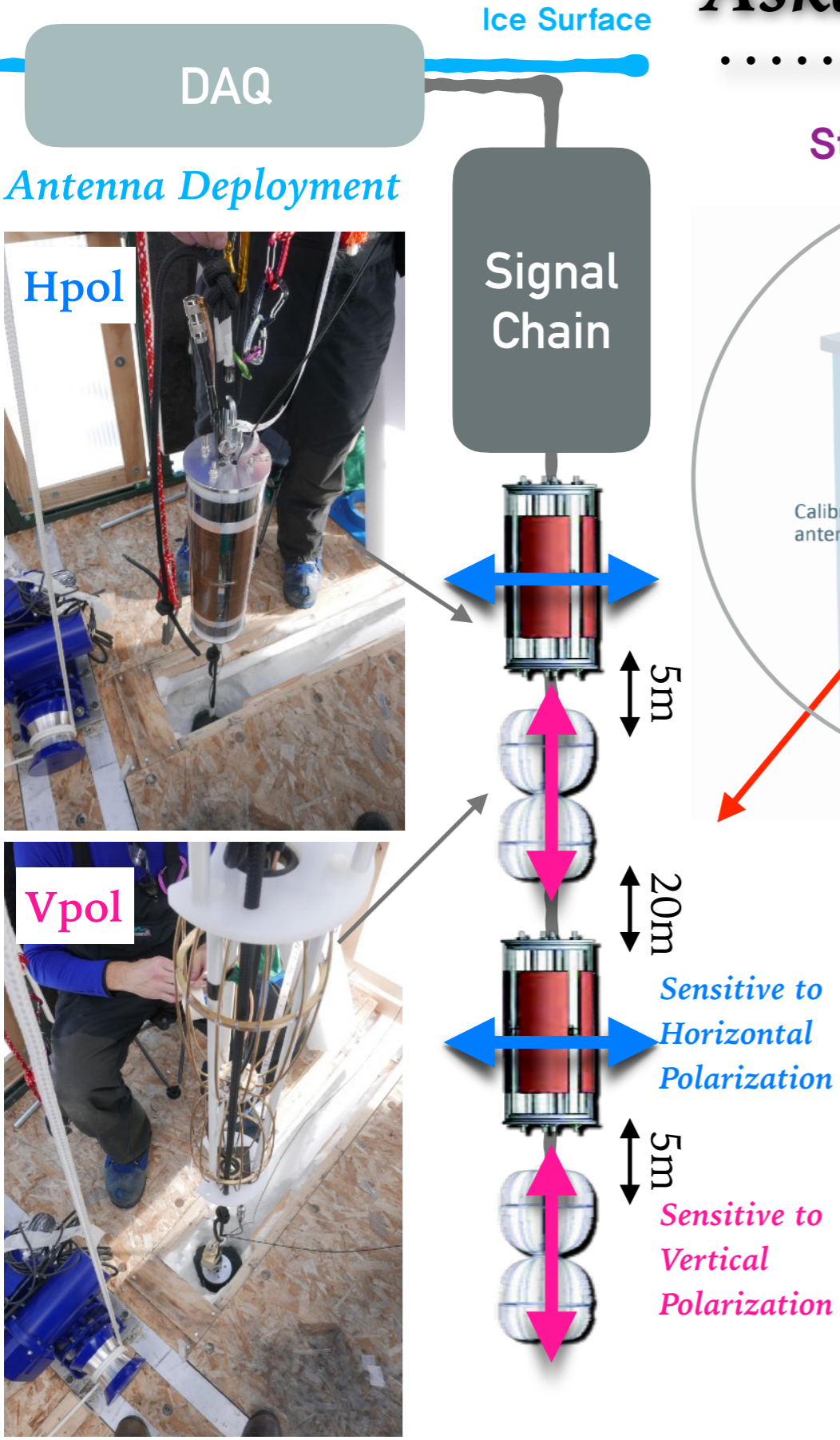
Myoungchul Kim

Outline

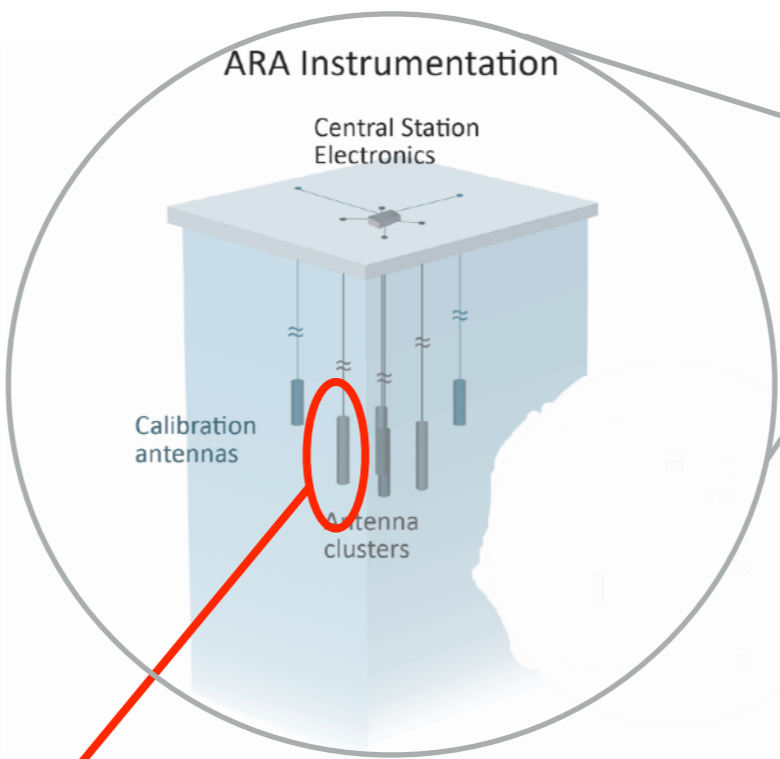
- Brief introduction of ARA antenna
- Strategy for developing antenna model (lesson learned)
 - In-air to in-ice transition strategy
 - Calibration in-air (Anechoic chamber) and in-ice (in-situ calibration)
 - Transition by simulation (XFDTD)
 - Empirical antenna model based on in-situ
- Slim antenna study
 - Development and optimization
 - Measurement at the South pole and Anechoic chamber
- Summary / Discussion

Askaryan Radio Array (ARA)

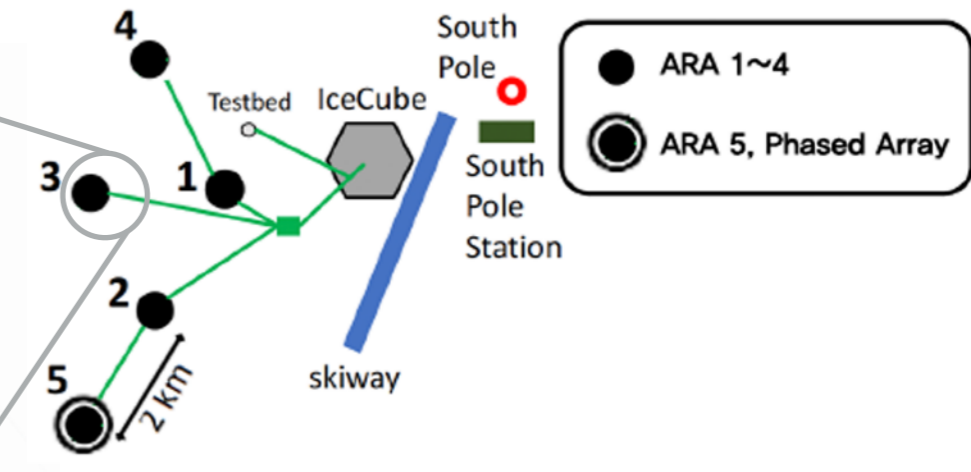
Detector Schematic



Station Schematic



ARA Five-Station

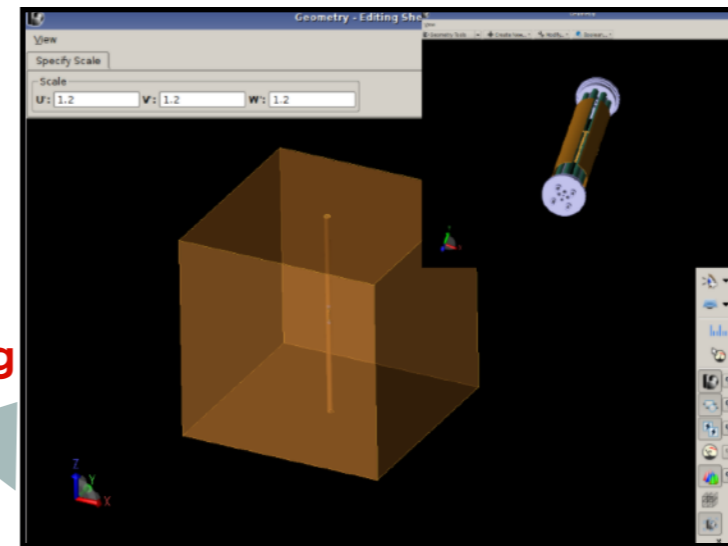


- ▶ Building radio detector in the Antarctic ice, a large volume of radio transparent medium with a long radio-wave attenuation length of ~ 1 km, would be cost-effective and the best option to observe UHE neutrinos.
- ▶ **Five independent ARA stations** are constructed 200 m below the ice surface with 2 km spacing.
- ▶ In each station, **16 RF antennas** + 4 calibration pulsers equipped with 6 downhole strings.
- ▶ **Vertically polarized (Vpol, Z-axis)** and **horizontally polarized (Hpol, XY-plane)** antennas are deployed to measure the polarization of the electric field.
- ▶ Signal chain corresponds to LNA, RFoF, and Amplifier

Strategy for developing antenna model

- ▶ The goal is to have an accurate antenna model for Gen2-Radio simulation.
- ▶ Developing an antenna model based on in-situ calibration is the optimal approach.
 - ▶ It can reflect the real environment, but difficult to scan the full angular gain pattern when detector is placed in the ice.
- ▶ Constructing in-air to in-ice transition strategy for covering the gap.
 1. **Measurement in anechoic chamber** (in-air) -> easily perform detail scan.
 2. **Antenna simulation** (XFDTD) -> bridge for in-air to in-ice transition (It was challenging).
 3. Verifying results with **In-situ calibration** (in-ice).
- ▶ Eventually, an **empirical antenna model** was developed based on **in-situ data**.

Antenna simulation
(In-air to In-ice transition)



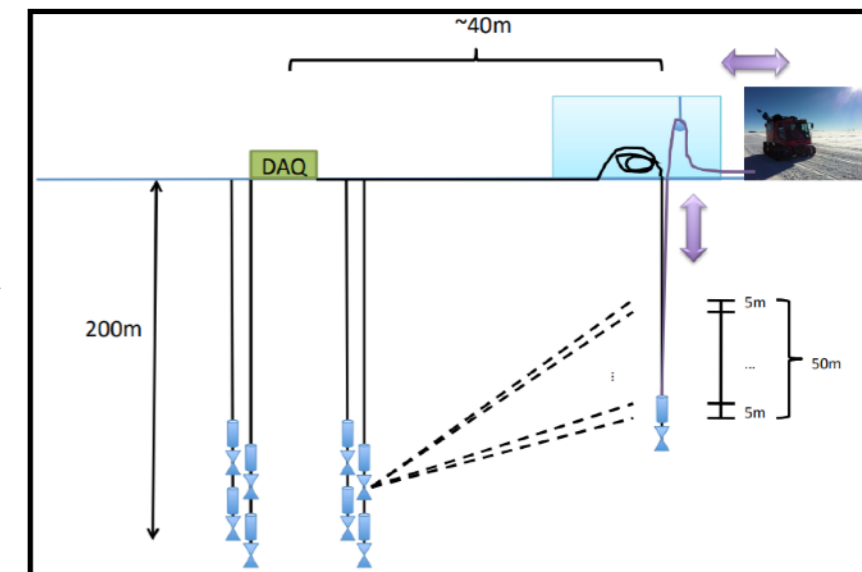
modeling

Verification

Antenna gain in-air
(Anechoic chamber measurement)



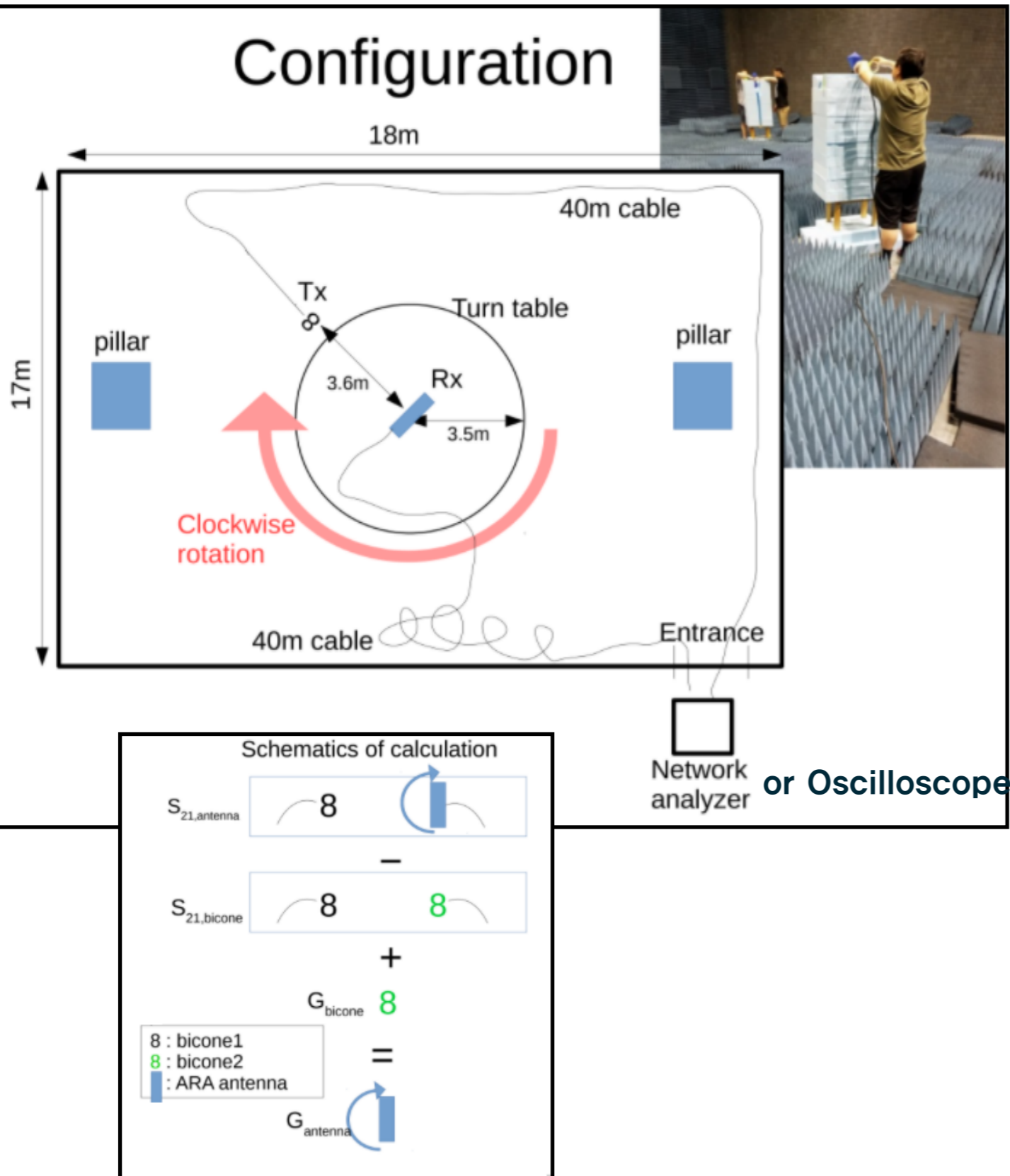
Antenna gain in-ice
(In-situ calibration)



comparison

Anechoic chamber measurement

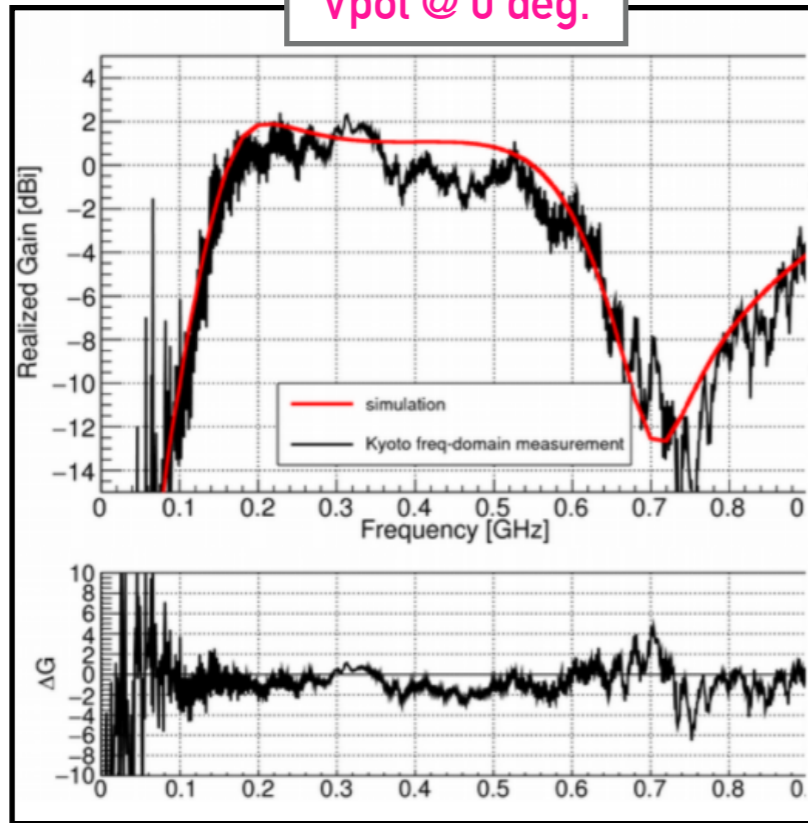
Configuration



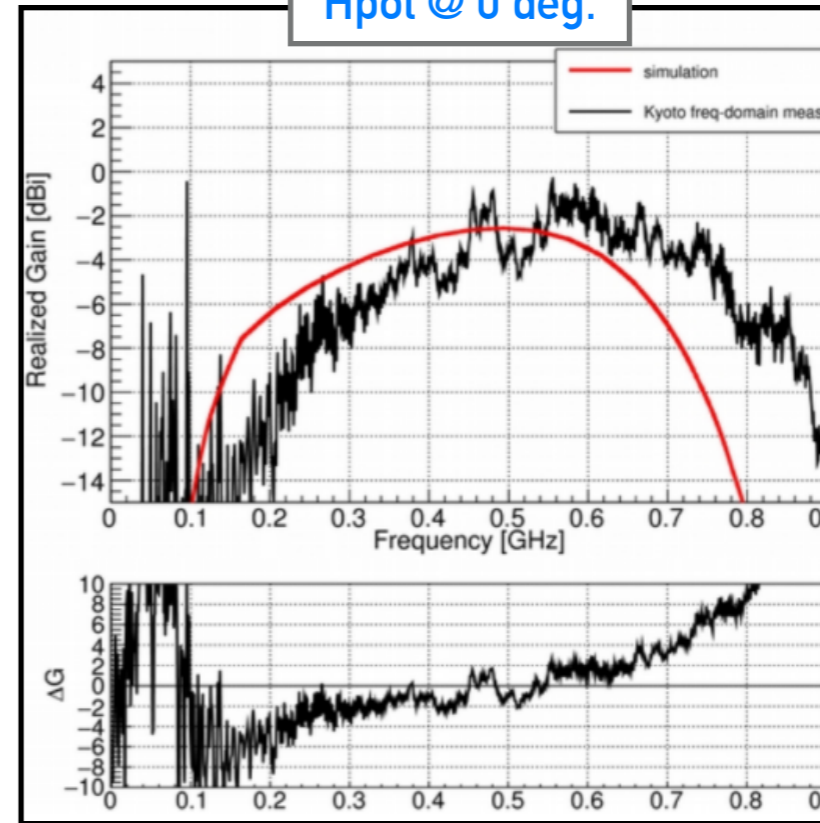
- The goal is measuring ARA antenna gain in air and verifying the simulation results.
- The measurement was performed in a large anechoic chamber at Kyoto (18 m x 17 m x 7.3 m) which is big enough to confirm the far-field effect.
- We measured,
 1. Vpol and Hpol antenna
 2. Original and slim antenna (later slide)
 3. 10 deg interval (for original antenna)
 4. Network analyzer : F-domain
 5. Oscilloscope : T-domain
- Bicone antenna was used for transmitting the signal and later it was removed from gain calculation.

Anechoic chamber measurement

Vpol @ 0 deg.



Hpol @ 0 deg.



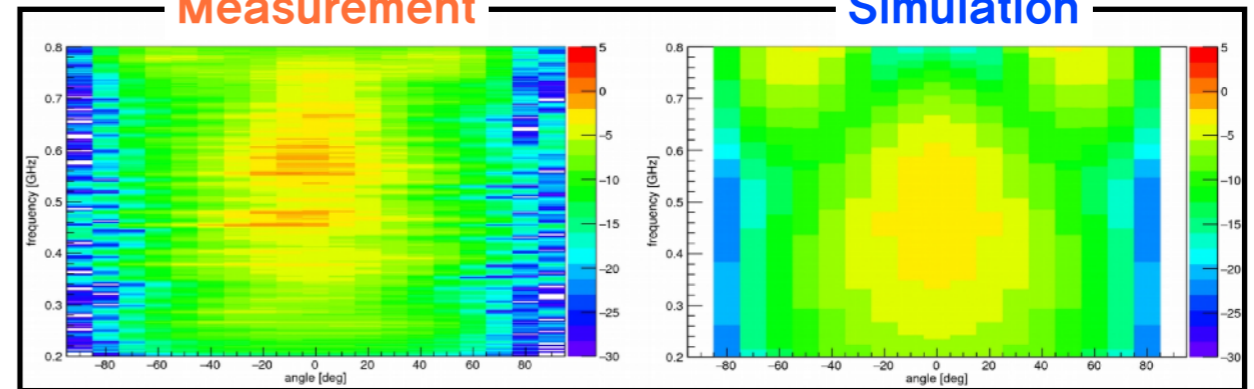
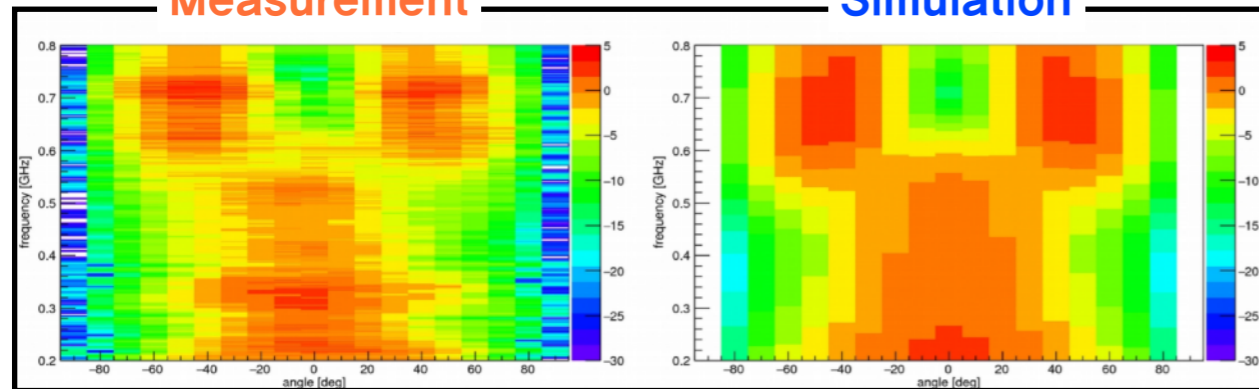
Measurement

Simulation

Angular gain map

Measurement

Simulation

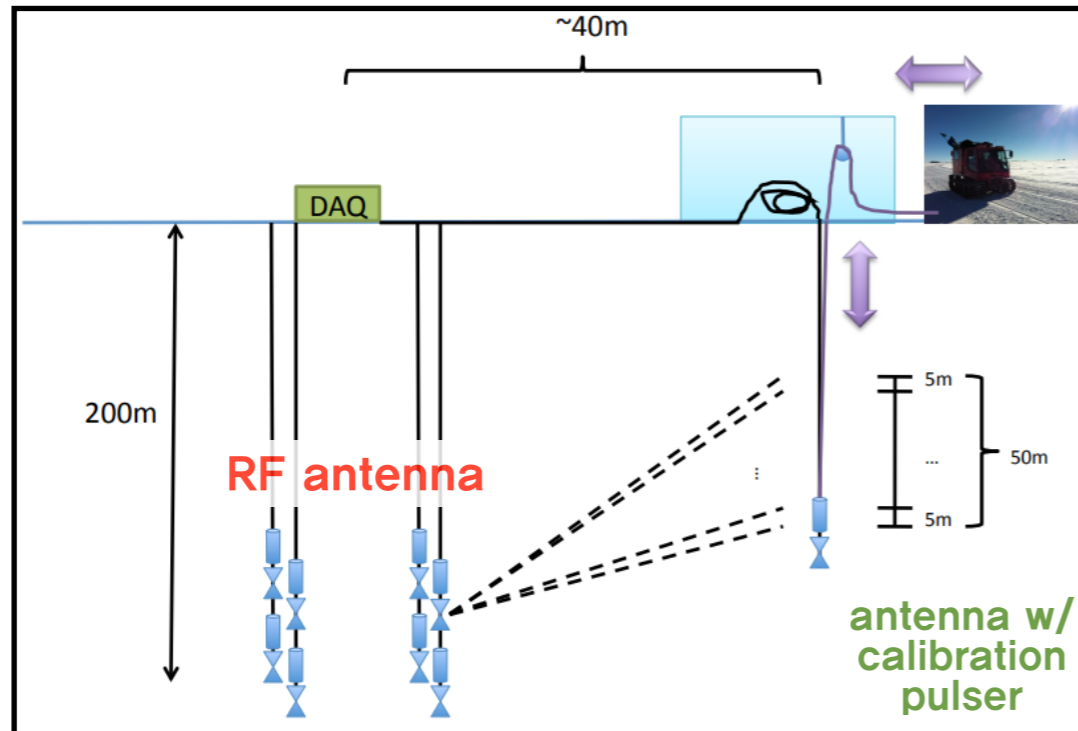


- **Vpol**: The gain frequency tendency is roughly the same as simulation. $\Delta G(\text{measurement} - \text{simulation})$: -0.79 ± 1.85 dB
- **Hpol**: Unknown ferrite property caused **mismatch** with simulation (frequency shift). The simulation cannot describe the data well. ΔG : -0.48 ± 3.65 dB

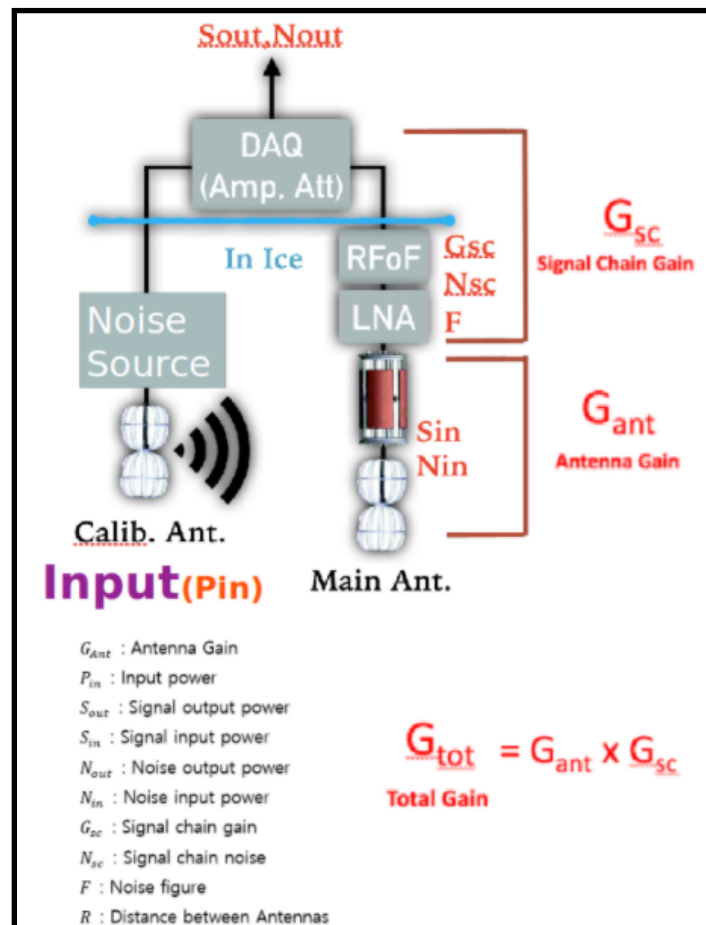
$$\sigma_{\Delta G} = \sqrt{\frac{\sum_{\text{angle, freq}} (\Delta G(\theta, f) - \mu_{\Delta G})^2}{n}}$$

In-situ calibration

Pulser lift measurement



- The crucial data for developing/verifying the antenna model. But it has **limitations** for measurement.
- Pulser lifting measurement (by Ming-Yuan Lu, Madison): lifting calibration string that contains transmitter antennas and pulser module.
- It was performed for measuring the zenith-dependent antenna pattern in ice.
- By gradually lifting pulser up to 50 m, ~60 degree amount of zenith angle data was obtained.
- Antenna gain and signal chain gain were calculated based on the Friis equation method (by Thomas Meures, Madison) by reflecting the real ice-hole/temperature environments.

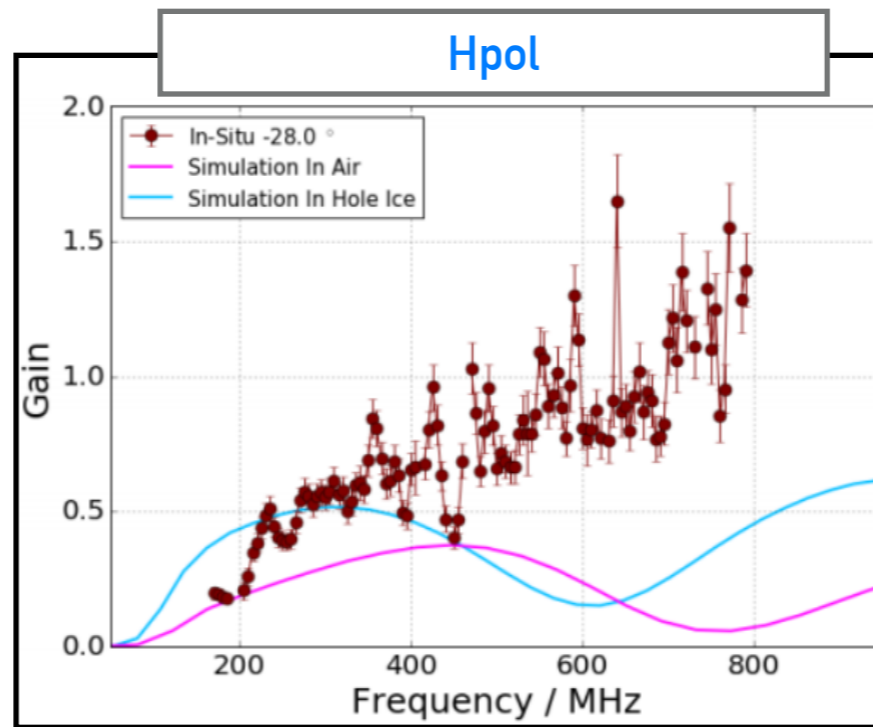
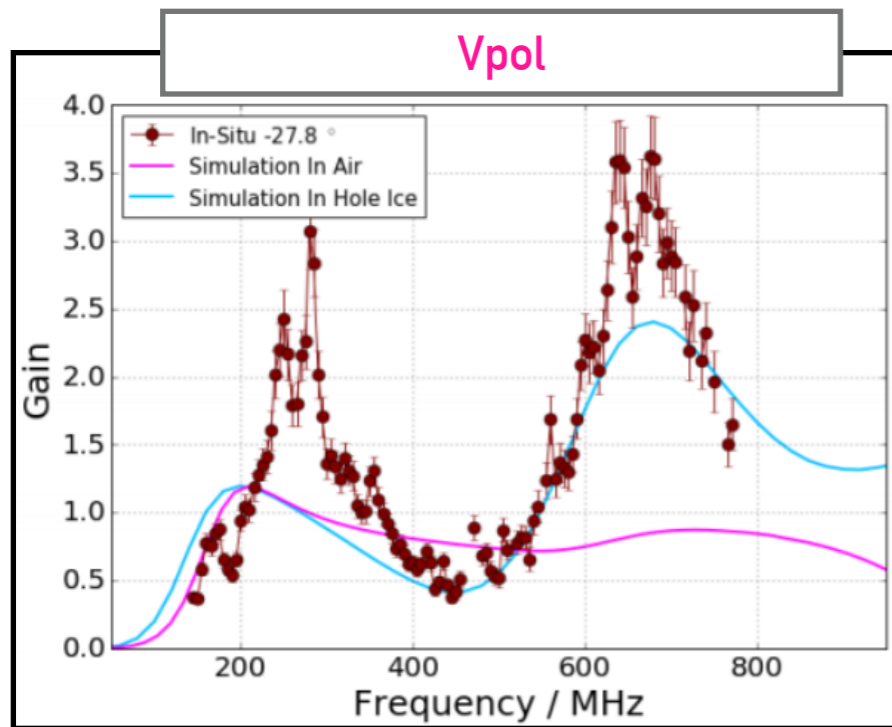


$$\text{Antenna Eq. (Friis Eq.) } G_{Ant} = \sqrt{\frac{1}{P_{in}} \left(\frac{4\pi R}{\lambda}\right)^2 \frac{S_{out}}{N_{out}} (N_{in} + N_{sc})}$$

$$\text{Signal Chain Eq. } G_{sc} = \frac{N_{out}}{(N_{in} + N_{sc})}$$

In-situ calibration

Linear scale

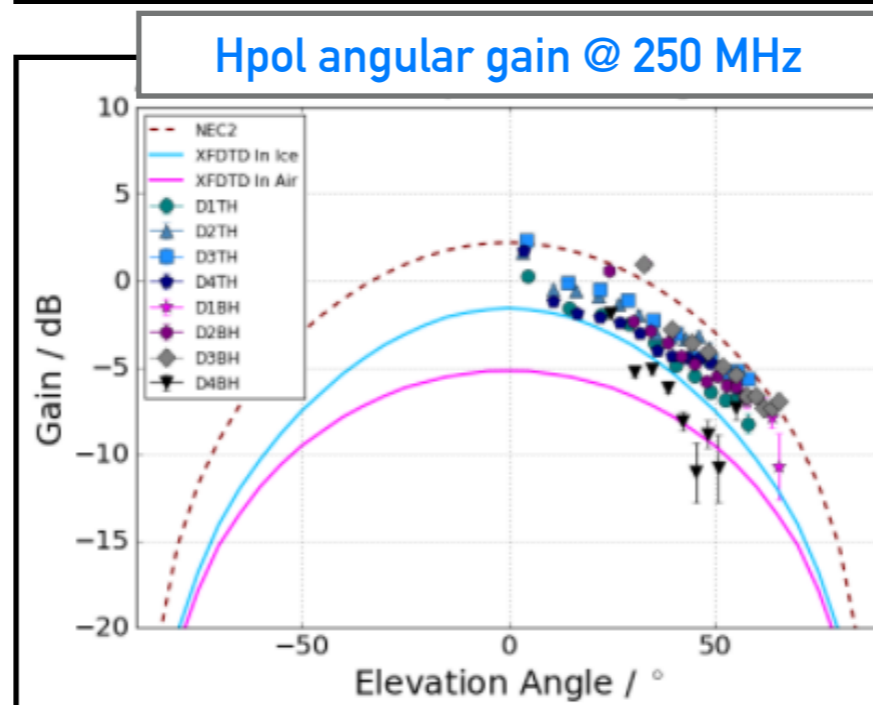
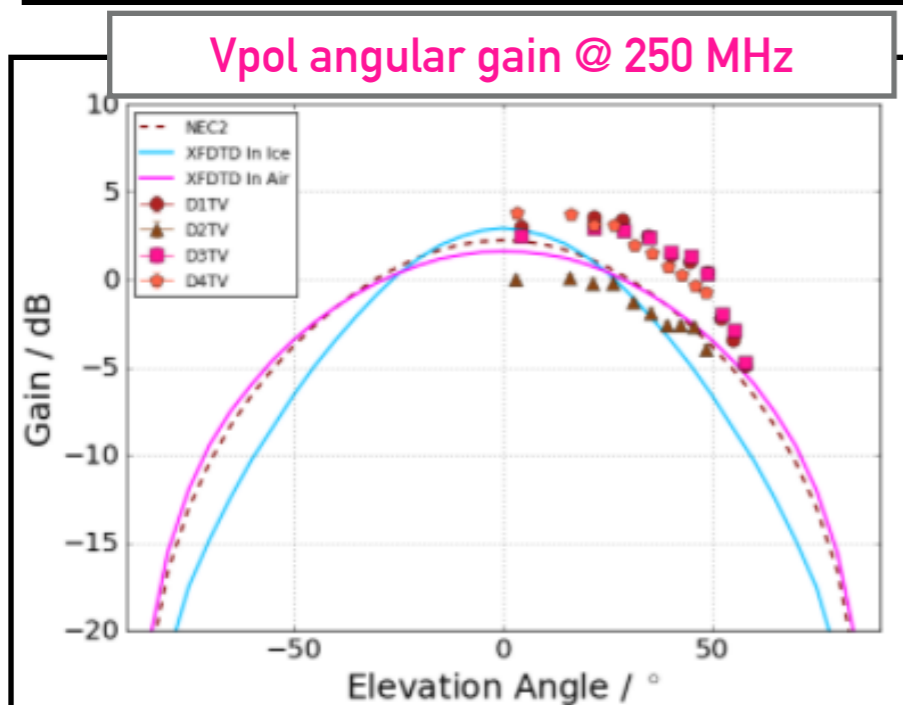


► **Vpol**: The results show acceptable agreement to the in-ice XFDTD simulation prediction.

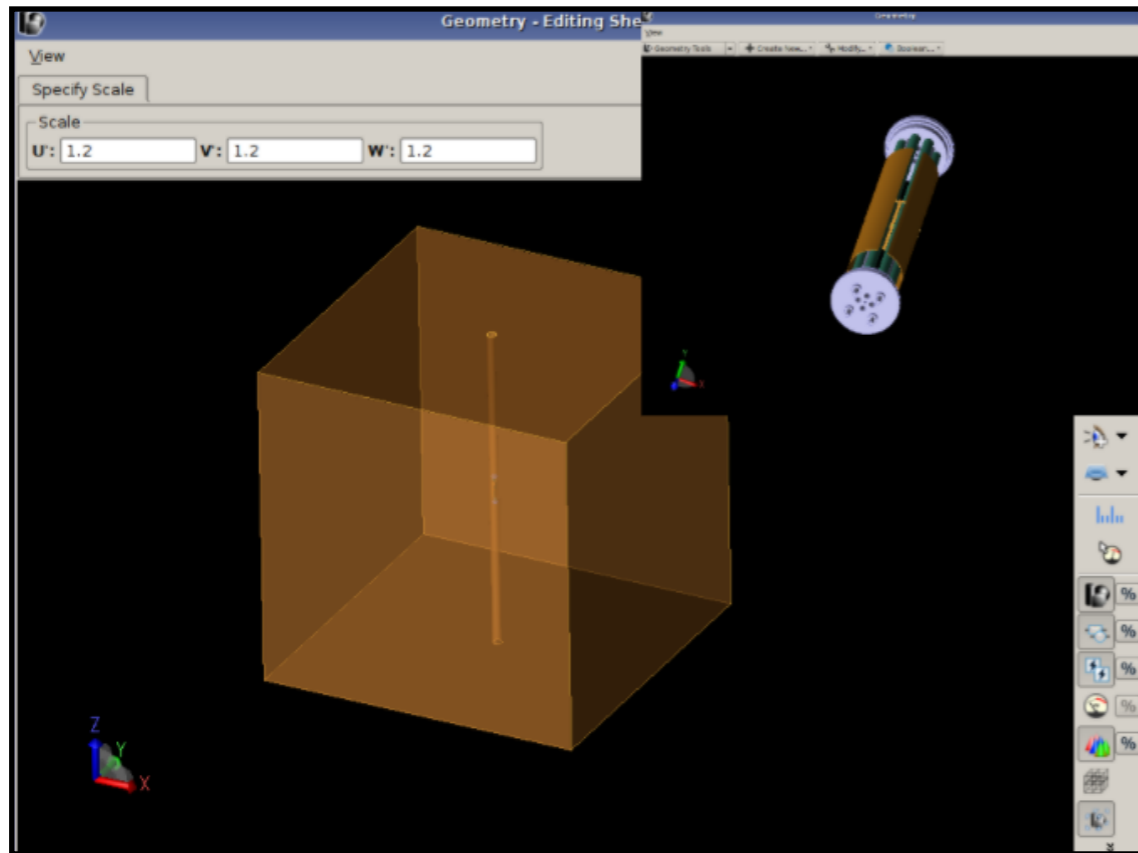
► The in-ice XFDTD simulation: simulating antenna inside of cube of ice block with dry hole.

► **Hpol**: The results generally disagree with simulation in high frequency region.

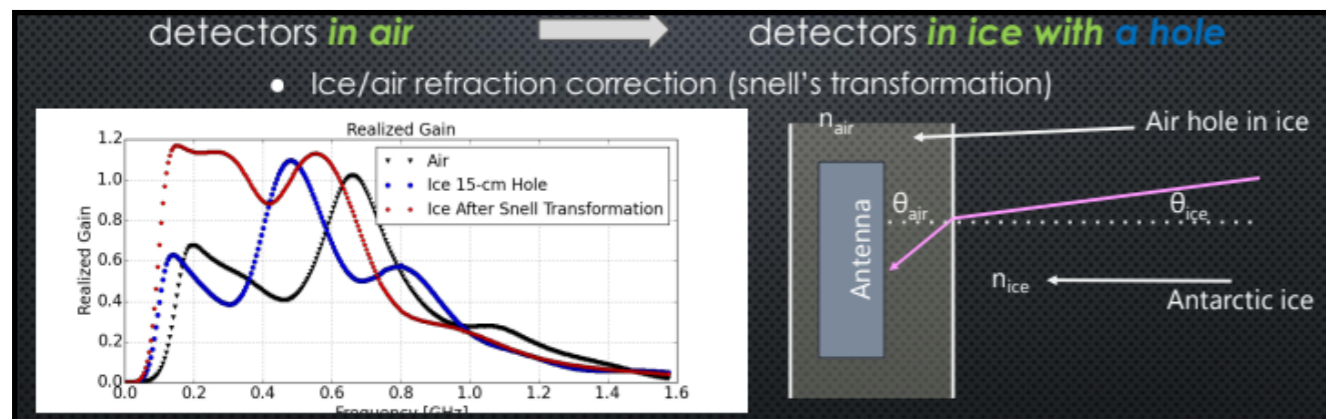
► The simulation cannot describe the data well.



Transition by simulation (XFDTD)

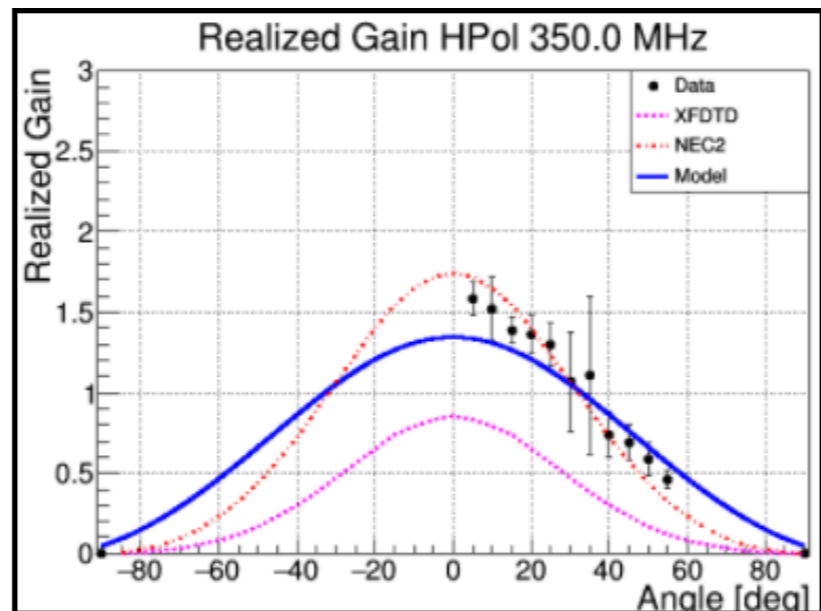
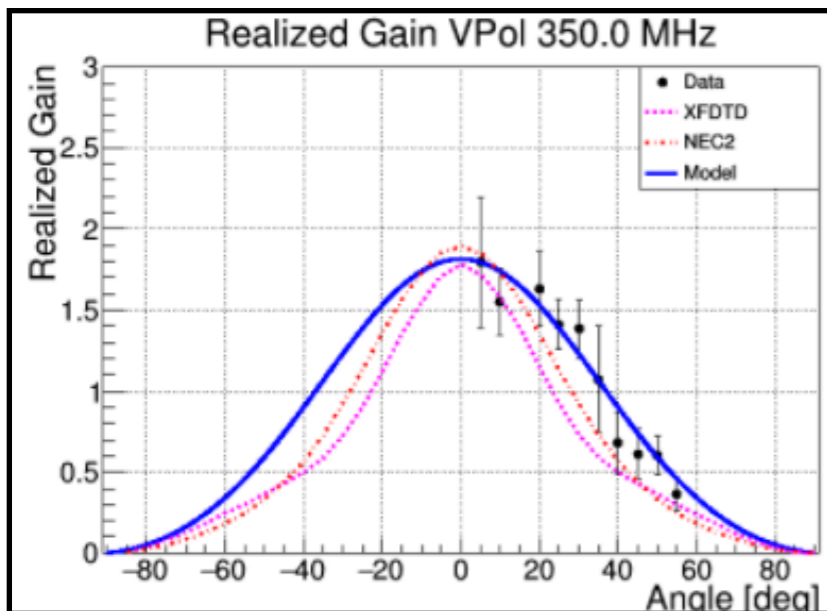
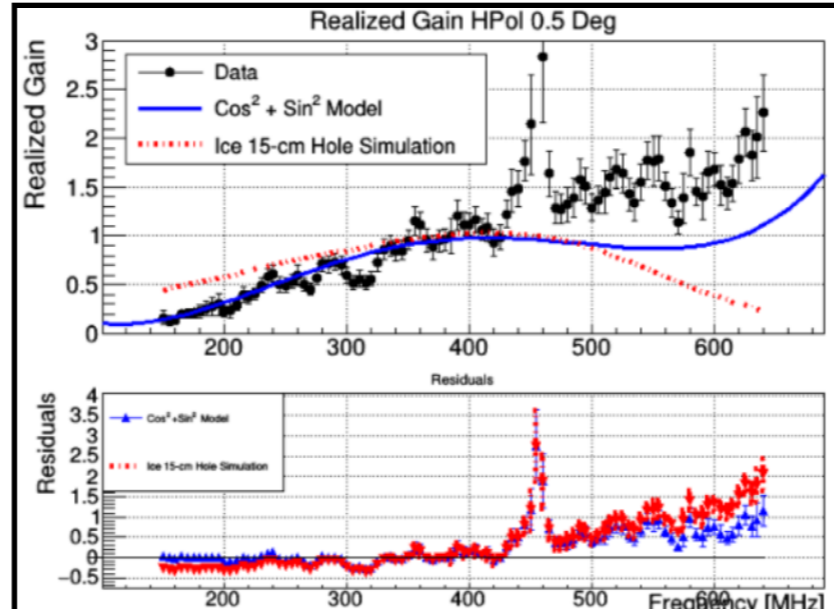
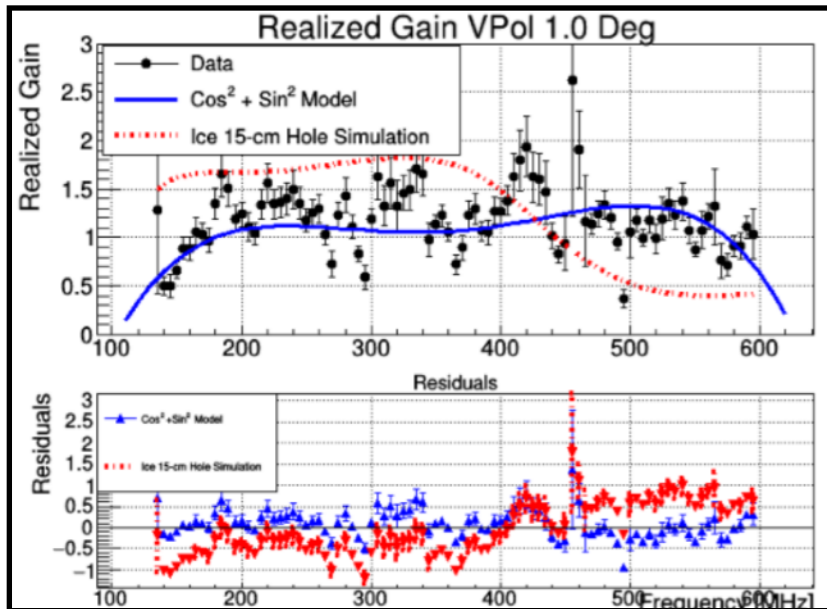


- ▶ XFDTD simulation was used for in-air to in-ice transition.
- ▶ The in-ice simulation was made by placing an antenna inside a cube of ice including a simulated dry hole.
- ▶ **The transition was challenging!**
 1. **Vpol**: It agrees better in the air but difficult to reproduce in ice measurements.
 2. **Hpol**: Lack of ferrite information cause a general mismatch in both air and ice results.
- ▶ Couldn't establish transition by XFDTD simulation.
- ▶ Need to make an **empirical antenna model** based on in-situ data.



Both **hole** and **snell's** method were failed to reproduce the in-situ data

Empirical antenna model



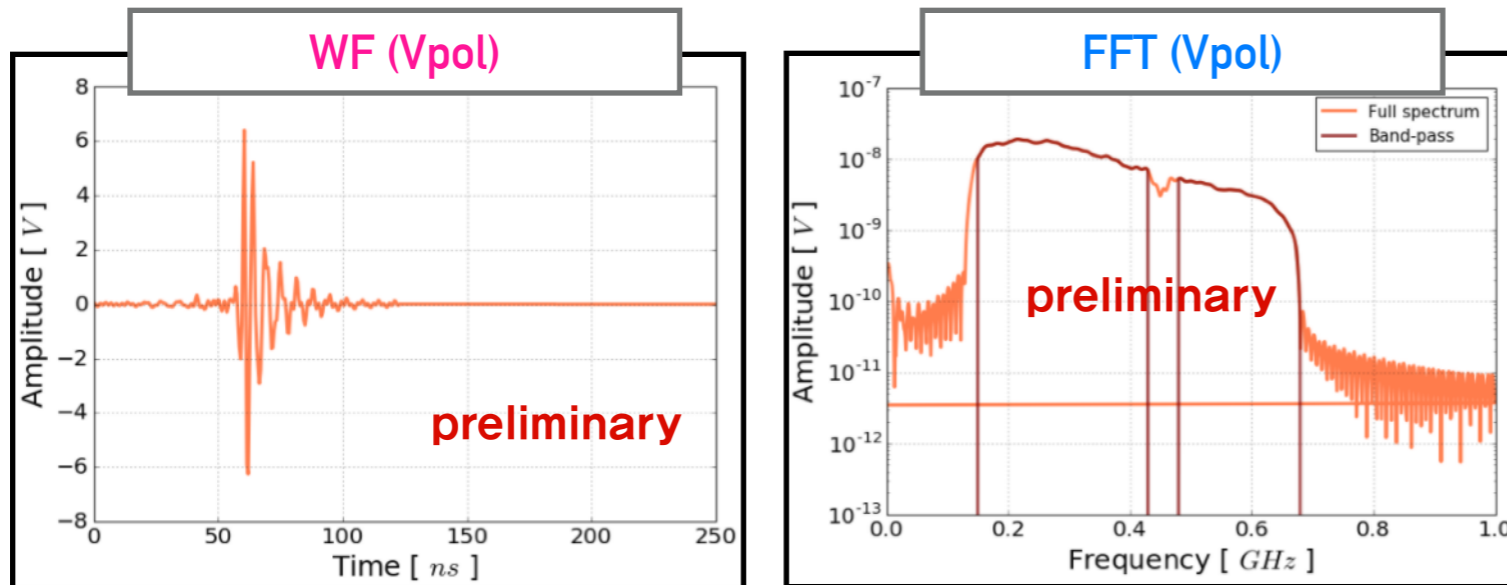
- ▶ Need to develop a model that describes both polarization and estimates different angles in ice.
- ▶ In-situ calibration data was used.
 - ▶ pros: reflects the real ice-hole/temperature environments.
 - ▶ cons: only limited angular coverage.
- ▶ The model-based from Legendre polynomials which should describe any angular patterns.
 - ▶ $A(f) \cdot \cos^2(B(f)\theta) + C(f) \cdot \sin^2(D(f)\theta)$
- ▶ Fit n-order polynomials to parameters to describe their behavior with frequency.
- ▶ Error is calculated by taking the difference between model and data error values (statistical uncertainty + 20% systematics).

| | VPol | HPol |
|---|------------------|------------------|
| Data (Average) | 1.010 +/- 0.008 | 1.006 +/- 0.008 |
| Model (rel Average / Systematics / reduced χ^2) | -16% / 38% / 1.8 | -13% / 32% / 3.9 |
| XFDTD (rel Average / Systematics / reduce χ^2) | -30% / 43% / 4.9 | -57% / 64% / 17 |

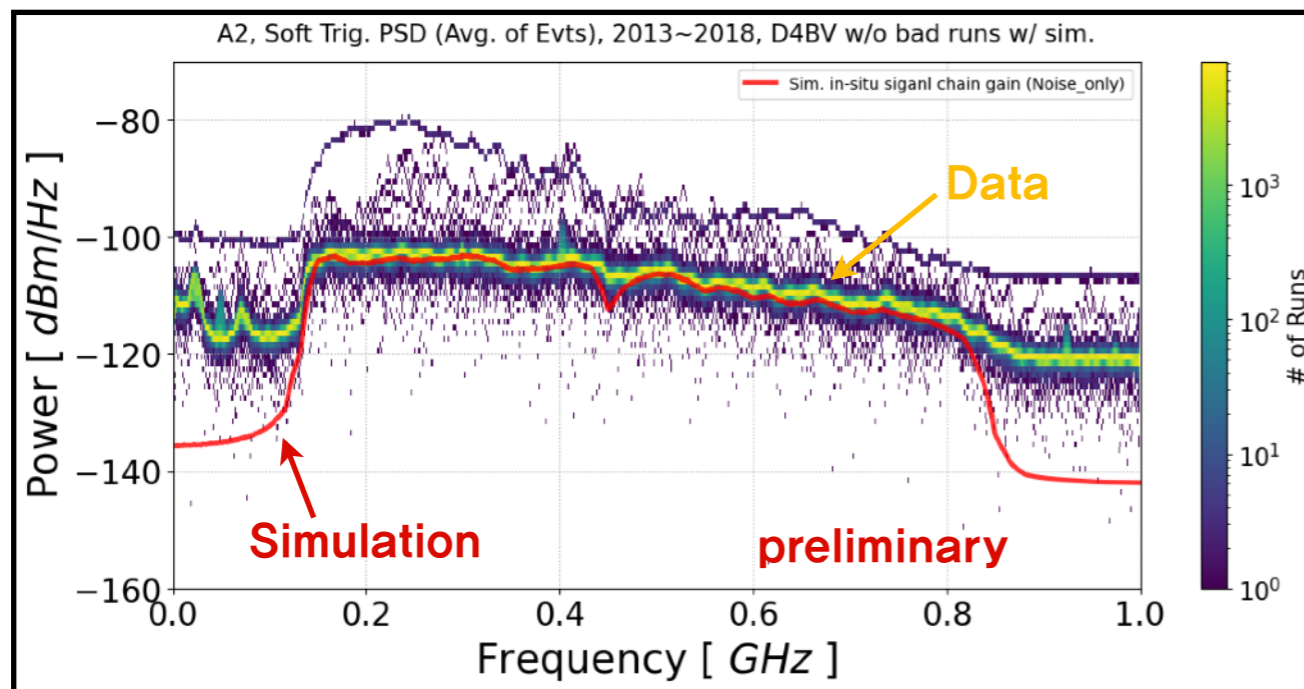
- ▶ Lesson learned:
 1. Thorough in-situ calibration is crucial for detector modeling/development.
 2. The future detector should be able to perform full in-situ calibration including wide angular gain scan and signal chain gain.

Analysis based on empirical antenna model (on progress)

Simulated Neutrino signal
based on empirical antenna model



In-situ signal chain gain model w/ data



- Empirical antenna and signal chain model is currently used in the template-based analysis (matched filtering method inspired by LIGO)
- The template is designed to including detector response and Nu. model.
 - Need to input accurate detector model.
 - Simulating an accurate frequency spectrum is crucial.
- Analysis is on progress.

Matched filtering Eq.

$$z(t) = 4 \int_0^\infty \frac{h(f)s^*(f)}{S_n(f)} e^{2\pi ift} df$$

$$\sigma^2 = 4 \int_0^\infty \frac{|h(f)|^2}{S_n(f)} df$$

$$\rho(t) = \frac{|z(t)|}{\sigma}$$

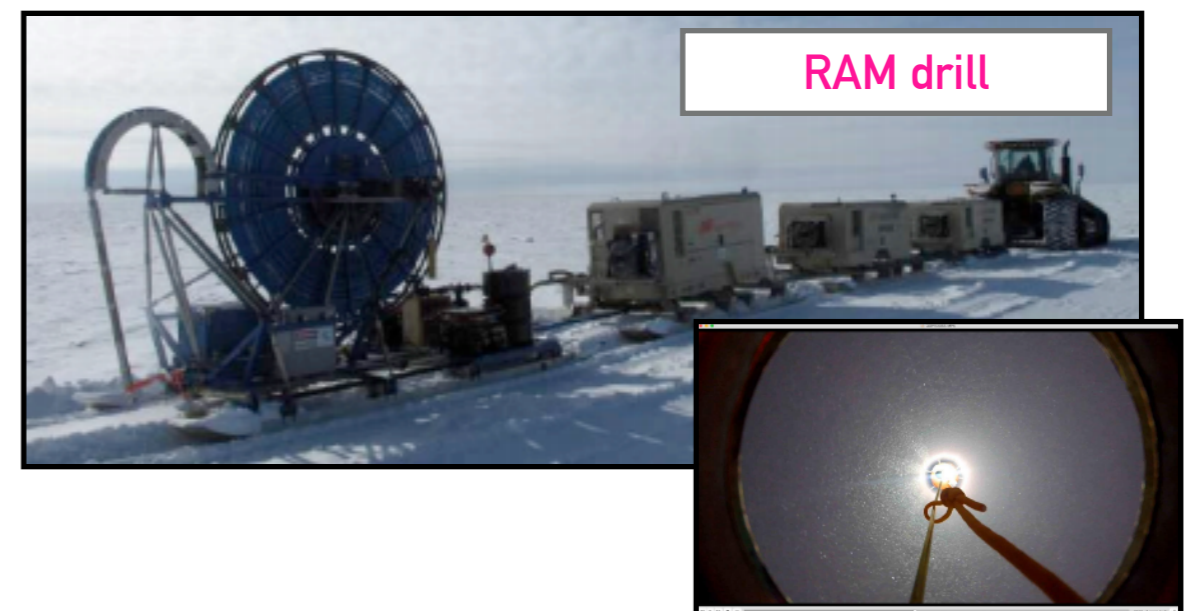
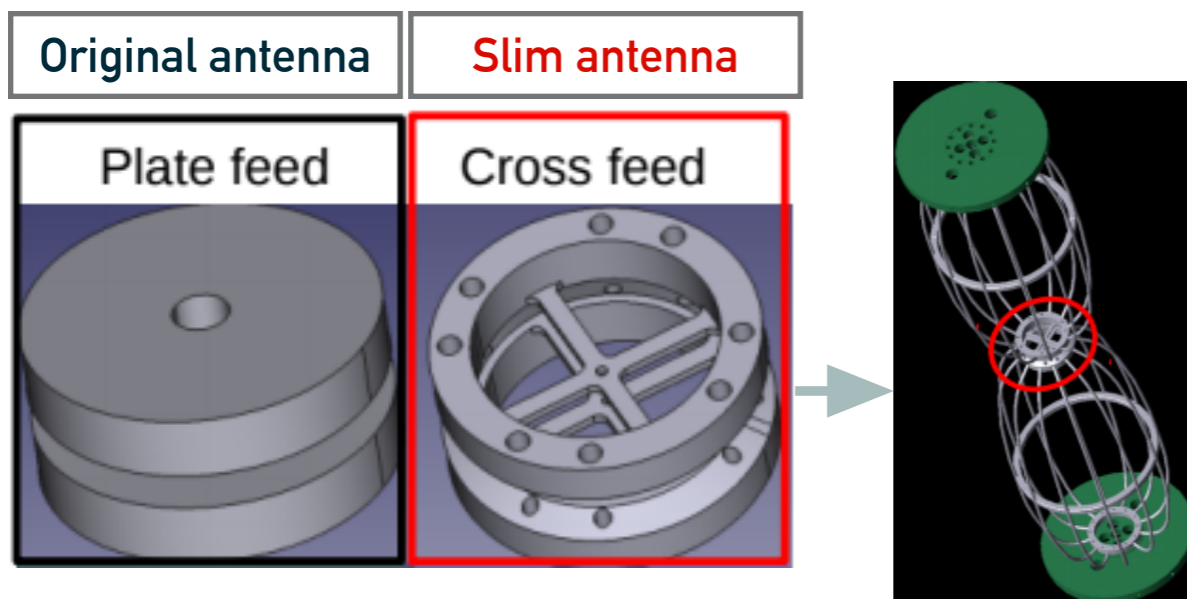
$\mathbf{s(f)}$ = ARA data spectrum
 $\mathbf{h(f)}$ = Template spectrum
 $\mathbf{z(t)}$ = Correlation (t-domain)
 $\mathbf{S_n(f)}$ = clean noise power spectrum
 σ = template normalization
 $\rho(t)$ = SNR vs lag plot [v/RMS]

Eqs from LIGO paper
Phys.Rev.D69:122001
,2004

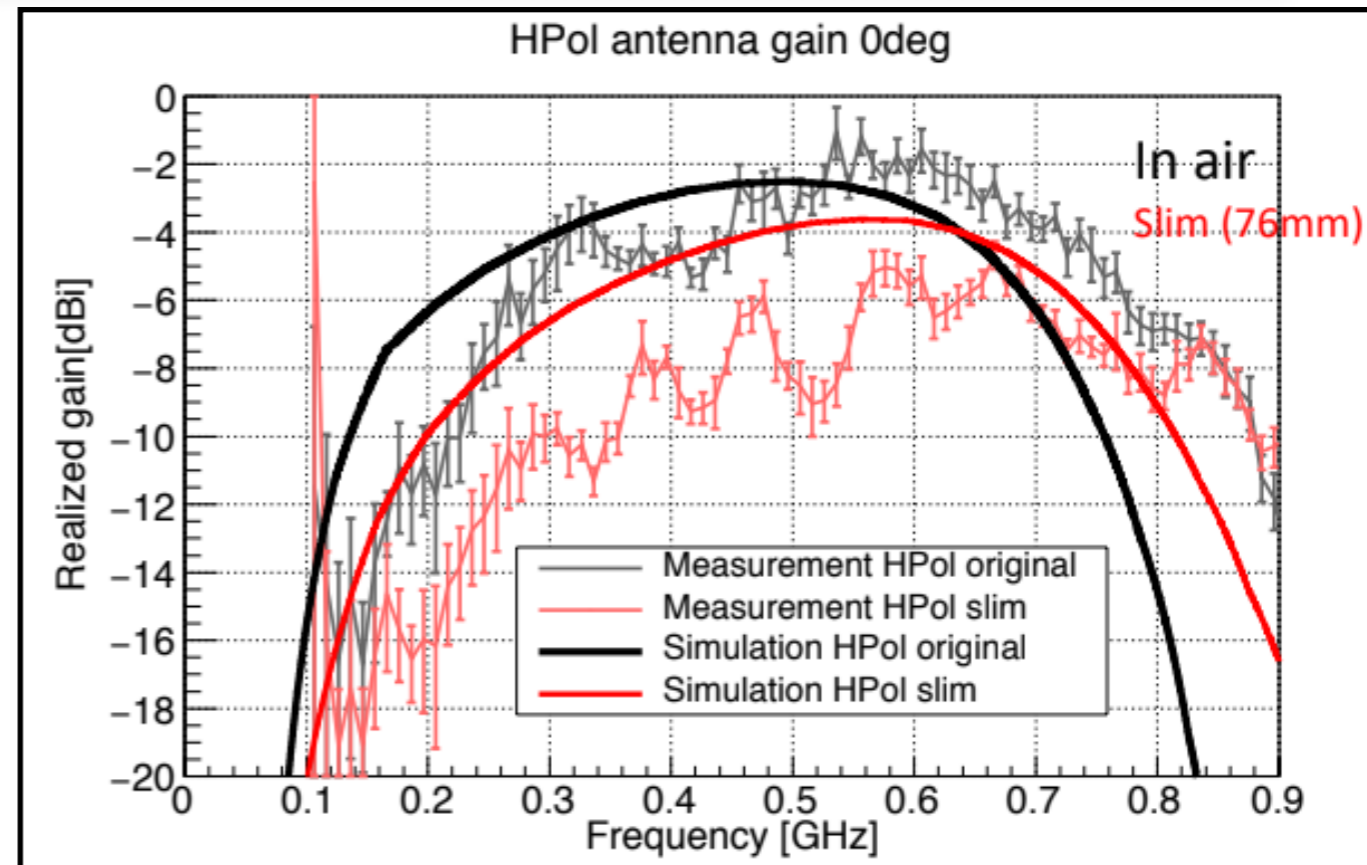
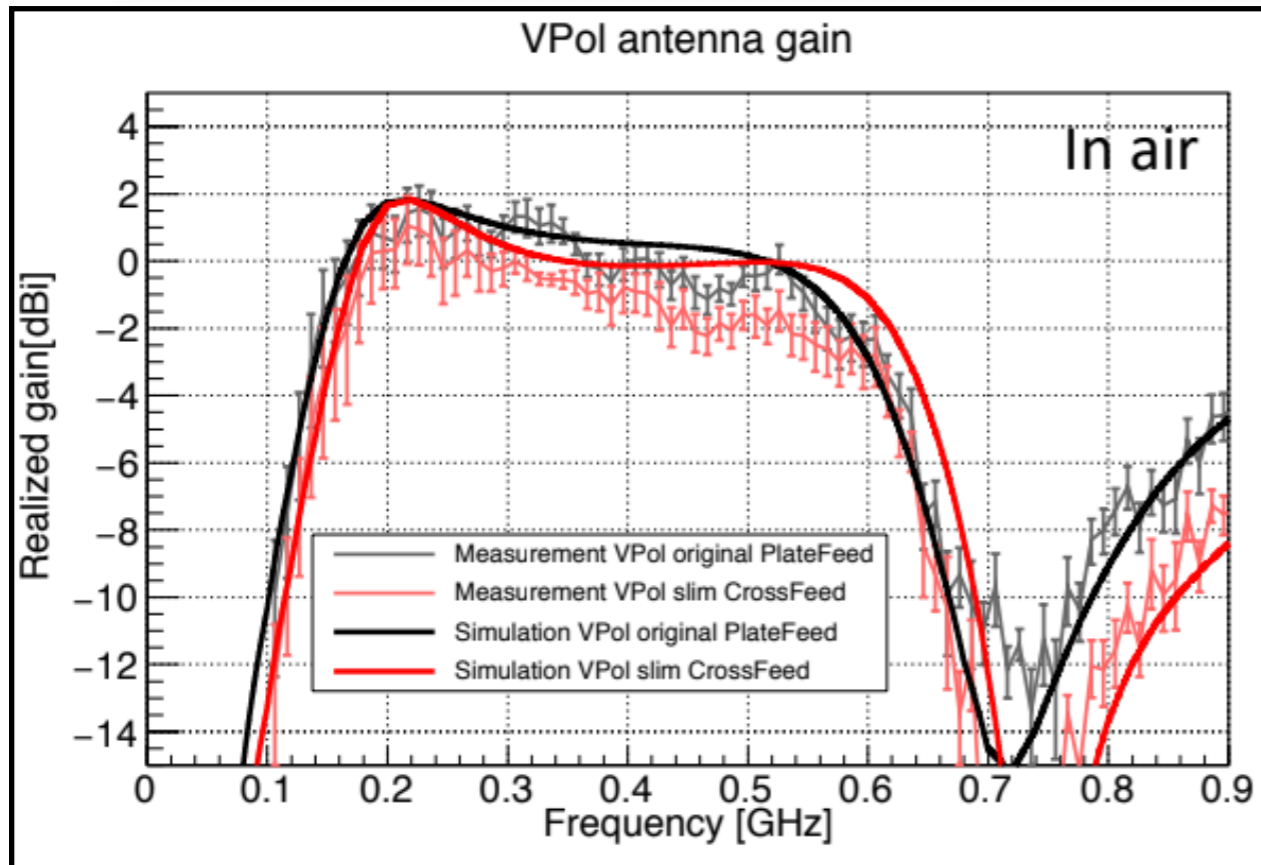
Slim antenna study



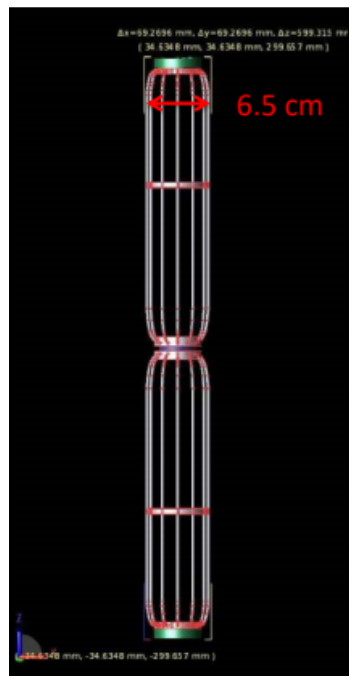
- ▶ The slim antenna was studied for next-generation detector design.
- ▶ The diameter of the antenna aimed to be below 10 cm for deploying it by RAM drill.
 - ▶ Very efficient (25 min. / hole. The current hot water drill 10 hours / hole of 200 m) ~10x faster.
 - ▶ The cost will be reduced by the speed of the drill (10 times less).
- ▶ The feed part is also optimized to reduce the impedance mismatch.



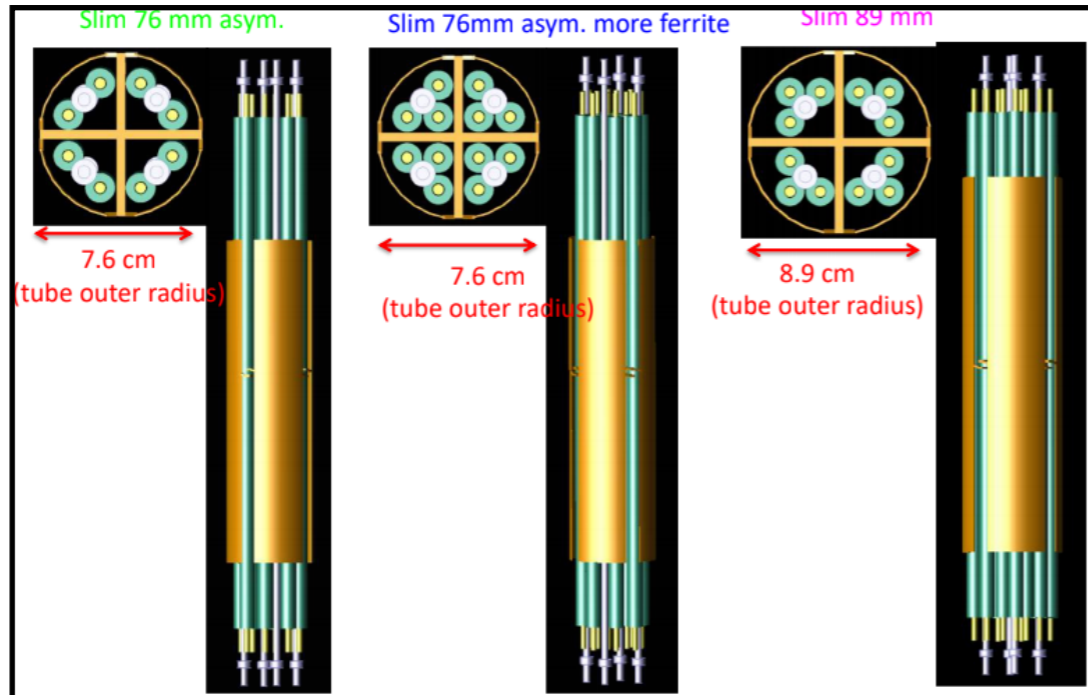
Anechoic chamber measurement



Vpol

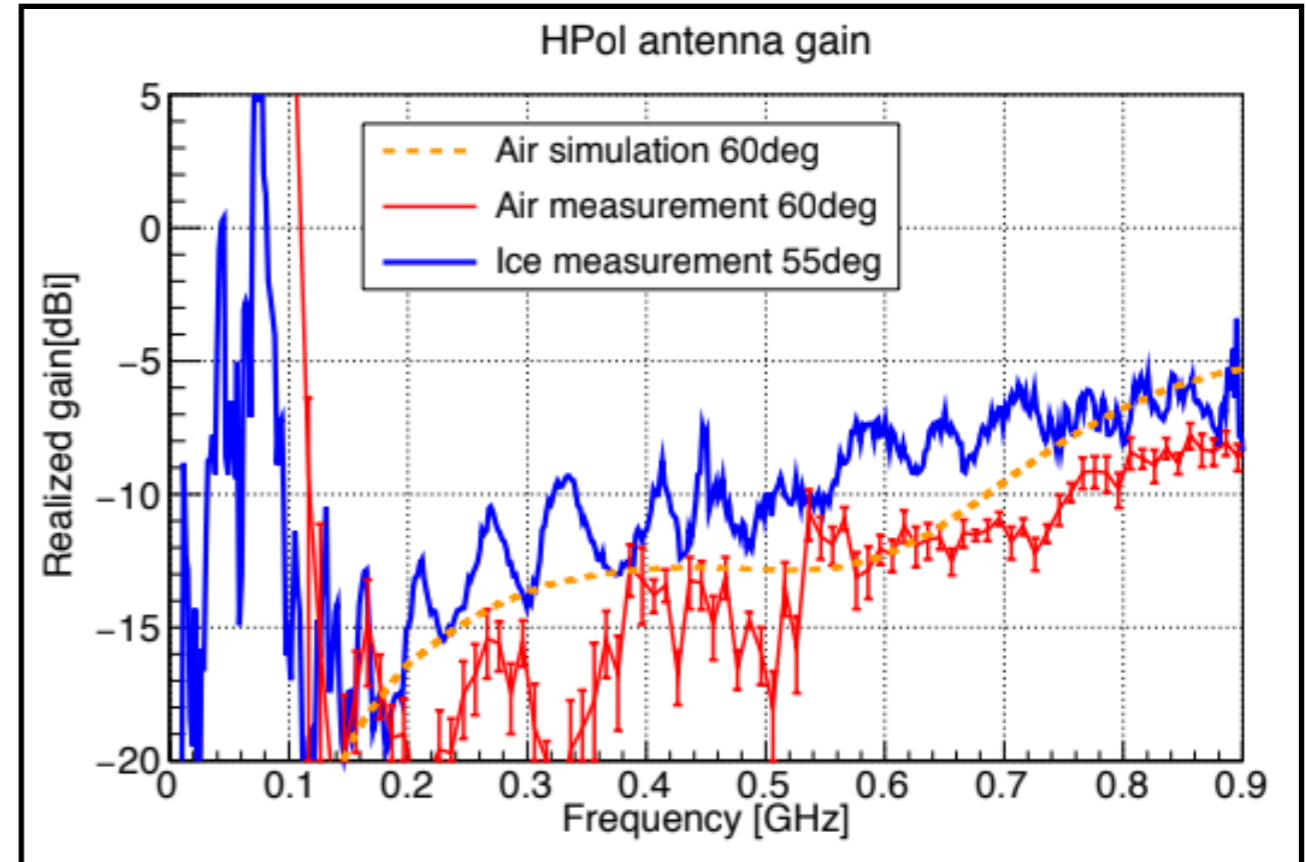
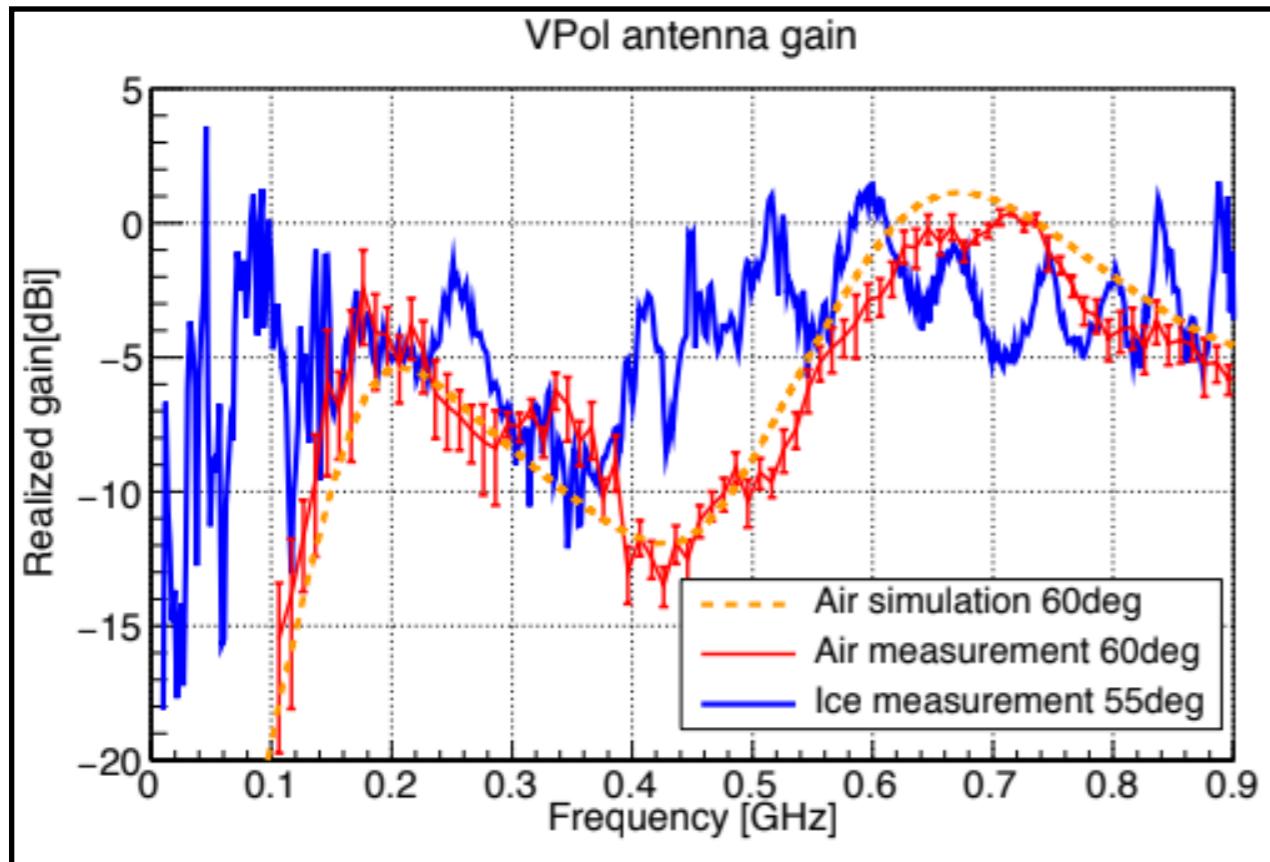


Hpol



- Measured slim Vpol antenna gain is about ~1 dB worse compared to the original size.
- Measured slim Hpol(76 mm asym.) gain is worse than the original by ~3 dB.
- Vpol slim antenna is a promising, slightly larger size for Hpol (89 mm) should be tried.

Measurement at the South pole



- **Vpol:** Relatively large fluctuations for the in-ice measurements. In-ice peak gain is not too different from in-air gain. Vpol slim antenna seems to be working properly.
- **Hpol:** Slim antenna also shows simulation/data mismatch for air (due to unknown ferrite characteristics). Larger gain in ice.
- Need more study for understanding in-ice behavior of the slim antenna.

Summary / Discussion

- Constructing an in-ice-with-hole detector model based on calibrations in anechoic chambers is challenging.
- In-air measurement/simulation is not good enough for modeling in-situ behavior
- In-situ calibration is crucial for detector modeling/development.
- Measuring more wider angular gain and signal chain gain in ice with good in-situ calibration plan would be crucial for future detector.
- The slim antenna is showing $\sim 1\text{dB}$ (Vpol) and $\sim 3\text{dB}$ (Hpol) worse than the original antenna but the quick deployment by RAM drill would reduce the cost.

